

Differential equations in a linear ring

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BARBARA MAŻBIC-KULMA (Warszawa)

The purpose of this paper is to solve linear differential equations with coefficients in a linear ring, in particular ordinary linear differential equations with variable coefficients, using the definition of algebraic derivative given by D. Przeworska-Rolewicz [3].

Definition 1. Let X be a commutative linear ring (over a field F) with the unit e.

If for a linear operator D acting in X there is a linear operator R defined on X such that RX is contained in the domain \mathscr{D}_D of D and

 $1^{\circ} DR = I,$

2° the operator I+Rp is invertible for any $p \in X$ (1),

3° D(xy) = (Dx)y + x(Dy) for $x, y \in \mathcal{D}_D$, then D will be called algebraic derivative and R — algebraic integral on X, the kernel $Z_D = \{z \in \mathcal{D}_D : Dz = 0\}$ is called the space of constants.

In particular, it follows from 2° that the operator $I-\lambda R$ is invertible for any $\lambda \in F$.

Indeed, $I - \lambda R = I + R(-\lambda e)$.

Proposition 1.

(i) $D(\lambda e) = 0$ for any $\lambda \in F$.

(ii) $Dx^n = nx^{n-1}Dx \text{ for } n = 1, 2, ...$

(iii) $D^k R^k = I$ for k = 1, 2, ...

(iv) There is a q such that Dq = e, namely q = Re.

(v) $(D+pI)(I+Rp)^{-1} = D$ for any $p \in X$.

Proof. (i) For all $\lambda \in F$ and $x \in \mathcal{D}_D$

$$Dx = D(ex) = (De)x + e(Dx) = (De)x + Dx.$$

Hence (De)x=0 and arbitrariness of x imply that De=0. Therefore $D(\lambda e)=\lambda De=0$.

⁽¹⁾ By Ep we will mean always the superposition of the operator E and of the operator of multiplication by an element $p \in X$.

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(ii), (iii) follows by an easy induction.

(iv) Dq = DRe = e (compare with Theorem 3.4 of [3]).

(v) Since D+pI=D+Ip=D+DRp=D(I+Rp), we find

$$(D+pI)(I+Rp)^{-1} = D(I+Rp)(I+Rp)^{-1} = D.$$

Now we will consider the following equation:

(1)
$$D^{k}x + p_{1}D^{k-1}x + p_{2}D^{k-2}x + \ldots + p_{k-1}Dx + p_{k}x = y$$

where $y \in X$ and $p_i \in X$ for i = 1, 2, ..., k. We denote $D^n p = p^{(n)}$ for n = 0, 1, ...

LEMMA 1. We have

(2)
$$aD^{k}x = \sum_{i=0}^{k} (-1)^{i} {k \choose i} D^{k-i}(a^{(i)}x)$$

for all positive integers k and for an arbitrary $a \in \mathcal{D}_D$.

Proof, by induction. For k=1 the formula (2) is true because aDx = D(ax) - (Da)x. We assume that (2) is true for k=n and we shall prove that (2) is true for k=n+1, i. e. that

$$aD^{n+1}x = \sum_{i=1}^{n+1} (-1)^i \binom{n+1}{i} D^{n+1-i}(a^{(i)}x).$$

Since

$$aD^{n+1}x = aD(D^nx) = D(aD^nx) - (Da)D^nx,$$

the induction assumption implies that

$$\begin{split} aD^{n+1}x &= D\Big[\sum_{i=0}^{n} (-1)^{i} \binom{n}{i} D^{n-i} (a^{(i)}x)\Big] - \sum_{j=0}^{n} (-1)^{j} \binom{n}{j} D^{n-j} (a^{(j+1)}x) \\ &= \sum_{i=0}^{n} (-1)^{i} \binom{n}{i} D^{n+1-i} (a^{(i)}x) + \sum_{j=0}^{n} (-1)^{j+1} \binom{n}{j} D^{n-j} (a^{(j+1)}x) \\ &= \sum_{i=0}^{n} (-1)^{i} \binom{n}{i} D^{n+1-i} (a^{(i)}x) + \sum_{i=1}^{n+1} (-1)^{i} \binom{n}{i-1} D^{n+1-i} (a^{(i)}x) \\ &= D^{n+1} (ax) + \sum_{i=1}^{n} (-1)^{i} \Big[\binom{n}{i} + \binom{n}{i-1}\Big] D^{n+1-i} (a^{(i)}x) + \\ &+ (-1)^{n+1} a^{(n+1)}x = \sum_{i=0}^{n+1} (-1)^{i} \binom{n+1}{i} D^{n+1-i} (a^{(i)}x) \end{split}$$

what was to be proved.

THEOREM 1. The general form of a solution of the equation (1) is

$$x = \left(I + \sum_{j=1}^k R^j \tilde{p}_j\right)^{-1} \left(R^k y + \sum_{m=0}^{k-1} R^m z_m\right)$$

where

1. $z_m \in Z_D$ for m = 0, 1, ..., k-1,

2.
$$\tilde{p}_{i} = \sum_{v=0}^{j-1} (-1)^{w} {k+w-j \choose w} p_{i-w}^{(w)},$$

3. the operator $(I + \sum_{j=1}^{k} R^{j} \tilde{p}_{j})$ is invertible (2),

4. $p_i \in \mathcal{D}_{pk-i}$ for j = 1, 2, ..., k.

Proof. Applying Lemma 1 to the left side of (1) we obtain:

$$D^k x + \sum_{i=0}^{k-1} (-1)^i {k-1 \choose i} D^{k-1-i} (p_1^{(i)} x) + \sum_{i=0}^{k-2} (-1)^i {k-2 \choose i} D^{k-2-i} (p_2^{(i)} x) + \dots + \sum_{i=0}^{1} (-1)^i {1 \choose i} D^{1-i} (p_{k-1}^{(i)} x) + p_k x = y.$$

If we order the left side of the equation with respect to the powers of D,

$$D^{k}x + D^{k-1} \left[{k-1 \choose 0} p_{1}x \right] + D^{k-2} \left[{k-2 \choose 0} p_{2} - {k-1 \choose 1} p'_{1}x \right] + \dots + \\ + \left[p_{k}x + (-1)^{1} p'_{k-1}x + \dots + (-1)^{k-1} p_{1}^{(k-1)}x \right] = y.$$

In virtue of Proposition 1 (iii) we have

$$D^k x + D^k R(p_1 x) + \ldots + D^k R^k [p_k x + \ldots + (-1)^{k-1} p_1^{(k-1)} x] = y.$$

Hence finally:

$$D^kig(I+\sum_{i=1}^k R^j ilde p_jig)\,x=y, \quad ext{ where } \quad ilde p_j=\sum_{w=0}^{j-1} (-1)^wig(ig)^wig(ig)^wig)_{j-w}.$$

Basing on the assumption (3) we obtain

$$D^k x = \left(I + \sum_{j=1}^k \, R^j ilde p_j
ight)^{-1} y \,.$$

From the Corollary 2.5 in [3] we have

$$x = \left(I + \sum_{j=1}^{k} R^{j} \tilde{p}_{j}\right)^{-1} \left(R^{k} y + \sum_{m=0}^{k-1} R^{m} z_{m}\right)$$

where $z_m \in Z_D$ for m = 0, 1, ..., k-1 what was to be proved.

⁽²⁾ This assumption does not limit us essentially because it is equivalent to the assumption that the respective Volterra integral equation is solvable uniquely, what is satisfied.

B. Mażbic-Kulma

EXAMPLE 1. Let us consider the space C[0, 1] and an ordinary differential equation:

$$x'' + px' + qx = y,$$

where $p, q, p', y \in C[0, 1]$.

Then, as follows from Theorem 1 we obtain:

$$[I+Rp+R^2(q-p')]x = R^2y+Rz_1+z_2$$

what implies

(3)
$$x(t) + \int_{0}^{t} [p(s) + (t-s)(q(s) - p'(s))] x(s) ds = y_{1}(t),$$

where

$$y_1(t) = R^2 y + R z_1 + z_2$$
.

Solving a corresponding Volterra integral equation (see [1]) we obtain:

$$x(t) = y_1(t) + \int_0^t \mathcal{N}(t,s) y_1(s) ds,$$

where the kernel

$$\begin{split} \mathcal{N}(t,s) &= N(t,s) + \sum_{n=1}^{\infty} N_n(t,s), \\ N(t,s) &= p(s) + (t-s) \big(q(s) - p'(s) \big), \\ N_n(t,s) &= \int\limits_{-t}^{t} N(t,w) N_{n-1}(w,s) \, dw, \quad N_0 &= N. \end{split}$$

It is easy to check that the solution x(t) defined by the formula (3) is twice differentiable.

We denote now

$$v_p(z) = (I + Rp)^{-1}z$$
 for $z \in Z_p$; $p \in X$.

As follows from Theorem 1, $v_p(z)$ is a solution of the equation (D+pI)x=0. $v_p(z)$ is a linear family with respect to z, because for all $a, b \in F$

$$v_p(az_1 + bz_2) = av_p(z_1) + bv_p(z_2)$$
.

From the definition we have

$$(D+pI)v_p(z) = (D+pI)v_p(z) = D(I+Rp)v_p(z) = Dz = 0$$

For a fixed $p \in X$ let us denote

$$V_p = \{v_p(z) \colon z \in Z_D\}.$$

The definition implies that the set $V_{-\lambda e}$ is the eigenspace corresponding to the eigenvalue $-\lambda$.



PROPOSITION 2. For all $p, q \in X$

$$V_n V_a \subset V_{n+a}$$
.

Proof. By the assumption we have: $Dv_p(z) = pv_p(z)$, $Dv_q(z) = qv_q(z)$ and $Dv_{n+q}(z) = (p+q)v_{n+q}(z)$, for all $z \in Z_D$. Hence

$$D[v_n(z)v_n(z)] = (Dv_n(z))v_n(z) + v_n(z)(Dv_n(z)) = (p+q)v_n(z)v_n(z).$$

This implies that

$$V_p V_q \subset V_{p+q}$$
.

We do not know if the opposite inclusion holds or not.

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INSTITUTE OF MATHEMATICS OF THE POLISH ACADEMY OF SCIENCES INSTITUT MATEMATYCZNY POLSKIEJ AKADEMII NAUK

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