interval \((b_m, a_{m+1})=(b_m, 1)\) contains no points of \(A_n\). Since, on account of (i), we certainly have \(p < n_0\), it follows from (ii) and (iii) that \(\sum_j |G[I_j]| \geq |G[A_n]| - p \cdot (|G[A_n]| - \frac{1}{2} \mu)n_0 \geq \frac{1}{2} \mu\), i.e. that the system of intervals \((I_0)\) fulfills the required conditions.

\((8.7)\) Theorem. Every finite function \(f\) which is \(\&\&\&\)-integrable with respect to a function \(G\) on an interval \(I_0\), is the Rousell derivative with respect to \(G\) of its indefinite \(\&\&\&\)-integral at each point \(x\) of \(I_0\) except at most those of a set \(E\) such that \(|G[E]| = 0\).

Proof. Let \(\varepsilon\) be any positive number and \(U\) a major function of \(f\) with respect to \(G\) such that \(U(I_0) - P(I_0) < \varepsilon^2\), where \(P\) denotes the indefinite \(\&\&\&\)-integral of \(f\). Let us write \(H=U-P\), and denote by \(E_0\) the set of the points \(x\) of \(I_0\) for which there exist intervals \(I\) of arbitrarily small lengths, such that \(x \in I\) and that \(H(I) > \varepsilon\cdot |G[I]|\). It follows that each point of \(E_0\) is an end-point of intervals \(I\), as small as we please, which fulfill the inequality \(H(I) > \varepsilon\cdot |G[I]|\). Therefore, denoting by \(\mu\) any number less than \(|G[E_0]|\) and applying Lemma 8.6, we can determine in \(I_0\) a finite system of non-overlapping intervals \((I)\) such that \(H(I_k) > \frac{1}{2} \varepsilon \cdot |G[I_k]|\) for \(k=1, 2, ..., p\) and that \(\sum_k |G[I_k]| > \frac{1}{2} \mu\). Consequently, since \(H\) is non-decreasing, \(\varepsilon^2 > H(I_0) > \varepsilon \mu / 4\); and therefore \(\varepsilon < 4 \varepsilon\), and hence \(|G[E_0]| = 0\).

Now let \(x\) be any point of \(I_0\). We have for every sufficiently small interval \(I\) containing \(x\),

\[ P(I) - f(x)G(I) = U(I) - f(x)G(I) - H(I) \geq -H(I) > -\varepsilon^2; \]

and, unless \(x\) belongs to the set \(E_0\), we have

\[ P(I) - f(x)G(I) - H(I) > -\varepsilon\cdot |G[I]| > -\varepsilon\cdot |G[I]|. \]

Combining this with the similar upper evaluations of \(P(I) - f(x)G(I)\) obtained by symmetry, we see, since \(\varepsilon\) is an arbitrary positive number, that \(f\) is the Rousell derivative of the function \(P\) with respect to \(G\), at every point \(x\) of \(I_0\) except at most those of a set \(E\) such that \(|G[E]| = 0\).

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CHAPTER VII.

Functions of generalized bounded variation.

§ 1. Introduction. The definition adopted in Chap. I (§ 10) as starting point of our exposition of the Lebesgue integral, connects the latter with the conception of definite integral due to Leibniz, Cauchy and Riemann (cf. Chap. I, § 1 and Chap. VI, § 1). On account of the results of § 7, Chap. IV, we may, however, also regard the Lebesgue integral as a special modification of that of Newton (cf. Chap. VI, § 1) and define it as follows:

\((L)\) A function of a real variable \(f\) is integrable if there exists a function \(F\) such that (i) \(F'(x)=f(x)\) at almost all points \(x\) and (ii) \(F\) is absolutely continuous.

The function \(F\) (then uniquely determined apart from an additive constant) is the indefinite integral of the function \(f\).

A definition of integral is usually called descriptive when it is based on differential properties of the indefinite integral and therefore connected with the Newtonian notion of primitive; this is the case of the definition \((L)\) of the Lebesgue integral. In the note of F. Riesz [9] the reader will find an elementary and elegant account of the fundamental properties of the Lebesgue integral based on a descriptive definition differing slightly from the one given above (an account based directly on the definition \((L)\) is given in the first edition of this book).

By contrast to the descriptive definitions, we call constructive the definitions of integral which are based on the conception of definite integral of Leibniz-Cauchy, i.e. on approximation by the usual finite sums. Thus for instance, the classical definition given by H. Lebesgue [1] in his Thesis may be regarded as constructive (the reader will find a very suggestive explanation of this definition in the note by H. Lebesgue [8]); cf. also the definitions of Lebesgue integral given in the following memoirs: W. H. Young [8], T. H. Hildebrandt [1], F. Riesz [1] and A. Denjoy [7, 8].

As is readily seen, the definition \((L)\) constitutes a modification of that of the integral of Newton, in two directions: firstly, a generalization which enables us to disregard sets of measure zero
in the fundamental relation $F'(x) = f(x)$; and secondly, an essential restriction, which excludes all but the absolutely continuous functions from the domain of continuous primitive functions considered. Some such restriction is, in fact, indispensable, unless we give up the principle of unicity for the integral: to see this it is enough to consider, for instance, singular functions which are continuous and not constant, and whose derivatives vanish almost everywhere (cf. Chap. III, § 13, p. 101).

But although the condition (ii) cannot be wholly removed from the definition (L), it is possible to replace it by much weaker conditions, and the corresponding generalizations of the notion of absolute continuity give rise to extensions of the Lebesgue integral, known as the integrals $\mathcal{P}_b$ and $\mathcal{D}$ of Denjoy.

We shall treat in this Chapter two generalizations of absolutely continuous functions: the functions which are generalized absolutely continuous in the restricted sense or $\Lambda CG_b$, and those which are generalized absolutely continuous in the wide sense or $\Lambda CG$. If, in the definition (L), we replace the condition (ii) by the conditions that the function $F$ is $\Lambda CG_b$ or $\Lambda CG$ respectively, we obtain the descriptive definitions of the integrals $\mathcal{P}_b$ and $\mathcal{D}$. It must be added however that the second of these definitions requires a simultaneous generalization of the notion of derivative, to which is assigned the name of approximate derivative (or asymptotic derivative) and which corresponds to approximate continuity (vide Chap. IV, § 10). A function which is $\Lambda CG$ (unlike those which are absolutely continuous or which are $\Lambda CG_b$) or $\Lambda CG$, in fact fail, at each point of a set of positive measure, to be derivable in the ordinary sense, and yet be almost everywhere derivable in the approximate sense. Therefore, in order to obtain the definition of the integral $\mathcal{D}$ from the definition (L), it is necessary not only to modify the condition (ii) as explained above, but also to replace in the condition (i) the ordinary by the approximate derivative.

The integrals $\mathcal{P}_b$ and $\mathcal{D}$ will be studied in the next chapter; the preliminary discussion of their definitions just given, is intended to emphasize the important part played by the generalizations of the notion of absolute continuity, which are treated in this chapter. The results of which an account is given in the following §§ are essentially due to Denjoy, Luzin and Khintchine. The first definition of the integral $\mathcal{P}_b$ was given in notes dating from 1912 by A. Denjoy [2; 3] who employed the constructive method based on a transfinite process (vide Chap. VIII, § 6). These notes at once attracted the attention of N. Luzin [3] who originated the descriptive theory of this integral. Finally, A. Khintchine [1; 2] and

A. Denjoy [4] defined, independently and almost at the same time, the process of integration $\mathcal{P}_b$ as a generalization of the integral $\mathcal{P}_b$. A systematic account of these researches may be found in the memoir of A. Denjoy [6].

As shown by W. H. Young [6] the generalization of the Denjoy integrals can be carried still further if we give up, partially at least, the continuity of the indefinite integral. For subsequent researches in this direction, vide J. C. Burkill [5; 6; 7], J. Riede [6; 7], M. D. Kennedy and S. Pollard [1], S. Verblunsky [1], and J. Marcinkiewicz and A. Zygmund [1].

Except in a few definitions in § 3, we shall consider in this chapter only functions of a real variable. As we shall be employing in $\mathbb{R}$ notions established in the preceding chapters for arbitrary spaces $\mathbb{R}_m$, it will be convenient to add a few complementary definitions.

We shall say that a point $a$ is a right-hand point of accumulation for a linear set $E$, if each interval $[a, a+h]$, where $h>0$, contains an infinity of points of $E$. A point of $E$ which is not a right-hand point of accumulation for the set $E$ is termed isolated on the right of this set. The definitions of left-hand points of accumulation and of points isolated on the left are obtained by symmetry.

Similarly, for each linear set $E$, in addition to the densities defined in § 10, Chap. IV, we define at each point $x$ four unilateral densities: two outer right-hand, upper and lower, and two outer left-hand, upper and lower, densities of $E$. We shall understand by these four numbers the values of four corresponding Dini derivatives of the measure-function (vide Chap. IV, § 6) of $E$ at the point $x$. If at a point $x$, two of these densities on the same side (right or left) are equal to 1, the point $x$ is termed unilateral (right or left-hand) point of outer density for the set $E$. The term "outer" is omitted from these expressions if the set $E$ is measurable.

Finally, we shall extend the notation of linear interval and denote, for each point $a$ of $\mathbb{R}_1$, by $(-\infty, a)$, $(-\infty, a]$, $(a, +\infty)$ and $[a, +\infty)$ the half-lines $x<a$, $x\leq a$, $x>a$ and $x\geq a$ respectively.

§ 2. A theorem of Luzin. While discussing the significance of the condition (ii) in the definition (L) of an integral, we remarked that a continuous function which is almost everywhere derivable is by no means determined (apart from the additive constant) when we are given its derivative almost everywhere. It is, however, of greater interest that, for a function $f$, the property of being almost everywhere the derivative of a continuous function, itself represents no restriction at all, except, of course, in so far as it implies that
the function \( f \) is measurable and almost everywhere finite (this last assertion follows, for instance, from the corollaries to Theorem 10.1, p. 236). We shall prove this result, which is due to N. Lusin [1; 4] (cf. also E. W. Hobson [II, p. 284]), by means of two lemmas.

(2.1) Lemma. If \( g \) is a function summable on an interval \([a,b]\), there exists, for each \( \varepsilon > 0 \), a continuous function \( G \) such that (i) \( G'(x) = g(x) \) almost everywhere on \([a,b]\), (ii) \( G(a) = G(b) = 0 \), and (iii) \( |G(x)| \leq \varepsilon \) at every point \( x \) of \([a,b]\).

Proof. Let \( H(x) \) be the indefinite integral of \( g(x) \). We insert in \([a,b]\) a finite sequence of points \( a = a_0 < a_1 < \ldots < a_n = b \) such that the oscillation of \( H \) is less than \( \varepsilon \) on each of the intervals \([a_i, a_{i+1}]\) where \( i = 0, 1, \ldots, n - 1 \). Let \( P \) be a partition of the interval \([a,b]\), monotone on each interval \([a_i, a_{i+1}]\) and coincides with the function \( H \) at the end-points of these intervals. Writing \( G = H - P \), we shall have

(i) \( G'(x) = H'(x) - P'(x) = H'(x) - g(x) \) at almost all the points \( x \) of \([a,b]\),

(ii) \( G(a) = G(b) = 0 \), and finally

(iii) \( |G(x)| = |H(x) - P(x)| \leq \varepsilon \) for each point \( x \) of \([a,b]\).

(2.2) Lemma. If \( f \) is a function which is summable on an interval \([a,b]\) and if \( P \) is a closed set in \( J \), there exists for each \( \varepsilon > 0 \) a continuous function \( G \) such that (i) \( G'(x) = f(x) \) almost at all the points \( x \) of \( J - P \), (ii) \( G(x) = 0 \) and \( G'(x) = 0 \) at all the points \( x \) of \( P \) and \( [a,b] \), and (iii) \(|G(x+h)| \leq \varepsilon|h|\) for every \( x \) of \( P \) and \( h \).

Proof. For us represent the open set \( J - P \) as the sum of a sequence \( \{I_k = (a_k, b_k)\}_{k=1}^\infty \) of non-overlapping open intervals, and in each interval \( I_k \) we introduce a sequence of points \( (a_k^n)_{n=-1,0,1,2,\ldots} \), infinite in both directions and tending to \( a_k \) or \( b_k \) according as \( i \to -\infty \) or \( i \to +\infty \). Let us next denote, for each \( k \), \( i \), \( o \), \( t \), \( t' \), \( + \) or \( 2 \), \( 0 \), \( 1 \), \( 2 \), ..., and \( \varepsilon = 2^n \) the smaller of the numbers \( \varepsilon \cdot (a_k^n - a_{k-1})/(k+1) \) and \( \varepsilon \cdot (b_k - a_k^{n+1})/(k + 1) \). Lemma 2.1 enables us to determine in each open interval \( I_k \) a continuous function \( G_k \) such that \( G_k(x) = G(x) \) almost everywhere on \( I_k \), \( G_k(a_k) = 0 \) for \( i = 0, 1, 2, \ldots \), and \( |G_k(x)| \leq \varepsilon \) when \( a_k^n \leq x \leq a_k^{n+1} \). If we now write \( G(x) = G_k(x) \) for \( x \in I_k \) and \( k = 1, 2, \ldots \) and \( G(x) = 0 \) elsewhere on \( R_n \), we see at once that the function \( G \) is continuous and fulfills the required conditions (i), (ii) and (iii).

(2.3) Lusin’s Theorem. If \( f \) is a function which is measurable and almost everywhere finite on an interval \( J = [a,b] \), there always exists a continuous function \( F \) such that \( F'(x) = f(x) \) almost everywhere on \( J \).

Proof. We shall define by induction a sequence of continuous functions \( \{G_n\}_{n=0,1,\ldots} \), each of these functions being almost everywhere derivable, and a sequence of closed sets \( \{P_n\}_{n=0,1,\ldots} \) in \( J \), such that

\[
Q_n = \sum_{k=0}^n P_k \quad \text{and} \quad F_n = \sum_{k=0}^n G_k,
\]

the following conditions will be satisfied for \( n = 1, 2, \ldots \):

(a) \( F_n(x) = f(x) \) for \( x \in Q_n \),

(b) \( G_n(x) = 0 \) for \( x \notin Q_{n-1} \),

(c) \( |G_n(x+h)| \leq |h|/2^n \) for every \( x \in Q_{n-1} \) and every \( h \),

(d) \( |J - Q_n| \leq 1/n \).

For this purpose, we choose \( G_0(x) = 0 \) identically and \( P_0 = 0 \), and we suppose that for \( n = 0, 1, \ldots, \tau \) the closed sets \( P_n \) and the continuous functions \( G_n \), almost everywhere derivable, have been defined so as to satisfy the conditions (a), (b), (c) and (d) for each \( n \leq \tau \). Since the function \( f \) is measurable and almost everywhere finite, and since the function \( F \), is almost everywhere derivable, we can determine a measurable subset \( E \) of \( J \), such that

\[
|J - Q_{\tau} - E| \leq 1/(\tau + 1),
\]

and such that the derivative \( F'(x) \) exists at each point \( x \) of the set \( E \), and is bounded, together with the function \( f(x) \), on this set. Hence by Lemma 2.2, we can determine a continuous function \( G_{\tau+1} \), almost everywhere derivable, in such a manner that (i) \( G_{\tau+1}(x) = f(x) - F(x) \) at almost all points of \( E \), (ii) \( G_{\tau+1}(x) = 0 \) at all points of \( Q_\tau \), and (iii) \( |G_{\tau+1}(x+h)| \leq |h|/2^{\tau+1} \) for every \( x \in Q_\tau \) and every \( h \).

Now it follows from the first of these conditions and from (2.4), that there exists a closed set \( P_{\tau+1} \subset E \), such that

\[
|J - Q_{\tau} - P_{\tau+1}| \leq 1/(\tau + 1),
\]

and we easily verify, on account of (2.6), (ii), (iii) and (2.5), that the conditions (a), (b), (c) and (d), still remain valid for \( n = \tau + 1 \).

Let us now write:

\[
F(x) = \lim_{n} F_n(x) = \sum_{n=0}^{\infty} G_n(x), \quad \text{and} \quad Q = \lim_{n} Q_n = \sum_{n=0}^{\infty} P_n.
\]
In view of the condition (c), the series occurring in (2.7) converges uniformly, and the function \( F \) is therefore continuous. Let \( x_0 \) be any point of \( Q \). Then for every sufficiently large integer \( n \) we have \( x_0 < Q_m \) and since 
\[
\frac{F(x_0 + h) - F(x_0)}{h} = \frac{F_n(x_0 + h) - F_n(x_0)}{h} + \sum_{k=n+1}^{\infty} G_k(x_0 + h) - G_k(x_0) \quad h \to 0,
\]
we find, on account of the conditions (a), (b) and (c), that 
\[
\lim_{h \to 0} \sup \left| \frac{F(x_0 + h) - F(x_0)}{h} - f(x_0) \right| \leq 1/2^n,
\]
and so, \( F'(x_0) = f(x_0) \). Now it follows from the condition (d) that \( |J - Q| = 0 \); therefore we have \( F'(x) = f(x) \) at almost all the points \( x \) of \( J \), and this completes the proof.

Theorem 2.3 remains valid for any space \( R_n \):

If \( f \) is a measurable function which is almost everywhere finite in a space \( R_m \), there exists an additive continuous function of an interval \( F \) such that \( F'(x) = f(x) \) almost everywhere in \( R_m \).

The proof is almost the same as that of Theorem 2.3. We may also, in the following statement, replace the ordinary derivative \( F'(x) \) by the strong derivative (c.f. Sect. IV, § 2, p. 106), but the proof is then more elaborate.

It may be remarked further that Lusin's theorem in the form (3.3) is obvious if the function \( f \) is summable; for \( f \) is everywhere the derivative of its indefinite integral. But this is no longer so when we wish to determine a function \( F \) with a strong derivative almost everywhere equal to \( f \) (c.f. Chap. IV, p. 132). Nevertheless, it can be shown that given in a space \( R_0 \) any summable function of a point \( f \), there always exists an additive continuous function of an interval, of bounded variation, \( F \), such that \( F'(x) = f(x) \) almost everywhere in \( R_0 \).

Lusin's method is applicable in several other arguments. It has been used, for instance, by J. Marcinkiewicz [1] to derive the theorem:

There exists a continuous function of a real variable \( f \) which has the following property: with each measurable function \( f \), almost everywhere finite, there can be associated a sequence of positive numbers \( \{h_n\} \) tending to 0 such that 
\[
\lim_{n \to \infty} [F(x + h_n) - F(x)]/h_n = f(x)
\]
at almost all the points \( x \).

§ 3. Approximate limits and derivatives. Given any function \( F \) defined in the neighborhood of a point \( x_0 \) of a space \( B_m \), we shall call \( F \) an approximate upper limit of \( F \) at \( x_0 \) the lower bound of all the numbers \( y \) (\( +\infty \) included) for which the set \( E[F(x) > y] \) has \( x_0 \) as a point of dispersion (c.f. Chap. IV, § 10). Similarly, the approximate lower limit of the function \( F \) at the point \( x_0 \) is the upper bound of the numbers \( y \) for which the set \( E[F(x) < y] \) has \( x_0 \) as a point of dispersion. These two approximate limits of \( F \) at \( x_0 \) are called also extreme approximate limits and denoted by \( \limsup_{x \to x_0} F(x) \) and \( \liminf_{x \to x_0} F(x) \); respectively. When they are equal, their common value is termed approximate limit of \( F \) at \( x_0 \) and denoted by \( \lim_{x \to x_0} F(x) \).

It is easily seen that if \( E \) is a measurable set for which \( x_0 \) is a point of density, then, in the preceding definitions of extreme approximate limits, the sets \( E[F(x) > y] \) and \( E[F(x) < y] \) may be replaced by the sets \( E[F(x) > y; x \in E] \) and \( E[F(x) < y; x \in E] \) respectively. Hence

(3.1) Theorem. If two functions coincide on a measurable set \( E \), their approximate extreme limits coincide at almost all points of \( E \), and in fact at every point of density of \( E \).

We see further that if \( x_0 \) is a point of density for a measurable set \( E \) and if the limit of \( F(x) \) exists as \( x \to x_0 \), then this limit is at the same time the approximate limit of \( F \) at the point \( x_0 \). Therefore, if a function \( F \) is approximately continuous (c.f. Chap. IV, p. 131) at a point \( x_0 \), we must have \( F(x_0) = \lim_{x \to x_0} F(x) \).

If \( x_0 \) is a point of density for a measurable set \( E \) and if, further, the function \( F \) is measurable on \( E \), it is easily seen that the approximate upper limit of \( F \) at \( x_0 \) is the lower bound of the numbers \( y \) for which the set \( E[F(x) < y; x \in E] \) has \( x_0 \) as a point of density. It follows, by the definition of approximate lower limit, that with the same hypotheses on the set \( E \) and on the function \( F \), in order that \( l = \lim_{x \to x_0} F(x) \), it is necessary and sufficient that for each \( \epsilon > 0 \) the set \( E \{l - \epsilon \leq F(x) \leq l + \epsilon; x \in E \} \) should have the point \( x_0 \) as a point of density.

Let us remark finally that the following inequalities hold between approximate and ordinary extreme limits:

\[
(3.2) \quad \liminf_{x \to x_0} F(x) \leq \lim_{x \to x_0} F(x) \leq \limsup_{x \to x_0} F(x) \leq \limsup_{x \to x_0} F(x);
\]

and hence the approximate limit exists and is equal to the ordinary limit, wherever the latter exists.
Functions of generalized bounded variation.

In order to understand better the meaning of the definitions of approximate limits, it may be remarked that the definitions of the ordinary limits are expressible in a very similar form. Thus the upper limit of \( F(x) \) at \( x_0 \) may be defined as the lower bound of all the numbers \( y \) for which \( x_0 \) is not a point of accumulation for the set \( E \). The inequality (3.2) then becomes obvious.

For functions of a real variable, in addition to the approximate limits defined above, and which in this case we call bilateral, we introduce also four unilateral approximate limits. The approximate upper right-hand limit of a function \( F \) at a point \( x_0 \) is the lower bound of the numbers \( y \) for which the set \( E \), \( F(x) > y; x > x_0 \) has \( x_0 \) as a point of dispersion. This limit is written \( \limsup_{x \to x_0^+} F(x) \). The three other approximate extreme unilateral limits are defined and denoted similarly.

These generalizations of the notion of limit lead very naturally to parallel generalizations of derivatives. Thus, given a finite function of a real variable \( F \), we define at each point \( x_0 \) the approximate right-hand upper derivative \( F^u_+(x_0) \), and lower derivative \( F^l_+(x_0) \), the approximate left-hand upper derivative \( F^u_-(x_0) \), and lower derivative \( F^l_-(x_0) \), and the approximate bilateral upper derivative \( F^u(x_0) \) and lower derivative \( F^l(x_0) \), as the corresponding approximate extreme limits of the ratio \( (F(x) - F(x_0)) / (x - x_0) \) as \( x \to x_0 \). When all these derivatives are equal (or, what comes to the same, when \( F^u_+(x_0) = F^u_-(x_0) \)), their common value is called approximate derivative of \( F \) at \( x_0 \) and is denoted by \( F'(x_0) \); if further, this derivative is finite, the function \( F \) is said to be approximately derivable at \( x_0 \).

For some further generalizations, such as "prépondérant derivatives" ("nombres dérivés prépondérants"), and for a deeper study of the properties of approximate derivatives, the reader should consult A. Denjoy [6] and A. Khintchine [5].

The properties of bilateral approximate limits, discussed above, can be taken over, with the obvious formal modifications, so as to apply to unilateral approximate limits. In particular, Theorem 3.1 may be completed as follows:

(3.3) Theorem. If two functions of a real variable coincide on a measurable set \( E \), their approximate extreme limits and their approximate derivatives coincide respectively at almost all points of \( E \), and in fact at every point of density of \( E \).

Also, if a function \( F \) is measurable on a set \( E \), we have \( F^u_0(x) = F^l_0(x) \) at almost all the points \( x \) of \( E \) at which the function \( F \) has a derivative with respect to the set \( E \).

§ 4. Functions VB and VBG. We shall denote by \( V(F; E) \), and call weak variation of a finite function \( F(x) \) on a set \( E \), the upper bound of the numbers \( \sum \left| F(b_i) - F(a_i) \right| \) where \( \{a_i, b_i\} \) is any sequence of non-overlapping intervals whose end-points belong to \( E \). If \( V(F; E) < +\infty \), the function \( F \) is said to be of bounded variation in the wide sense on the set \( E \), or, simply, of bounded variation on \( E \), or VB on \( E \).

In the special case in which the set \( E \) is a closed interval, we clearly have \( V(F; E) = W(F; E) \), i.e. the weak variation of the function \( F \) on \( E \) then coincides with its absolute variation in the sense of Chap. III, § 13.

The definition of functions of bounded variation in the wide sense on a set thus constitutes a generalization (for functions of a real variable) of that of functions of bounded variation on an interval. If \( E \) is a linear figure formed of disconnected intervals we only get the inequality \( V(F; E) \geq W(F; E) \), but it is easy to see that even then the relation \( W(F; E) < +\infty \) always implies \( V(F; E) < +\infty \).

Plainly, every function which is VB on a set \( E \) is bounded on \( E \) and is VB on each subset of \( E \). Again, any function \( F \) which is continuous on a set \( E \) and VB on a set \( A \subset E \) everywhere dense in \( E \) (cf. Chap. II, § 2) is VB on the whole set \( E \) for then \( V(F; E) = V(F; A) \). Finally, if \( F \) and \( G \) are two functions which are bounded on a set \( E \) and \( M \) denotes the upper bound of the absolute values of these functions on \( E \), we have \( V(\alpha F + \beta G; E) \leq |\alpha| \cdot V(F; E) + |\beta| \cdot V(G; E) \) for each pair of constants \( \alpha \) and \( \beta \), and \( V(F \cdot G; E) \leq M \cdot \{V(F; E) + V(G; E)\} \) (cf. Chap. III, p. 97). Hence every linear combination, with constant coefficients, of two functions which are VB on a set, and the product of the two functions, are themselves VB on this set.

A function \( F(x) \) is said to be of generalized bounded variation in the wide sense on a set \( E \), or simply, of generalized bounded variation on \( E \), or again, for short, VBG on \( E \), if \( E \) is the sum of a finite or enumerable sequence of sets on each of which \( F(x) \) is VB. From what has just been proved for functions which are VB we see at once that every linear combination of two functions which are VBG on a set, and the product of the two functions, are themselves VBG on this set.

(4.1) Lemma. In order that a function \( F \) be bounded and non-decreasing [of bounded variation] on a set \( E \), it is necessary and sufficient that \( F \) coincide on \( E \) with a function which is bounded and non-decreasing [of bounded variation] on the whole straight line \( R_1 \).
Proof. Let us denote for each \( x \), by \( E_{(x)} \) the set of the points of \( E \) which belong to the interval \((-\infty, x]\). We shall consider two cases separately.

1° The function \( F \) is bounded and non-decreasing on \( E \). For each \( x \), let \( G(x) \) denote the upper bound of the function \( F \) on the set \( E_{(x)} \), or else the lower bound of the function \( F \) on \( E \), according as \( E_{(x)} \cap \emptyset = 0 \). The function \( G \) thus defined is evidently bounded and non-decreasing on the whole straight line \( R_1 \) and coincides with the function \( F \) on \( E \).

2° The function \( F \) is VB on \( E \). For each point \( x \), let \( V(x) = V(F; E_{(x)}) \) if \( E_{(x)} \cap \emptyset = 0 \), and \( V(x) = 0 \) if \( E_{(x)} \cap \emptyset = 0 \). We see at once that the function \( V(x) \) is monotone and bounded on the whole straight line \( R_1 \) and that \( V(x) - F(x) \) is non-decreasing and bounded on \( E \). Hence, by what has just been proved in 1°, there exists a function \( G(x) \) which is bounded and non-decreasing on \( R_1 \) and which coincides with \( E \) with \( V(x) - F(x) \). We have therefore \( F(x) = V(x) - G(x) \) for every \( x \in E \), and since the function \( V(x) - G(x) \), as difference of two bounded monotone functions, is clearly of bounded variation on \( R_2 \), this completes the proof.

(4.2) Theorem. Let \( F \) be a function which is measurable on a set \( E \) and which is VB on a set \( E_1 \subset E \). Then (i) \( F \) is approximately derivable at all points of \( E_1 \) and (ii) there exists a measurable set \( E_2 \) such that \( E_1 \subset E_2 \subset E \) and that \( F \) is VB on \( E_2 \).

Proof. By Lemma 4.1, there exists a function \( G \) which coincides with \( F \) on the set \( E_2 \) and which is of bounded variation on the whole straight line \( R_1 \). Let \( E_2 \) be the set of the points \( x \) of \( E \) at which \( F(x) = G(x) \). Then since \( F \) is, by hypothesis, measurable on \( E_1 \), the set \( E_2 \) must be measurable. Moreover, as \( E_1 \subset E_2 \subset E \), the function \( F \) is, with \( G \), of bounded variation on \( E_2 \), and by Lebesgue's Theorem 5.4, Chap. IV, and Theorem 3.3, the finite approximate derivative \( F'(x) = G(x) \) exists at almost all the points \( x \) of \( E_2 \).

Theorem 4.2 leads at once to the following theorem, which for the Denjoy integral takes the place of Lebesgue's Theorem on derivability of functions of bounded variation:

(4.3) Theorem of Denjoy-Khintchine. A function which is measurable and VB on a set is approximately derivable at almost all points of this set.
Neither can we construct an example of a function which is $\Delta G$ on an interval and which is not derivable in the ordinary sense at the points of a set of positive measure.

For this purpose, let $H$ denote a bounded, perfect, non-dense set of positive measure, with the bounds $a$ and $b$. Let $I = [a, b]$ and let $\{I_n = [a_n, b_n]\}$ be the sequence of the intervals contiguous to $H$. We denote further by $\varepsilon_n$ the length of the largest subinterval of $[a, b]$ which does not overlap the first $n$ intervals $I_1, I_2, \ldots, I_n$ of the sequence. Plainly

$$\lim_{n \to \infty} |I_n| = 0 \quad \text{and} \quad \lim_{n \to \infty} \varepsilon_n = 0.$$  

Now let $c_n$ denote for each $n = 1, 2, \ldots$, the centre of the interval $I_n$, and let $F$ be the function defined on the interval $I$ by the following conditions:

1. $F(x) = 0$ for $x \in H$;
2. $F(c_n) = |I_n| + \varepsilon_n$ for $n = 1, 2, \ldots$;
3. the function $F$ is linear in each of the intervals $[a_n, c_n]$ and $[c_n, b_n]$ where $n = 1, 2, \ldots$. Thus defined, the function $F$ is continuous on $I$ by (5.1) and is $\Delta G$ on $H$ and on each $I_n$; since $I = H + \sum \frac{1}{n} I_n$, it follows that $F$ is $\Delta G$ on $I$.

We shall show that $F$ is not derivable at any point $x \in H$. In fact, since $F$ vanishes on $H$, we have

$$E(x) \leq 0 \leq F(x) \quad \text{for every } x \in H.$$

If therefore a point $x_0$ is a left-hand end-point of an $I_n$, there can be no derivative $F'(x_0)$ since it is clear that $F(x_0) = \frac{F(x_n) - F(x_0)}{x_n - x_0} > 0$ and therefore, by (5.2), that $F(x_0) = F(x_n) > 0$. Similarly, $E(x_0) > 0 \leq F(x_0)$ if $x_0$ is a right-hand end-point of an interval $I_n$.

If, on the other hand, $x_0 \in H$, $x_0 \notin I_n$, and $x_0 \notin I_m$, then $E(x_0) = F(x_0) - F(x_n) = x_n - x_m > 0$ since the definition of $F(x_0)$, we have $F(x_0) = |I_n| + \varepsilon_n > 0$. Since $\lim \varepsilon_n = 0$, it follows that either $F(x_0) = \infty$ or $E(x_0) = 0$, which by (5.2), proves that $F$ is not derivable at $x_0$.

Let us remark, in conclusion, that a function $F$, which is continuous on a set $E$ and which is $\Delta G$ on a subset of $E$ everywhere dense in $E$, is $\Delta G$ on the whole set $E$.

§ 6. Lusin's condition (N). A finite function $F$ is said to fulfill the condition $(N)$ on a set $E$, if $|F[H]| = 0$ for every set $H \subset E$ of measure zero (for the notation cf. Chap. III, p. 100). Clearly, a function which fulfills the condition $(N)$ on each of the sets of a finite or enumerable sequence, also fulfills this condition on the sum of these sets.

The condition $(N)$ was introduced by N. Lusin [1, p. 109], who was the first to recognize the importance of this condition in the theory of the integral. It is easy to see that in the domain of continuous functions the condition $(N)$ is necessary and sufficient in order that the function should transform every measurable set into a measurable set (cf. H. Rademacher [1] and H. Hahn [1, p. 898]). Among the more recent researches devoted to the condition $(N)$ and to other similar conditions (cf., below, Chap. IX) the reader should consult above all N. Bary [9].

(6.1) Theorem. A function which is $\Delta G$ on a set necessarily fulfills the condition $(N)$ on this set.

Proof. Since each set on which a function is $\Delta G$ is the sum of a sequence of sets on which it is $\Delta C$, it will suffice to prove that $|F[H]| = 0$ whenever $H$ is a set of measure zero and $F$ a function $\Delta C$ on $H$.

For this purpose, let $\varepsilon$ be any positive number. We denote, for brevity, by $M(E)$ and $m(E)$ respectively the upper and lower bounds of $F$ on $E$, when $E$ is any subset of $H$, and we write $M(E) = m(E) = 0$ in the case in which $E = 0$. Since the function $F$ is $\Delta C$ on $H$, there exists a number $\eta > 0$ such that $\sum \frac{1}{k} [M(H \cdot I_k) - m(H \cdot I_k)] < \varepsilon$ for every sequence of non-overlapping intervals $\{I_k\}$ which satisfies the condition $\sum \frac{1}{k}$. Now since the set $H$ is of measure zero, we can determine a sequence of non-overlapping intervals $\{I_k\}$ which satisfies this last condition and which covers, at the same time, the whole set $E$. Therefore, since $|F[H \cdot I_k]| = |M(H \cdot I_k) - m(H \cdot I_k)|$ for each $k$, it follows that $|F[H]| = 0$. Hence, $\varepsilon$ being arbitrary, $|F[H]| = 0$.

It follows from Theorem 7.8 (19'), Chap. IV, that every function which is absolutely continuous on an interval and whose derivative is almost everywhere non-negative, is monotone non-decreasing. With the help of Theorem 6.1, this result can be extended to functions which are $\Delta G$ and we have:

(6.2) Theorem. Every function $F(x)$ which is $\Delta G$ on an interval $I$ and for which we have almost everywhere in this interval $F'(x) \geq 0$, or more generally, $F''(x) \geq 0$, is monotone non-decreasing.

In particular therefore, if the approximate derivative of a function which is $\Delta G$ on an interval vanishes almost everywhere on this interval, then the function is a constant.

Proof. Let $\varepsilon$ be any positive number and let $G(x) = F(x) + \varepsilon x$. The function $G$ is then $\Delta G$ on the interval $I$ (together with the function $F$), and moreover, we have $G''(x) = F''(x) + \varepsilon \geq 0 > 0$ at almost all the points $x$ of $I$. Hence, denoting by $H$ the set of the points $x$ at which $G''(x) \leq 0$, we have $|H| = 0$, and this implies, by Theorem 6.1, that $G[H] = 0$. Thus the set $G[H]$ cannot contain any non-degenerate interval, and by Theorem 7.1, Chap. VI, the function $G(x) = F(x) + \varepsilon x$ is non-decreasing on $I$. It follows at once, by making $\varepsilon = 0$, that the function $F$ is itself non-decreasing.
If we analyze the preceding proof, we notice that the hypothesis of generalized absolute continuity of \( F(x) \) has been used only to show that every function of the form \( F(x) + \varepsilon x \), where \( \varepsilon > 0 \), fulfills the condition \( (N) \). It is remarkable that the condition \( (N) \) need not remain satisfied when we add a linear function to a function fulfilling the condition, even when this last function is restricted to be continuous (see S. Mazurkiewicz [1]). For this reason it is not enough to suppose in the preceding proof that the function \( F(x) \) merely fulfills the condition \( (N) \).

Nevertheless, Theorem 6.2 itself does remain true for arbitrary functions which fulfill the condition \( (N) \). The theorems which will be proved in Chap. IX, §7, include a more general result, namely that every continuous function which fulfills the condition \( (N) \) and whose derivative is non-negative at almost all the points at which it exists, is monotone non-decreasing.

We shall show (vide, below, Theorem 6.8) that for continuous functions of generalized bounded variation on closed sets, the converse of Theorem 6.1 is true, i.e. that in this case the condition \( (N) \) is equivalent to generalized absolute continuity. Similarly, for continuous functions of bounded variation the condition \( (N) \) is equivalent to absolute continuity in the ordinary sense.

We shall begin with a lemma which will also prove useful elsewhere.

(6.3) **Lemma.** If, for a finite function \( F \), the inequalities \( F^+(x) \leq M \) and \( F^-(x) \geq -M \), where \( M \) is a finite non-negative number, hold at each point \( x \) of a set \( D \), then \( |F(D)| \leq M \cdot |D| \).

**Proof.** Let \( \varepsilon \) be any positive number. Let \( D_n \) denote for each positive integer \( n \) the set of the points \( x \) of \( D \) for which we have \( F(x) - (M + \varepsilon) \cdot |x| \leq \varepsilon \) whenever \( |x - a| \leq 1/n \). The sets \( D_n \) evidently constitute an ascending sequence and we see easily that \( D = \lim D_n \).

With each \( D_n \) we can associate a sequence of intervals \( (I^n_k)_{k=1}^{\infty} \) which covers \( D_n \) and fulfills the condition
\[
\sum_k |I^n_k| \leq |D_n| + \varepsilon,
\]
and in which, further, no \( I^n_k \) has length greater than \( 1/n \). By definition of \( D_n \) we therefore have, for every pair \( a_k, a_{k+1} \) of points of \( D_n \cdot I^n_{k+1} \), the inequality \( |F(a_k) - F(a_{k+1})| \leq (M + \varepsilon) \cdot |a_k - a_{k+1}| \leq (M + \varepsilon) \cdot |I^n_k| \), so that \( |F(D_n) \cdot I^n_{k+1}| \leq (M + \varepsilon) \cdot |I^n_k| \). In view of the inequality (6.4) it therefore follows that, for every \( n \),
\[
|F(D_n)| \leq \sum_k |F(D_n) \cdot I^n_k| \leq (M + \varepsilon) \cdot \sum_k |I^n_k| \leq (M + \varepsilon) \cdot (|D_n| + \varepsilon);
\]
and, by making first \( n \to \infty \) and then \( \varepsilon \to 0 \), we derive \( |F(D)| \leq M \cdot |D| \).

(6.5) **Theorem.** If a function \( F \) is derivable at every point of a measurable set \( D \), then
\[
|F(D)| \leq \int_D |F'(x)| \, dx.
\]

**Proof.** We may clearly assume that the set \( D \) is bounded. Given any \( \varepsilon > 0 \), let \( D_\varepsilon \) denote, for each positive integer \( n \), the set of the points \( x \in D \), at which \( (n-1)\varepsilon \leq |F'(x)| < n \cdot \varepsilon \). We then have, by the preceding lemma,
\[
|F(D)| \leq \sum_n |F(D_n|) \leq \sum_n n \cdot |D_n| \leq \int_D |F'(x)| \, dx + \varepsilon \cdot |D|,
\]
and hence, \( \varepsilon \) being arbitrary, the inequality (6.6).

The formula (6.6) remains true when we replace in it the derivative \( F'(x) \) by any Dini derivative, provided however that we restrict the latter to be finite in \( D \). The proof then becomes rather more elaborate and requires certain general theorems on derivatives which will be established later (see Chap. IX, §4).

(6.7) **Theorem.** In order that a function \( F(x) \) which is continuous and \( VB \) on a bounded closed set \( E \), be \( AC \) on \( E \), it is necessary and sufficient that \( F(x) \) fulfill the condition \( (N) \) on this set.

**Proof.** In view of Theorem 6.1, it remains to be shown that the condition is sufficient.

Suppose then that \( F \) fulfills the condition \( (N) \) on \( E \). Let \( a_0 \) and \( b_0 \) be the bounds of \( E \), and let \( G \) denote the function which coincides with \( F \) at the points of \( E \) and is linear in the intervals contiguous to \( E \). The function \( G \) is evidently continuous and of bounded variation, and fulfills the condition \( (N) \) on the whole interval \([a_0, b_0]\).

Given any subinterval \( I = [a, b] \) of \([a_0, b_0]\), let us denote by \( D \) the set of the points of \( I \), at which the function \( G \) is derivable, and write \( H = I - D \). Clearly \( |H| = 0 \), and therefore also \( |G(H)| = 0 \).

On the other hand, since the interval with the end-points \( G(a) \) and \( G(b) \) is contained in \( G(I) \), we have by Theorem 6.5
\[
|G(b) - G(a)| \leq |G(D)| + |G(H)| = |G(D)| \leq \int_I |G'(x)| \, dx.
\]

Since this inequality is valid for every subinterval \( I = [a, b] \) of \([a_0, b_0]\) and since by Theorem 7.4, Chap. IV, the derivative \( G'(x) \) is summable on \([a_0, b_0]\), it follows that the function \( G \) is \( AC \) on \([a_0, b_0]\), and therefore that \( F \) is \( AC \) on the set \( E \), where \( F \) and \( G \) coincide.
It is easy to see that the same argument leads to a more general theorem: in order that a continuous function \( F \) which is continuous on an interval \( I_0 \) be absolutely continuous on this interval, it is necessary and sufficient that \( F \) fulfil the condition \( (N) \) on \( I_0 \) and that its derivative exist almost everywhere on \( I_0 \) and be summable on \( I_0 \). This theorem will again be generalized in Chap. IX, § 7.

(8.8) **Theorem.** In order that a function \( F \) which is continuous and VBG on a closed set \( E \) be ACG on \( E \), it is necessary and sufficient that \( F \) fulfil the condition \( (N) \) on this set.

**Proof.** In view of Theorem 6.1, we need only prove the condition \( (N) \) sufficient. Now, since \( F \) is VBG on the set \( E \), this set is expressible as the sum of a sequence of bounded sets \( \{E_n\} \) such that the function \( F \) is VB on each \( E_n \). By continuity of \( F \) on the closed set \( E \), we may suppose (cf. § 4, p. 221) that each set \( E_n \) is closed. Since further \( F \) fulfills the condition \( (N) \) on \( E \), it follows from Theorem 6.7 that the function \( F \) is AC on each \( E_n \), and therefore ACG on \( E \).

§ 7. **Functions VB* and VBG*.** We shall denote by \( V_*(F; E) \) and term strong variation of a finite function \( F \) on a set \( E \), the upper bound of the sums \( \sum_x O(F; I_k) \) where \( \{I_k\} \) is any sequence of non-overlapping intervals whose end-points belong to \( E \) (in accordance with Chap. III, p. 60, \( O(F; I_k) \) denotes the oscillation of \( F \) on the interval \( I_k \)). If \( V_*(F; E) = +\infty \), the function \( F \) will be said to be of bounded variation in the restricted sense on the set \( E \), or \( VB_* \) on \( E \).

Following the order of the definitions of § 4, we shall say further that a finite function is of generalized bounded variation in the restricted sense, or simply, is VBG* on a set \( E \), if \( E \) is the sum of a finite or enumerable sequence of sets on each of which the function is VB*.

In the special case in which the set \( E \) is a closed interval, we clearly have \( V_*(F; E) = V(F; E) = W(F; E) \). It is easy to see that we always have \( V(F; E) \leq V_*(F; E) \); so that every function which is VB* on a set, is VB on this set, and consequently, every function which is VBG* on a set, is VBG on this set. We next observe (by using trivial inequalities for the VB* case, and thence passing on to the VBG* case) that every linear combination, with constant coefficients, of two functions which are VB* [VBG*], and also the product of two such functions, are themselves VB* [VBG*].

Let us observe that, for a function, the property of being VB, VBG, AC, or ACG, on a set \( E \) depends solely on the behaviour of the function on \( E \); whereas the property of being VB* or VBG* on \( E \) depends on the behaviour of the function on the whole of an interval containing \( E \). In other words, of two functions which coincide on a set \( E \), one may be VB* or VBG* on \( E \) and the other not. The same remark applies to the property of being ACG or ACG* with which we shall be concerned in the next §.

We have remarked in § 4, p. 221, that a function which is continuous on a set \( E \) and which is VB on an everywhere dense subset of \( E \), is necessarily VB on \( E \). A similar result is true for functions which are VB*, the assumption of continuity of the given function being now superfluous. We have in fact:

(7.1) **Theorem.** Every finite function \( F \) which is VB* on a bounded set \( E \) is equally so on the closure \( \bar{E} \) of this set.

**Proof.** Let \( a \) and \( b \) denote the bounds of \( E \) and therefore also of \( \bar{E} \). Let \( a = a_0 < a_1 < \ldots < a_n = b \) be any finite sequence of points of \( \bar{E} \); we write \( I = [a, b] \) and \( I_k = [a_{k-1}, a_k] \) for \( k = 1, 2, \ldots, n \). We shall say that an interval \( I_k \) is of the first class if it contains points of \( E \), and otherwise of the second class. The intervals \( I_1 \) and \( I_n \) are clearly of the first class, and we see easily that, if an interval \( I_k \) is of the second class, then both the adjacent intervals \( I_{k-1} \) and \( I_{k+1} \) are certainly of the first class.

Let us denote by \( 1 = i_0 < i_1 < \ldots < i_r = n \) the suffixes of the intervals \( I_k \) of the first class and by \( j_0 < j_1 < \ldots < j_r \) those of the second. With each interval \( I_{i_k} \) of the first class we associate a point \( b_k \in I_{i_k} \) \( \bar{E} \) and we write \( J_k = [b_{i_{k-1}}, b_k] \) for \( k = 1, 2, \ldots, r \). It is easy to see that

\[
\sum_{n=0}^{r} O(F; I_{i_k}) \leq O(F; I_1) + O(F; I_n) + 2 \sum_{k=1}^{r} O(F; J_k)
\]

and

\[
\sum_{n=0}^{r} O(F; I_{i_k}) \leq \sum_{k=1}^{r} O(F; J_k).
\]

Hence, \( \sum_{k=1}^{r} O(F; I_k) \leq 3 \cdot \sum_{k=1}^{r} O(F; J_k) + 2 \cdot O(F; I) \leq 3 \cdot [V_*(F; E) + O(F; I)] \), and therefore \( V_*(F; E) \leq 3 \cdot [V_*(F; E) + O(F; I)] \leq +\infty \). This completes the proof.
(7.2) **Theorem.** If a function $F$ is VBG$_n$ on a set $E$, then $F$ is dericable at almost all points of this set; and further if $N$ denotes the set of the points $x$ of $E$ at which the function has no derivative, finite or infinite, then $|F[N]| = A(B(F; N)) = 0$.

**Proof.** We may clearly suppose that the set $E$ is bounded and that the function $F$ is VB$_n$ on $E$. Moreover, by Theorem 7.1, we may suppose that the set $E$ is closed.

Let therefore $a$ and $b$ denote the bounds of $E$ on the left and on the right, and $(I_n)_{n=1,2,...}$ the sequence of the intervals contiguous to $E$. Writing $m_a$ and $M_a$, respectively for the lower and upper bounds of $F$ on $I_n$, we define two functions $m(x)$ and $M(x)$ on $[a, b]$ making $m(x) = m_a$ and $M(x) = M_a$ for $x \in I_n^2$, where $n = 1, 2, ...$, and $m(x) = M(x) = F(x)$ for $x \in E$. The two functions $m(x)$ and $M(x)$ thus defined are plainly of bounded variation on the whole interval $[a, b]$ and coincide with $F(x)$ on the set $E$. Therefore, denoting by $N_0$ the set of the points $x \in E$ at which either one at least of the (finite or infinite) derivatives $m'(x)$ and $M'(x)$ does not exist, or both exist without being equal, we find by Theorem 9.1, Chap. IV, that

$$|F[N_0]| = |A(B(F; N_0))| = 0.$$ (7.3)

On the other hand, $m(x) = F(x) = M(x)$ at every point $x$ of $E$, while $m(x) \leq F(x) \leq M(x)$ on the whole interval $[a, b]$. It follows that the derivative $F'(x) = m'(x) = M'(x)$ exists at each point $x$ of $E$, except at most those of the set $N_0$ which is subject to the relation (7.3). Finally, since the functions $m(x)$ and $M(x)$ are derivable almost everywhere on the interval $[a, b]$, the function $F$ must be derivable at almost all points of $E$, and this completes the proof.

Theorem 7.2 (for continuous functions and in a slightly less complete form) was first proved by Denjoy and by Luzin, independently. It plays in the theory of the Denjoy-Perron integral (vide, below, Chap. VII) a part similar to that of Lebesgue's Theorem (Chap. IV, §8) in the theory of the Lebesgue integral. A corresponding part is played in the theory of the Denjoy-Khintchine integral by Theorem 4.3. But the latter is stated in terms of approximate derivation (cf. the example of p. 224) whereas Theorem 7.2, which requires no modification of the notion of derivative, is, for functions of a real variable, a direct generalization of Lebesgue's Theorem.

§ 8. Functions AC$_n$ and ACG$_n$. A finite function $F$ is said to be absolutely continuous in the restricted sense on a bounded set $E$, or to be AC$_n$ on $E$, if $F$ is bounded on an interval containing $E$ and if to each $\varepsilon > 0$ there corresponds an $\lambda > 0$ such that, for every finite sequence of non-overlapping intervals $(I_i)$ whose end-points belong to $E$, the inequality $\sum_i |I_i| < \lambda$ implies $\sum_i O(F; I_i) < \varepsilon$.

A function will be termed generalized absolutely continuous on a set $E$, or AC$_n$ on $E$, if the function is continuous on $E$ and if the set $E$ is expressable as the sum of a sequence of bounded sets on each of which the function is AC$_n$.

In the case in which the set $E$ is an interval, the class of functions AC$_n$ on $E$ coincides with that of the functions which are absolutely continuous on $E$ in the ordinary sense. Every function which is AC$_n$ on an arbitrary set $E$ is AC on $E$, and every function which is ACG$_n$ on $E$ is AC on $E$. On the other hand, any function which is AC$_n$ on a bounded set is VB$_n$ on this set, and therefore, any function which is ACG$_n$ on a set is VB$_n$ on this set. To see this, let $F$ be AC$_n$ on a bounded set $E$. We can then determine a positive number $\eta_0$ such that $V_*(F; E-I) \leq 1$ for every interval $I$ of length less than $\eta_0$. Let $I$ be the smallest interval containing $E$, let $M$ be the upper bound of $|F(x)|$ on $I$, and suppose $J$ expressed as the sum of a finite number of non-overlapping intervals $J_1, J_2, ..., J_p$, each of length less than $\eta_0$. We shall then have

$$V_*(F; E) \leq \sum_{j=1}^p V_*(F; E-J_j) + 2M \leq (2M+1)\cdot p < +\infty,$$

and this shows that the function $F$ is VB$_n$ on $E$.

Thus a function which is AC$_n$ on a bounded set $E$ is both AC and VB$_n$ on this set, and similarly a function which is ACG$_n$ on $E$ is both ACG and VB$_n$ on $E$. The converse also is true, provided that the set $E$ is restricted to be closed (vide, below, Theorem 8.8). Instead of giving a special proof of this result, we shall establish some more general theorems about the relations between the notions VB, AC, VB$_n$, AC$_n$, VB$_n$, ACG, and ACG$_n$.

(8.1) **Lemma.** Let $E$ denote a bounded closed set, $(J_i)$ the sequence of the intervals contiguous to $E$, and $I_0$ the smallest interval containing $E$. Then, for any function $F$ which is finite on $I_0$, we have

$$O(F; I_0) \leq V(F; E) + 2 \sum_i O(F; J_i).$$
Proof. Let \( M_1, m_1 \) and \( M_2, m_2 \) be the bounds (upper, lower) of \( F \) on \( E \) and on \( I_0 \) respectively. Let \( M_0 \) be any finite number less than \( M_0 \), and \( x_0 \) a point of \( I_0 \) such that \( M_0 \leq F(x) \leq M \). If we have \( x_0 \in E \), this inequality implies \( M_0 \leq M_0 \), while if \( x_0 \) belongs to an interval, \( J_k \), say, of the sequence \( \{J_n\} \), \( M_0 \leq M + \mathcal{O}(F; J_k) \). Hence
\[
(8.3) \quad M_0 \leq M + \sum x \mathcal{O}(F; J_k),
\]
and similarly
\[
(8.4) \quad m_0 \geq m - \sum x \mathcal{O}(F; J_k).
\]
On subtracting (8.4) from (8.3), we obtain, since \( M - m \leq V(F; E) \), the relation (8.2).

(8.5) Theorem. In order that a function \( F \) which is VB [AC] on a bounded closed set \( E \), be VB* [AC*] on \( E \), it is necessary and sufficient that the series of its oscillations on the intervals contiguous to \( E \) be convergent.

Proof. The necessity of these conditions is obvious (cf. above p. 231); we have therefore only to prove them sufficient.

Let then \( \{J_n\} \) denote the sequence of the intervals contiguous to \( E \), and suppose that
\[
(8.6) \quad \sum x \mathcal{O}(F; J_n) < +\infty.
\]
We shall consider the two cases separately:

1° The function \( F \) is VB on \( E \), i.e. \( V(F; E) < +\infty \). Then by Lemma 8.1, we have for every sequence \( \{I_n\} \) of non-overlapping intervals whose end-points belong to \( E \),
\[
\sum_{n=1}^{\infty} \mathcal{O}(F; I_n) \leq \sum_{n=1}^{\infty} V(F; E - I_n) + 2 \sum \mathcal{O}(F; J_n).
\]
It follows by (8.6) that \( V(F; E) < +\infty \), i.e. that the function \( F \) is VB* on \( E \).

2° The function \( F \) is AC on \( E \). Then, given any \( \varepsilon > 0 \), there exists a number \( \eta > 0 \) such that for every sequence of non-overlapping intervals \( \{I_n\} \) whose end-points belong to \( E \), the inequality \( \sum |I_n| < \eta \) implies \( \sum V(F; E - I_n) < \varepsilon / 2 \). Now by (8.6), there exists a positive integer \( k_0 \) such that
\[
(8.7) \quad \sum_{k=k_0}^{\infty} \mathcal{O}(F; J_k) < \varepsilon / 4.
\]
Denote by \( \eta \) the smallest of the \( k_0 + 1 \) numbers \( \eta, |J_1|, |J_2|, \ldots, |J_{k_0}| \), and let \( \{\tilde{I}_n\} \) be any sequence of non-overlapping intervals with end-points in \( E \), the sum of whose lengths is less than \( \eta \). None of these intervals \( \tilde{I}_n \) can contain one of the first \( k_0 \) intervals of the sequence \( \{J_n\} \), and it follows from (8.7) and from Lemma 3.1, that
\[
\sum \mathcal{O}(F; \tilde{I}_n) \leq \sum \mathcal{O}(F; I_n) + \varepsilon / 2 < \varepsilon. \]
Therefore the function \( F \) is AC* on \( E \), and this completes the proof.

(8.8) Theorem. In order that a function \( F \) be AC* [ACG*] on a bounded closed set \( E \), it is necessary and sufficient that \( F \) be both VB* and AC [VBG* and ACG] on \( E \).

Proof. The necessity of these conditions is obvious, so that we have only to prove them sufficient.

Now, if the function \( F \) is both VB* and AC on \( E \), it follows at once from Theorem 8.5 that \( F \) is AC* on \( E \). If on the other hand, \( F \) is VBG* and ACG on \( E \), we can express the set \( E \) as the sum of a sequence of sets \( \{E_n\} \) each of which \( F \) is both VB* and AC.

Since \( F \) is ACG and so continuous, on the set \( E_n \) which is by hypothesis closed, \( F \) is AC on the closure \( \bar{E}_n \) of each \( E_n \). Similarly, by Theorem 7.1, \( F \) is VB* on each \( \bar{E}_n \). Therefore by what has just been proved, \( F \) is AC* on each of the sets \( \bar{E}_n \) and so, ACG* on the set \( E \).

Theorem 8.8 ceases to hold if we remove the restriction that the set \( E \) is closed. Let \( E \) be the set of irrational points, and \( \{a_i\}_{i=1}^{\infty} \) the sequence of rational points, of the interval \([0, 1]\); and let \( F(x) = 0 \) for \( x \in E \), and \( F(x) = 1, 2, \ldots \) for \( x = a_i, \ldots \). The function \( F \) thus defined is evidently VBG* and ACG on \( E \). To show that \( F \) is not AC*, nor even ACG*, on \( E \), suppose that the set \( E \) is the sum of a sequence of sets \( \{E_n\} \) on each of which \( F \) is AC*. By Baire's Theorem (Chap. II, Theorem 9.2), one at least of the sets \( E_n \) would be everywhere dense in a (non-degenerate) subinterval of \([0, 1]\). But this is plainly impossible, since every subinterval of \([0, 1]\) contains, in its interior, points of discontinuity of the function \( F \).

§ 9. Definitions of Denjoy-Lusin. The definitions which we have adopted in this chapter for the classes of functions VBG, ACG, VBG*, and ACG* are based on the ideas of A. Khintchine [3]. Rather different definitions were given by N. Lusin [1] and A. Denjoy [6], which are equivalent to those of Khintchine when we restrict ourselves to continuous functions. We give them here, in the form of necessary and sufficient conditions, in the following theorem.

(9.1) Theorem. In order that a function which is continuous on a closed set \( E \), be VBG [VBG*, ACG, ACG*] on \( E \), it is necessary and sufficient that every closed subset of \( E \) contain a portion on which the function is VB [VB*, AC, AC*].
Proof. We shall deal only with the VBG case, the proof for the other three cases being quite similar.

The condition is necessary. Let \( F \) be a function which is continuous and VBG on \( E \). We can then express the set \( E \) as the sum of a sequence of sets \( \{E_n\} \) on each of which the function \( F \) is VBG and, by continuity of \( F \), the sets \( E_n \) may be supposed closed. Then by Baire's Theorem (Chap. II, § 9), every closed subset of \( E \) has a portion \( F \) contained wholly in one of the sets \( E_n \). The function \( F \), which is VBG on each \( E_n \), is thus certainly VBG on \( P \).

The condition is sufficient. Suppose that \( F \) is a continuous function on \( E \) and that every closed subset of \( E \) contains a portion on which \( F \) is VBG. Let \( \{I_n\} \) be the sequence of all the open intervals \( I \) with rational end-points such that \( F \) is VBG on \( E-I \). Let \( Q=\sum I_n \) and \( H=E-Q \). Plainly \( F \) is VBG on \( Q \) and we need only prove that the set \( H \) is empty.

Suppose therefore that \( H \neq \emptyset \). Since \( H \) is clearly a closed set, there exists, by hypothesis, an open interval \( J \) such that \( H-J \neq \emptyset \) and that the function \( F \) is VBG on \( H-J \). We may evidently assume that the end-points of \( J \) are rational. Therefore, the function \( F \), which is VBG on the set \( Q \), is also VBG on the set \( E-J \subset H-J \). This requires \( J \) to belong to the sequence of intervals \( \{I_n\} \) and we have a contradiction, since the set \( H \), by definition, has no points in common with any of the intervals \( I_n \).

Theorem 9.1 shows in particular that every continuous function which is VBG on an interval \( I \) is at the same time VBG on some subinterval of \( I \). It follows that for every continuous function which is VBG on an interval \( I \), there exists an everywhere dense system of subintervals on each of which the function is almost everywhere derivable, although this function may, as shown in § 5, have no derivative at the points of a set of positive measure.

§ 10. Criteria for the classes of functions VBG\( \ast \), ACG\( \ast \), VBG and ACG. A series of theorems enabling us to distinguish certain types of functions of generalized bounded variation and certain types of generalized absolutely continuous functions, are due to A. Denjoy [6].

(10.1) Theorem. If \( F(x) \) is a function which fulfills at all points of a set, except at most those of an enumerable subset, one of the inequalities

\[ F(x) < +\infty \quad \text{or} \quad F(x) > -\infty, \]

then the function \( F(x) \) is VBG\( \ast \) on this set.
Proof. It is enough to show that if at every point \( x \) of a set \( A \) the two extreme right-hand derivatives \( F^+(x) \) and \( F^-(x) \) are finite, then \( A \) is expressible as the sum of an at most enumerable infinity of sets on each of which the function \( F \) is \( AC_\alpha \).

Let \( A_n \) denote, for each positive integer \( n \), the set of the points \( x \in A \) such that, for every \( t \),
\[
0 < t - x < \frac{1}{n} \quad \text{implies} \quad |F(t) - F(x)| < n(t - x);
\]
and, for each integer \( i \), let \( A_n^i \) denote the common part of \( A_n \) and of the interval \([i/n, (i+1)/n]\). Plainly \( A = \sum_{n=1}^{\infty} A_n = \sum_{n=1}^{\infty} \sum_{i=1}^{\infty} A_n^i \).

Now, if \( I = [x_a, x_b] \) is any interval whose end-points belong to \( A_n^i \), we have, for every \( t \in I \), the inequality \( 0 < t - x < \frac{1}{n} \), and so, on account of (10.7), \( |F(t) - F(x)| < n(t - x) < n|I| \). This gives us \( O(F; I) < 2n|I| \); and therefore for any finite sequence \( \{I_j\} \) of such intervals, \( \sum_{j=1}^{\infty} O(F; I_j) < 2n \sum_{j=1}^{\infty} |I_j| \). It follows that the function \( F \) is \( AC_\alpha \) on each of the sets \( A_n \), and this completes the proof.

Theorem 10.5 shows, in particular, that every function which is continuous and everywhere derivable (even only uni-directionally) is \( AC_\alpha \). Nevertheless as we saw in Chaps. VI. p. 187, such a function need not be absolutely continuous.

In view of Theorem 7.2, we may state also the following corollary of Theorems 10.1 and 10.5: A function \( F \) which fulfills at each point of a set \( E \) one at least of the inequalities (10.2) or (10.6), is derivable at almost all points of \( E \). In particular therefore, the set of the points at which a function has (on one side at least) its derivative infinite, is of measure zero. These statements will be generalized in Chaps. IX, §4.

Theorems 10.1 and 10.5 contain sufficient conditions in order that a function be \( VBG_\alpha \) or \( ACG_\alpha \), but these conditions are clearly not necessary. Nevertheless, by employing the notion of derivates relative to a function (cf. Chap. IV, p. 108), it is easy to establish conditions similar to those of the preceding theorems, the conditions being this time both sufficient and necessary. Thus, as shown by A. J. Warr [3]:

In order that a finite function \( F \) be \( VBG_\alpha \) on a set \( E \), it is necessary and sufficient that there exist a bounded increasing function \( U \) such that the extreme derivates of \( F \) with respect to \( U \) are finite at each point of \( E \) except, perhaps, those of an enumerable set.

1° In order to establish the necessity of the condition, let us suppose first that the function \( F \) is \( VB_\alpha \) on \( E \). In view of Theorem 7.1 we may assume that the set \( E \) is bounded and closed. Let \([a, b]\) be the smallest interval containing \( E \); and, for each point \( x \) of the interval \([a, b]\), let \( V_1(x) \) and \( V_2(x) \) denote the strong variations of \( F \) (cf. §7) on the parts of \( E \) contained in the intervals \([a, x]\) and \([x, b]\), respectively. Finally, for each \( x \) of \([a, b]\), let \( U(x) = V_1(x) - V_2(x) + x \). The function \( U \) thus defined is increasing and finite on \([a, b]\), and can therefore be continued as a bounded increasing function on the whole straight line \( U \). We see at once that throughout the set \( E \), except at most at the points \( a \) and \( b \), the derivates of the function \( F \) with respect to \( U \) are finite and indeed cannot exceed in absolute value the number 1.

Suppose now given any function \( F \) which is \( VB_\alpha \) on \( E \). The set \( E \) is then expressible as the sum of a sequence \( \{E_n\} \) of sets on each of which the function \( F \) is \( VB_\alpha \). Consequently, by what has just been proved, there exists for each \( n \) a bounded increasing function \( V_n \) with respect to which the function \( F \) possesses finite derivates at each point of the set \( E_n \) except at most at the bounds of this set. Therefore, denoting by \( M_n \) the upper bound of \(|V_n(x)|\) and writing \( U(x) = \sum_{n=1}^{\infty} V_n(x)/2^n M_n \), we see at once that the function \( U \) thus defined is increasing and bounded and that at each point of \( E \), except perhaps those of an enumerable set, the function \( F \) possesses finite derivates with respect to \( U \).

2° The condition is sufficient. Let \( F \) be a finite function having at each point of \( E \), except perhaps at those of an enumerable subset, finite derivates with respect to a bounded increasing function \( U \). For each positive integer \( n \), let \( E_n \) denote the set of the points \( x \) of \( E \) for which the inequality \( |t - x| < 1/n \) implies \( |F(t) - F(x)| < n|t - x|\); and let each \( E_n \) be expressed as the sum of a sequence \( \{E_n^i\} \) of sets of diameter less than \( 1/n \) and, for each \( n \), at once that the function \( F \) is \( VB_\alpha \) on \( E \). This completes the proof.

If we analyze the first part of the above argument, we see that if the function \( F \) is \( VB_\alpha \) on \( E \) and moreover bounded on an interval containing the set \( E \) in its interior, there exists an increasing bounded function \( U \) with respect to which the function \( F \) has its derivates finite at each point of \( E \). Moreover, if the function \( F \) is continuous on an interval containing \( E \) in its interior, the function \( U \) may be defined in such a way as to be itself continuous (cf. the proof of Lemma 3.4, Chap. VIII). Finally, it can be shown that in order that a function \( F \) be \( ACG_\alpha \) on an open interval \( I \), it is necessary and sufficient that there exist an increasing and absolutely continuous function with respect to which the function \( F \) has its derivates finite at every point of \( I \).

\textbf{Theorem.} If at every point \( x \) of a set \( E \), except perhaps at the points of an enumerable subset, a function \( F \) fulfills any one of the inequalities
\[
F^+(x) < +\infty, \quad F^+(x) > -\infty, \quad F^-(x) < +\infty, \quad F^-(x) > -\infty,
\]
then \( F \) is \( VBG_\alpha \) on \( E \).
CHAPTER VII. Functions of generalized bounded variation.

Proof. We need only consider the case of the first of the inequalities (10.9) and that of the first of the inequalities (10.10). It is therefore sufficient to show that each of the sets $A = E[F^b(x) < +\infty]$ and $B = E[F^b(x) < +\infty]$ is expressible as the sum of an enumerable infinity of sets on which each of $F$ is of bounded variation.

Consider first the set $A$. Given any positive integer $n$, let $A_n$ denote the set of all the points $x \in A$ such that, for every $t$,

$$0 \leq t - x \leq 1/n$$

implies $F(t) - F(x) \leq n \cdot (t - x)$,

and by $A_n^i$, for each integer $i$, the part of $A_n$ contained in the interval $[i/n, (i + 1)/n]$. Let $F_n(x) = F(x) - nx$.

For every pair $x_1, x_2$ of points of $A_n^i$, where $x_1 \leq x_2$, we have $0 \leq x_1 - x_2 \leq 1/n$ and so, by (10.11), $F(x_1) - F(x_2) \leq n \cdot (x_1 - x_2)$, i.e., $F_n(x_1) - F_n(x_2) \leq 0$. The function $F_n(x)$ is thus monotone non-increasing on each set $A_n^i$ and it follows that $A_n^i$ is expressible as the sum of a sequence of sets $\{A_n^{i,j}\}_{j=1}^\infty$ on each of which $F_n(x)$ is monotone and bounded. The function $F(x) = F_n(x) + nx$ is then plainly of bounded variation on each of the sets $A_n^i$, and moreover we have

$$A = \sum_{n=1}^\infty A_n = \sum_{n=1}^\infty \sum_{i=1}^\infty A_n^i.$$

Consider now the set $B$. From the definitions of approximate upper limit and approximate upper derivate (cf. § 3, p. 220), it follows at once that to each point $x \in B$ we can make correspond a positive integer $n$ such that the set $E\left[\frac{F(x) - F(y)}{x - y} \geq n\right]$ has the point $x$ as a point of dispersion. Therefore, denoting by $B_n$ the set of the points $x \in B$ such that the inequality $0 \leq x \leq 1/n$ implies both the inequalities

$$E\left[\frac{F(x) - F(y)}{x - y} \geq n\right] \leq h/3$$

and

$$E\left[\frac{F(x) - F(y)}{x - y} \geq n\right] \leq h/3,$$

we have $B = \sum_{n=1}^\infty B_n$. We denote further, for every integer $i$, by $B_n^i$ the part of $B_n$ contained in the interval $[i/n, (i + 1)/n]$ and we write, as before, $F_n(x) = F(x) - nx$.

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The main part of the proof consists in showing that, for every $i$, the function $F_n(x)$ is monotone on $B_n^i$.

For this purpose, let $x_1, x_2$ be any pair of points of a $B_n^i$, and let $x_1 < x_2$. We plainly have $0 < x_2 - x_1 < 1/n$, so that by writing $x = x_1$ and $h = x_2 - x_1$, we obtain

$$E\left[\frac{F(x) - F(y)}{x - y} \geq n\right] \leq h/3.$$
CHAPTER VIII.

Denjoy integrals.

§ 1. Descriptive definition of the Denjoy integrals.
We shall base the study of the Denjoy integrals on their descriptive definition. The essential ideas have already been sketched in Chap. VII, § 1. We now complete them further as follows.

A function of a real variable \( f \) will be termed \( S \)-integrable on an interval \( I=[a,b] \) if there exists a function \( F \) which is ACG on \( I \) and which has \( f \) for its approximate derivative almost everywhere. The function \( F \) is then called indefinite \( S \)-integral of \( f \) on \( I \). Its increment \( F(b)-F(a) \) over the interval \( I \) is termed definite \( S \)-integral of \( f \) over \( I \) and is denoted by

\[
(\mathcal{S}) \int_a^b f(x) \, dx.
\]

Similarly, a function \( f \) will be termed \( \mathcal{S}_* \)-integrable on an interval \( I=[a,b] \), if there exists a function \( F \) which is ACG* on \( I \) and which has \( f \) for its ordinary derivative almost everywhere. The function \( F \) is then called indefinite \( \mathcal{S}_* \)-integral of \( f \) on \( I \); the difference \( F(b)-F(a) \) is termed definite \( \mathcal{S}_* \)-integral of \( f \) over \( I \) and denoted by

\[
(\mathcal{S}_*) \int_a^b f(x) \, dx.
\]

For uniformity of notation, the Lebesgue integral will frequently be called \( L \)-integral.

The integrals \( S \) and \( \mathcal{S}_* \) are often given the names of Denjoy integrals in the wide sense, and in the restricted sense, respectively. The first of these is also termed Denjoy-Khintchine integral (cf. Chap. VII, § 1), and the second, Denjoy-Perron integral (for the latter, as we shall see below in § 3, is equivalent to the Perron integral considered in Chap. VI).