

On spaces of holomorphic functions

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S. ROLEWICZ (Warszawa)

In this paper we consider locally convex metrisable spaces whose elements are analytic functions of several variables. We develop Kolmogorov's ideas [14], which concern the existence of continuous linear mappings at such spaces. In particular, we consider the following problem: For which domains D_1 and D_2 in Euclidean complex spaces of dimensions k_1 and k_2 , respectively, the spaces $\mathscr{H}(D)$ and $\mathscr{H}(D_1)$ — of all holomorphic (1) functions defined on these domains — are isomorphic (linearly homeomorphic).

Our results (Corollaries 4.1, 4.2, and 4.3) contain as particular cases a result of Kolmogorov which states that if D_1 and D_2 are polycylinders and dim $D_1 \neq \dim D_2$, then the spaces $\mathscr{H}(D_1)$ and $\mathscr{H}(D_2)$ are not isomorphic, and a result of Pełczyński [21] stating that the spaces of all entire functions of one variable and $\mathscr{H}(C_0)$ — of all holomorphic functions defined for |z| < 1 — are not isomorphic.

We also consider the spaces of all holomorphic functions having a given degree of growth.

Similarly to Kolmogorov [14] and Pełczyński [21], in order to establish that given spaces are not isomorphic we compute the so-called "approximative dimension", which is an invariant of linear homeomorphisms. Our method of computing approximative dimension is different from that of Kolmogorov-Tichomirov [15] and Erochin [9]. It is based on finding some matrix representations of a given space by basic expansions. A matrix representation determines the isomorphic structure of the space, in particular it determines its approximative dimension. Matrix representations of some spaces of holomorphic functions are found in § 3 and in § 5, section 2. Examples given in § 5 show that non-isomorphic spaces can have the same approximative dimension. However, under the assumption that spaces have matrix representations of a special form, the equality of approximative dimensions implies the isomorphism of the spaces (Theorem 5.3).

⁽¹⁾ i. e. analytic and one-valued functions.



In many cases the matrix representation is obtained by replacing every function of a given space by its Taylor coefficients. This allows us to find estimations of Taylor coefficients of holomorphic functions for some functional classes. Examples of such estimations are given in § 6.

Most of the results of this paper were announced in [23] and [24]. Recently some results have been obtained independently by Aizenberg and Mitiagin [1], [2].

The results of § 1, section 3, and § 5 were obtained in collaboration with C. Bessaga and A. Pełczyński.

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§ 1. Preliminaries

1. B_0 -spaces; bases. In the sequel we shall consider only B_0 -spaces, i.e. locally convex complete metric linear spaces. For the basic properties of such spaces see Mazur and Orlicz [18] or Bourbaki's monograph [6], in which they are called F-spaces. Now we recall only that the topology in a B_0 -space X can be given by a non-decreasing sequence of pseudonorms ($\|\cdot\|_a$), $\alpha = 1, 2, ...$

Linear topological spaces X and Y are said to be *isomorphic* (written $X \approx Y$) if and only if there exists a linear homeomorphic mapping from X onto Y. The symbol $X \not\Rightarrow Y$ will denote that the spaces X and Y are not isomorphic.

Let (X_j) be a sequence of B_0 -spaces whose topologies are given by sequences of pseudonorms $(\|\cdot\|_{ij})$, j=1,2,..., respectively. The space $\mathscr X$ whose elements are sequences (x_j) , x_j being in X_j , with the topology determined by the pseudonorms $\|(x_j)\|_a = \sup\{\|x_i\|_{\beta i} \colon i,\beta \leqslant a\}$ will be called a product in sense s of spaces X_j and denoted by the symbol $(X_1 \times X_2 \times ...)_s$.

A series $\sum_{n=1}^{\infty} x_n$ of elements of a B_0 -space X is said to be absolutely convergent if and only if $\sum_{n=1}^{\infty} ||x_n|| < \infty$ for every continuous pseudonorm $\|\cdot\|$ defined on X.

A sequence (e_n) with $e_n \in X$ is called a *basis* (an *absolute basis*) of the space X if and only if every vector x in X may be uniquely represented as the sum of a convergent (absolute convergent) series:

$$x = \sum_{n=1}^{\infty} t_n e_n$$
 (t_n —scalars).

2. Köthe spaces. We shall consider a class of "Stufenräume" introduced by Köthe. Let \mathcal{N}^k denote the set of all systems of k non-negative integers. Suppose we are given a (k+1)-dimensional matrix of num-

bers a_{an} , where $\alpha = 1, 2, ..., n \in \mathcal{N}^k$, such that

(11)
$$a_{a_n} \geqslant 0$$
, $\sup_{\alpha} a_{a_n} > 0$, $a_{a_n} \leqslant a_{\beta_n}$ for $\alpha \leqslant \beta$.

A Köthe space $\mathcal{M}(c_{on})$ is the space of all (k-fold) sequences $\xi=(\xi_n)$ of complex numbers such that

$$\|\xi\|_a = \sup_{\mathbf{n}} a_{a_{\mathbf{n}}} |\xi_{\mathbf{n}}| < \infty \quad (a = 1, 2, \ldots).$$

Addition and multiplication by scalars in this space is defined as usual; the topology is given by pseudonorms $\|\cdot\|_a$.

In the case of k = 1 we shall write n instead of n; spaces $\mathcal{M}(a_{an})$ will be called *single Köthe spaces*.

If $X = \mathcal{M}(a_{a_n})$, we shall say that X has a matrix representation $\mathcal{M}(a_{a_n})$.

THEOREM 1.1 [22]. Let X be a B_0 -space with topology determined by a non-decreasing sequence of pseudonorms ($\|.\|_a$) and with a basis (e_n). Let $a_{an} = \|e_n\|_a$. If

(12) for every a there exists a β such that $\sum_{n=1}^{\infty} a_{an}/a_{\beta n} < \infty$ (here we understand 0/0 = 0),

then $x = \mathcal{M}(a_{an})$.

For the proof see [4].

A B_0 -space X with a basis satisfying condition (12) is said to be nuclear (2).

Remark 1.1. It follows immediately from Theorem 1.1 that if a set of vectors (e_n) can be reordered in such a way as to constitute a basis of X and if for every a there is a β such that $\sum_{n \in J^{-k}} ||e_n||_a/||e_n||_{\beta} < \infty$, then $X \approx \mathcal{M}(||e_n||_a)$.

3. Approximative dimension. Let A, B be subsets of a linear space X. By $M(A, B, \varepsilon)$ we shall denote the maximal number n of such points x_1, \ldots, x_n in A that $x_i - x_j \notin 2\varepsilon B$ for $i \neq j$. M(A, B) will denote the class of all non-negative functions $\varphi(\varepsilon)$ defined for $\varepsilon > 0$ such that for sufficiently small ε

$$\varphi(\varepsilon) \geqslant M(A, B, \varepsilon).$$

Now let us suppose that X is a linear topological space. Let $\mathfrak U$ be the class of all open sets in X and $\mathfrak H$ —the class of all bounded sets in this space. The class of functions:

$$\Phi(X) = \bigcap_{U \in \mathfrak{A}} \bigcap_{B \in \mathfrak{D}} M(B, U)$$

is called the approximative dimension of space X (Kolmogorov [14]).

⁽²⁾ For general definition of nuclear spaces see [11].

Pełczyński's considerations [21] lead to the distinction of another class, namely:

$$\bigcap_{V \in \mathfrak{A}} \bigcup_{U \in \mathfrak{A}} M(U, V).$$

In the case of B₀-spaces both classes are identical [22].

We shall say that the approximative dimension of space X is equal to, less than or equal to, and less than that of Y (written $d_aX = d_aY$, $d_aX \leq d_aY$, $d_aY < d_aY$) if $\Phi(X) = \Phi(Y)$, $\Phi(X) \supset \Phi(Y)$, and $\Phi(X) \supseteq \Phi(Y)$, respectively.

It is easily seen that the approximative dimension is an isomorphic invariant of spaces; moreover if Y is a subspace or a linear (continuous) image of X, then $d_aY \leq d_aX$.

In the case of B_0 -spaces it is more convenient to deal with formula (13): instead of the family $\mathfrak U$ one may take an arbitrary basis (U_n) of neighbourhoods of zero.

Let $X = M(a_{an})$, with $n \in \mathcal{N}^k$, be a nuclear Köthe space and let

$$M_{aeta}(X;\,arepsilon) = \prod_{m{n} arepsilon^{\prime} k} \mathrm{E}ig(1 + a_{am{n}}/(arepsilon a_{m{eta}m{n}})ig)\,(^3)\,.$$

Denote by $M_{\alpha\beta}(X)$ the class of all non-negative functions $\varphi(\varepsilon)$ defined for $\varepsilon > 0$ such that $\varphi(\varepsilon) \geqslant M_{\alpha\beta}(\varepsilon)$ for sufficiently small ε .

THEOREM 1.2. If $X = \mathcal{M}(a_{a,n})$, with $n \in \mathcal{N}^k$, is a nuclear Köthe space, then $\Phi(X) = \bigcap_{a} \bigcup_{\beta} M_{a\beta}(X)$ (4).

THEOREM 1.3 (5). Let matrices $a_{an}^{(j)}$ $(j=1,\ldots,k)$ satisfy condition (12) and let

$$a_{a_{22}}=a_{an_1}^{(1)}\cdot\ldots\cdot a_{an_k}^{(k)}; \hspace{0.5cm} N_{aeta j}(arepsilon)=\overline{\{n:a_{eta n}^{(j)}/a_{an}^{(j)}\geqslantarepsilon\}}\,(^6)\,.$$

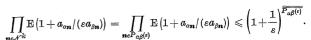
Then

$$\frac{1}{2} \log \frac{1}{\varepsilon} \prod_{j=1}^k N_{\alpha\beta j} (\sqrt[2k]{\varepsilon}) \leqslant \log M_{\alpha\beta} \big(\mathscr{M}(\alpha_{cn}); \, \varepsilon \big) \leqslant \log \Big(1 + \frac{1}{\varepsilon} \Big) \prod_{j=1}^k N_{\alpha\beta j} (\varepsilon).$$

Proof. Write

$$P_{aeta}(arepsilon) = \left\{n \colon a_{an}^{(1)}/a_{eta n}^{(1)} \geqslant rac{1}{arepsilon}
ight\} imes \ldots imes \left\{n \colon a_{an}^{(k)}/a_{eta n}^{(k)} \geqslant rac{1}{arepsilon}
ight\}.$$

Right-hand inequality. We have



Since $\overline{P_{a\beta}(arepsilon)}=\prod_{i=1}^k N_{a\beta i}(arepsilon),$ we obtain the required inequality.

Left-hand inequality. Since $\mathrm{E}\left(1+a_{nn}/(\varepsilon a_{\beta n})\right)\geqslant 1/\sqrt{\varepsilon}$ for $n\epsilon P_{\alpha\beta}\stackrel{2k}{(\sqrt[2k]{\varepsilon})}$, we have

$$\prod_{\boldsymbol{n} \in \mathcal{N}^k} \mathrm{E} \left(1 + a_{\alpha_{\boldsymbol{n}}} / (\varepsilon a_{\beta_{\boldsymbol{n}}}) \right) \geqslant \prod_{\boldsymbol{n} \in \mathcal{P}_{\alpha\beta} \left(\frac{2k}{\sqrt{\varepsilon}} \right)} \mathrm{E} \left(1 + a_{\alpha_{\boldsymbol{n}}} / (\varepsilon a_{\beta_{\boldsymbol{n}}}) \right) \geqslant (1/\sqrt{\varepsilon})^{\frac{2k}{P_{\alpha\beta} \left(\frac{2k}{\sqrt{\varepsilon}} \right)}}.$$

THEOREM 1.4. Let matrices (a_{op}) , (b_{oq}) satisfy condition (12), where $\mathbf{p} = (n_1, \dots, n_r) \in \mathcal{N}^r$, $\mathbf{q} = (n_{r+1}, \dots, n_k) \in \mathcal{N}^{k-r}$, and let $e_{on} = a_{op} \cdot b_{oq}$, where $\mathbf{n} = (n_1, \dots, n_k) \in \mathcal{N}^k$. Then

THEOREM 1.5. Let X_n be a sequence of B_0 -spaces. If $d_a(X_i \times X_j) = d_a X_1$, then $d_a(X_1 \times X_2 \times \ldots)_s = d_a X_1$. In particular, if $d_a X = d_a(X \times X)$, then $d_a X = d_a(X \overline{\otimes} s)$. (Symbol $X \times Y$ denotes the Cartesian product of spaces X and Y).

4. Spaces $\mathscr{H}_{\mu}(D)$. Let D be a domain in a k-dimensional Euclidean complex space. Let $\mu(\varepsilon,z)$ be a non-negative function defined for $0<\varepsilon<1$, $z\in D$, non-increasing with respect to ε and such that $\lim_{\varepsilon\to 0}\mu(\varepsilon,z)>0$, for every z in D. By $\mathscr{H}_{\mu}(D)$ we shall denote the space of all holomorphic functions x=x(z) defined on D and such that

(14)
$$||x||_{\varepsilon} = \sup_{z \in D} |x(z)| \, \mu(\varepsilon, z) < + \infty$$

with the topology induced by the pseudonorms $\|\cdot\|_{\epsilon}.$

Since $\mu(\varepsilon, z)$ is non-increasing with respect to ε , the topology of the space $\mathscr{H}_{\mu}(D)$ may be given by the sequence of pseudonorms $\|.\|_{1/n}$. Hence $\mathscr{H}_{\mu}(D)$ is a B_0 -space.

If A_{ε} $(0<\varepsilon<1)$ is a non-increasing family of compact sets such that $\bigcup_{\varepsilon} A_{\varepsilon} = D$ and $\mu(\varepsilon,z) = \chi_A(z)$ (the characteristic function of the set A), then $\mathscr{H}_{\mu}(D)$ is the space of all holomorphic functions defined on D with the topology of almost uniform convergence. This space will be briefly denoted by $\mathscr{H}(D)$.

If D is the whole k-dimensional Euclidean complex space, then instead of $\mathscr{H}_{\mu}(D)$ we shall write \mathscr{H}_{μ} .

The symbols C and C_0 will be reserved further for denoting the whole complex plane and the interior of the unit circle; \overline{C} will denote

⁽³⁾ Ea denotes the greatest integer in a.

⁽⁴⁾ Proofs of theorems 1.2, 1.4, and 1.5 will be published in Studia Math. in a joint paper with C. Bessaga and A. Pełczyński.

⁽⁵⁾ cf. Mitiagin [19], theorem 1.

⁽⁸⁾ The symbol $\bar{\bar{A}}$ denotes the cardinality (number of elements) of the set A.

the extended complex plane, i. e. $\overline{C} = C + \{\infty\}$. C^r (resp. C_0^r) will denote the Cartesian product of r copies of C (resp. C_0).

THEOREM 1.6. Suppose we are given a space $\mathscr{H}_{\mu} = \mathscr{H}_{\mu}(C^k)$ such that the function $\mu(\varepsilon,z)$ depends only on $|z_1|,\ldots,|z_k|$, and let $z^n=z_1^{n_1}\ldots z_k^{n_k}$, for $n \in \mathscr{N}^k$. If for every $0 < \varepsilon < 1$ there exists an ε' such that

then the mononomials z^n constitute a basis of \mathscr{H}_{μ} . The space \mathscr{H}_{μ} has a matrix representation $M(|z^n|_{\varepsilon_a})$, where (ε_a) is an arbitrary sequence such that $0 < \varepsilon_a < 1$, lim $\varepsilon_a = 0$.

Proof. Every entire function, in particular every function from \mathscr{H}_{μ} , can be uniquely represented as the sum of the series

$$x(z) = \sum_{n \in \mathcal{N}^k} c_n z^n,$$

which is absolutely and almost uniformly convergent ([10], p. 74). By Cauchy formula ([10], p. 24) we obtain $|c_{n-1}| \leq (1/r^n) \max |x(z)|$,

where $r^n = r_1^{n_1} \dots r_k^{n_k}$, for every n in \mathcal{N}^k . Therefore

$$|c_{n-1}z^n| \leq \max\{|x(\xi)| : \xi = (\xi_1, ..., \xi_k), |\xi_i| = |z_i|\}.$$

Hence

$$\mu(\varepsilon, z) |c_{n-1} z^n| \leqslant \mu(\varepsilon, z) \max_{|\xi_i| = |z_i|} |x(\xi_i)|.$$

Now, the assumption that $\mu(\varepsilon,z)$ depends on $|z_1|,\ldots,|z_k|$ gives us

$$||c_{n-1}z^n||_{\varepsilon} \leqslant ||x||_{\varepsilon}$$
 for every $n \in \mathcal{N}^k$.

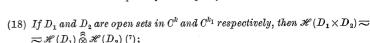
From this inequality we deduce by (15) that the series (16) is convergent in the topology of the space \mathscr{H}_{μ} . Since, by (14), convergence in \mathscr{H}_{μ} implies uniform convergence, expansion (16) is unique also in the topology of \mathscr{H}_{μ} , i. e. (z^n) is a basis of \mathscr{H}_{μ} .

The matrix representation of \mathscr{H}_{μ} follows from formula (15) and Theorem 1.1.

5. Tensor products. Let X and Y be B_0 -spaces, X^* and Y^* —their conjugate spaces. The space of all bilinear forms defined on the Cartesian product $X^* \times Y^*$ is called the *tensor product* of spaces X and Y (written $X \otimes Y$) [11].

Further we shall make use of the following three facts concerning tensor products:

(17) If $X_1 = X$, $Y_1 = Y$, then $X \, \hat{\otimes} \, Y = X_1 \, \hat{\otimes} \, Y_1$, $X \, \hat{\otimes} \, (Y \times Z) = (X \, \hat{\otimes} \, Y) \times (X \, \hat{\otimes} \, Z)$:



(19) If $X = M(a_{ap})$, $Y = M(b_{aq})$, with $\mathbf{p} = (n_1, \dots, n_r) \in \mathcal{N}^r$, $\mathbf{q} = (n_{r+1}, \dots, n_k) \in \mathcal{N}^{k-r}$, are nuclear Köthe spaces and $c_{an} = a_{ap} b_{aq}$ for $\mathbf{n} = (\mathbf{p}, \mathbf{q}) = (n_1, \dots, n_k) \in \mathcal{N}^k$, then $X \otimes Y = \mathcal{M}(c_{an})$.

§ 2. Some isomorphic relations between spaces $\mathcal{H}(D)$

LEMMA 2.1. Suppose we are given an analytic transformation of an open plane set D_1 onto an open plane set D_2 . Then the space $\mathscr{H}(D_2)$ is isomorphic to a subspace of $\mathscr{H}(D_1)$.

Proof. Let

$$(Tx)(z) = x(\varphi(z)).$$

We shall show that T is an isomorphism mapping of $\mathscr{H}(D_2)$ into $\mathscr{H}(D_1)$. Obviously T is a linear one-to-one mapping. To show that it is continuous let us choose $y_n \in T(\mathscr{H}(D_2))$ $(n=1,2,\ldots)$ such that $y_n \to 0$. Let $x_n = Ty_n$ $(n=1,2,\ldots)$. Suppose that $x_n \not\to 0$. Then there is a compact set $K_2 \subset D_2$ such that $\overline{\lim_n \|x_n\|_{K_2}} = \overline{\lim_n \sup_{y \in K_3} \|x_n(y)\|} > 0$.

Since for every compact $K_2 \subset D_2$ there is a compact set $K_1 \subset D_1$ such that $\Phi(K_1) \supset K_2$, we have $\overline{\lim} \ \|y_n\|_{K_1} \geqslant \overline{\lim} \sup_{w \in \Phi^{-1}(K_1)} |x_n(w)| \geqslant \overline{\lim} \ \|x_n\|_{K_2} > 0$, which leads to a contradiction.

LEMMA 2.2. Let D be an arbitrary k-dimensional domain. Then the space $\mathcal{H}(C \times D)$ (resp. the space $\mathcal{H}(C_0 \times D)$) is isomorphic to its cartesian square.

Proof. First we note that the space $\mathcal{H}(C)$ is isomorphic to its Cartesian square. Let us put $hx = (x_1, x_2)$, where

$$x_1(z) = \frac{x(z) + x(-z)}{2}, \quad x_2(z) = \frac{x(z) - x(-z)}{2z},$$

for any $x \in \mathcal{H}(C)$. It is easily seen that h is the required isomorphism. In the general case, according to (17) and (18), we have

$$\begin{split} \mathscr{H}(C \times D) &\eqsim \mathscr{H}(C) \otimes \mathscr{H}(D) = \big(\mathscr{H}(C) \times \mathscr{H}(C) \big) \otimes \mathscr{H}(D) \\ &\eqsim \big(\mathscr{H}(C) \otimes \mathscr{H}(D) \big) \times \mathscr{H}(C) \otimes \mathscr{H}(D) \eqsim \mathscr{H}(C \otimes D) \times \mathscr{H}(C \otimes D). \end{split}$$

The proof for the space $\mathcal{H}(C_0 \times D)$ is analogous.

⁽⁷⁾ This formula follows from the fact that every function x(z) in $\mathscr{H}(D_1 \times D_2)$ can be almost uniformly approximated by sums of functions of form $x_1(z_1) \cdot x_2(z_2)$ with $z_1 \in D_1$, $z_2 \in D_2$ and from the example 1 in [11], p. 89-90.

THEOREM 2.1. Let D be a finite connected domain in C. Let Z_1, Z_2, \ldots, Z_m be components of the complement of D. Then

1° $\mathcal{H}(D) \approx \mathcal{H}(C)$ if all Z_i are points,

 $2^{\circ} \mathcal{H}(D) \approx \mathcal{H}(C_0)$ if all Z_i are continua,

3° $\mathscr{H}(D) \approx \mathscr{H}(C_0) \times \mathscr{H}(C)$ if among Z_i there are points and continua.

Proof. For m=1 our assertion is obvious. Let us suppose that it is true for an l-conected domain. Let D be an m-conected domain. According to Riemann theorem on conform mappings we may suppose that the component Z_m of the complement of D is (α) either the point set $\{\infty\}$ or (β) the set $\{z:|z|\geqslant 1\}$. Then in both cases there is a positive number r such that

$$x(z) = \sum_{n=0}^{\infty} a_n z^n + \sum_{n=1}^{\infty} b_n z^{-n}$$
 for $x \in \mathscr{H}(D)$

and for |z| > r in the case (α) (1-1/r < |z| < 1 in the case (β)). It is easy to see that the correspondence $x \leftrightarrow (x_1, x_2)$, where

$$x_1(z) = \sum_{n=0}^{\infty} a_n z^n, \quad x_2(z) = \sum_{n=1}^{\infty} a_n z^{n-1},$$

is an isomorphism between $\mathscr{H}(D)$ and $\mathscr{H}(C)\times\mathscr{H}(D\cup Z_m)$ (between $\mathscr{H}(D)$ and $\mathscr{H}(C_0)\times\mathscr{H}(D\cup Z_m)$.

Since the domain $D \cup Z_m$ is m-1 connected, by the induction hypothesis and lemma 2.2 we obtain the assertion of our theorem, q. e. d.

CONJECTURE. If D is an arbitrary finite connected domain in C, then $\mathcal{H}(D)$ is one of the standard forms: $\mathcal{H}(C)$, $\mathcal{H}(C_0)$, $\mathcal{H}(C \times C_0)$.

THEOREM 2.2. Let D_1, \ldots, D_k be a family of finite connected plane domains. Suppose that all components of each of the spaces $C-D_i$ are points for $i=1,\ldots,r$, continua for $i=r+1,\ldots,r+p$, points and continua for $i=r+p+1,\ldots,k$, where $1\leqslant r\leqslant r+p\leqslant k$. Then $\mathscr{H}(D_1\times\ldots\times D_k)$ is isomorphic to the space

$$\mathscr{H}(C^r \times C_0^{k-r}) \times \mathscr{H}(C^{r+1} \times C_0^{k-r-1}) \times \ldots \times \mathscr{H}(C^{k-p} \times C_0^p)$$
.

This follows immediately from theorem 2.1 and formulas (17) and (18).

Let Ω be an algebra with two operations, + and \cdot , and one relation of "equality", defined by the following axioms:

I. Ω has two generators u, v (in other words, elements of Ω are sums of mononomials u^pv^q with p, q > 0, p+q > 0, where $u^p = u \dots u$, $v^q = v \dots v$).

II. $\omega_1 + \omega_2 = \omega_2 + \omega_1$, $\omega_1 \cdot \omega_2 = \omega_2 \cdot \omega_1$, $\omega_1 + (\omega_2 + \omega_3) = (\omega_1 + \omega_2) + \omega_3$, $\omega_1 \cdot (\omega_2 \cdot \omega_3) = (\omega_1 \cdot \omega_2) \cdot \omega_3$, $\omega_1 \cdot (\omega_2 + \omega_3) = \omega_1 \cdot \omega_2 + \omega_1 \cdot \omega_3$.

III. If $p' \leqslant p$, $q' \leqslant q$, then $u^p v^q + u^{p'} v^{q'} = u^p v^q$.

Let $\omega = u^{p_1}v^{q_1} + \ldots + u^{p_n}v^{q_n}$. Denote by $\omega(X, Y)$ the space constructed from the ω by substitution $\begin{pmatrix} \vdots & u & v \\ \times & \mathscr{R}(C) & \mathscr{H}(C_0) \end{pmatrix}$.

From theorems 2.1, 3.1 and formulas (17) and (18) follows

Theorem 2.3. If $\omega_1 = \omega_2$, then $\omega_1(X, Y) = \omega_2(X, Y)$.

Problem 2.1. Does the relation $\omega_1(X, Y) = \omega_2(X, Y)$ imply $\omega_1 = \omega_2$?

Using theorems 2.1, 4.1, results of § 5, and formulas (17), (18) and (19) we obtain the following statements:

1º if degree $\omega_1 \neq$ degree ω_2 , then $\omega_1(X, Y) \neq \omega_2(X, Y)$;

2º if ω_1 depends on one variable u, ω_2 depends on v, and ω_3 is not equal to any element of Ω depending only on one variable, then the spaces $\omega_1(X, Y)$, $\omega_2(X, Y)$, $\omega_3(X, Y)$ are not isomorphic. In particular $\mathscr{H}(C)$, $\mathscr{H}(C_0 \times C)$ and $\mathscr{H}(C_0)$ are not isomorphic.

THEOREM 2.4. Let $D=D_1\times D_2\times \ldots \times D_k$ be an arbitrary polycylinder. Then $\mathscr{H}(D)$ is isomorphic to a subspace of $\mathscr{H}(C_0^k)$.

Proof. According to (17) and (18) it is sufficient to restrict our attention to the ease where D is one-dimensional. By theorem 2.1 we may assume without loss of generality that $\overline{C}-D$ contains at least three points, for instance $\{0\}$, $\{1\}$, $\{\infty\}$. Now by a result of Poincaré ([13], p. 275) there is an analytic function φ which transforms D onto C_0 . To complete the proof we apply lemma 2.2.

THEOREM 2.5. Let $D = D_1 \times D_2 \times ... \times D_k$ be a bounded polycylinder. Then $\mathscr{H}(D)$ contains a subspace isomorphic to $\mathscr{H}(C_k^b)$.

Proof. As in the proof of Theorem 2.4, it is enough to restrict our attention to the one-dimension case. D^* denotes the complement of the unbounded component of the complement of D. Let $r: \mathscr{H}(D^*) \to \mathscr{H}(D)$ be the restriction of functions in $\mathscr{H}(D^*)$ to functions in $\mathscr{H}(D)$, i. e. rx(z) = x(z) for $z \in D$ and $x \in \mathscr{H}(D^*)$. Obviously r is a linear one-to-one operator and according to the maximum principle r^{-1} is continuous. Hence $\mathscr{H}(D^*)$ is isomorphic to a subspace of $\mathscr{H}(D)$. Since D^* , is a bounded domain, $\mathscr{H}(D^*)$ is isomorphic to $\mathscr{H}(C_0)$, q. e. d.

From theorems 2.4 and 2.5 we obtain

COROLLARY 2.1. If $D = D_1 \times ... \times D_k$ is a bounded polycylinder, then the spaces $\mathscr{H}(D)$ and $\mathscr{H}(C_0^k)$ have the same linear dimension in the sense of Banach ([3], p. 193).

THEOREM 2.6. Let D_0 be an arbitrary k-dimensional bounded domain. Then, for every k-dimensional domain D, $\mathcal{H}(D)$ is isomorphic to a subspace of the space $(\mathcal{H}(D) \times \mathcal{H}(D) \times \dots)_s$.

Proof. There exist points $\boldsymbol{z}^{(n)}$ in \boldsymbol{C}^k and positive numbers \boldsymbol{s}_n such that

$$D = igcup_{n=1}^{\infty} D_n, \quad ext{where} \quad D_n = \Big\{ z \, \epsilon \, C^k \colon rac{z-z^{(n)}}{s^{(n)}} \, \epsilon \, D_0 \Big\}.$$

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Obviously all the spaces $\mathscr{H}(D_n)$ are isomorphic to $\mathscr{H}(D)$. Let h_n denote an isomorphism from $\mathscr{H}(D_n)$ onto $\mathscr{H}(D_0)$ and let $r_n:\mathscr{H}(D)\to \mathscr{H}(D_n)$ be the operation of restriction of functions in $\mathscr{H}(D)$ to functions in $\mathscr{H}(D_n)$. Let us put $hx=(h_nr_nx)$ for $x\in\mathscr{H}(D)$. We omit the asy checking that h is the required isomorphism.

COROLLARY 2.2. Let D be an arbitrary k-dimensional domain; then $\mathscr{H}(D)$ is isomorphic to a subspace of the space $(\mathscr{H}(C_0^k) \times \mathscr{H}(C_0) \times \ldots)_s$.

§ 3. Matrix representations of spaces $\mathcal{H}_{\mu}(D)$

1. Matrix form $\mathscr{M}\left(\exp\left(\alpha(n_1^{q_1}+\ldots+n_r^{q_r})-\frac{1}{\alpha}\left(n_{r+1}^{q_r+1}+\ldots+n_k^{q_k})\right)\right)$. Now we prove

THEOREM 3.1. We have

$$\mathscr{H}(C^r \times C_0^{k-r}) \approx \mathscr{M}\left(\exp\left(\alpha(n_1+\ldots+n_r)-\frac{1}{\alpha}(n_{r+1}+\ldots+n_k)\right)\right).$$

Proof. The sequence $z^n = z_1^{n_1} \dots z_k^{n_k}$ constitutes a basis of the space $\mathscr{H}(C^r \times C_0^{k-r})$ ([10], p. 74). We assume as pseudonorms

$$||x||_a = \sup\{|x(z)| : |z_1|, \ldots, |z_r| \leqslant e^a; |z_{r+1}|, \ldots, |z_k| \leqslant e^{-1/a}\}.$$

Since $\sum_{n_e \neq r^k} \|z^n\|_a / \|z^n\|_{a+1} < \infty$, by Theorem 1.1 we have $\mathscr{H}(C^r \times C_0^{k-r})$ $\approx \mathscr{M}(\|z^n\|_a)$. But $\|z^n\|_a = \exp\left(\alpha(n_1 + \ldots + n_r) - \frac{1}{2}(n_{r+1} + \ldots + n_k)\right)$, q. e. d.

Now we shall establish single matrix representations of the spaces $\mathscr{H}(\mathcal{C}^k)$ and $\mathscr{H}(\mathcal{C}^k_0)$. We shall use the following

LEMMA 3.1. Let $\begin{bmatrix} j \\ k \end{bmatrix}$ denote the number of all mononomials of degree j of k variables. Then $j^k/k! \leqslant \begin{bmatrix} j \\ k \end{bmatrix} \leqslant (j+1)^k$.

Proof. It is easy to see that

Let $f_k(t) = \begin{bmatrix} \operatorname{E} t \\ k \end{bmatrix}$. By (31) we have $\int_0^{n+1} f_{k-1}(t) dt = f_k(n)$; therefore $\int_0^t f_{k-1}(\tau) d\tau \leqslant f_k(t)$. Hence, by induction, we obtain $f_{k+1}(t) \geqslant t^k/k!$; in particular $\begin{bmatrix} j \\ k+1 \end{bmatrix} \geqslant j^k/k!$.

On the other hand, from (31) it follows that $\begin{bmatrix} j \\ k \end{bmatrix} \leqslant (j+1) \begin{bmatrix} j \\ k-1 \end{bmatrix}$, and by induction $\begin{bmatrix} j \\ k \end{bmatrix} \leqslant (j+1)^{k-1}$, q. e. d.

Proof. Let $p(n) = (p_1(n), \ldots, p_k(n))$ be an arbitrary one-to-one function from \mathcal{N}^1 onto \mathcal{N}^k such that $|p(n)| \leq |p(n')|$ for $n \leq n'$, where $|p(n)| = p_1(n) + \ldots + p_k(n)$. Write $e_n = z_1^{p_1(n)} \ldots z_k^{p_k(n)}$. By Lemma 3.1, there are positive constants A and B such that

$$\exp aA \stackrel{k}{V}_n^- \leqslant \|e_n\|_a \leqslant \exp aB \stackrel{k}{V}_n^- \quad ext{for} \quad \mathscr{H}(C^k),$$

$$\exp\left(-A\sqrt[k]{n}/a\right) \leqslant \|e_n\|_a \leqslant \exp\left(-B\sqrt[k]{n}/a\right) \quad \text{for} \quad \mathscr{H}(C_0^k).$$

Thus the formula $T(c_n) = \sum_{n \in \mathcal{N}^1} c_n z^{p(n)}$ gives the required isomorphic

mappings from $\mathcal{M}(\exp \alpha^k \sqrt[k]{n})$ onto $\mathcal{H}(C^k)$ and from $\mathcal{M}(\exp(-\sqrt[k]{n}/\alpha))$ onto $\mathcal{H}(C^k_0)$, q. e. d.

The next two theorems will concern matrix representations of spaces of holomorphic functions defined on circular or p_1, \ldots, p_k -circular ([10], p. 113 and 117) domains D. For simplicity we shall formulate these theorems for the case where the centre of D coincides with $(0, \ldots, 0)$.

Theorem 3.2. Let D be a bounded domain in C^k such that

(32)
$$\overline{aD} \subset D$$
 for every $|a| < 1$ (8).

Then $\mathscr{H}(D) \approx \mathscr{M}(\exp(-\sqrt[k]{n}/a))$.

Proof. Let $D_s = (1-\varepsilon)D$. We introduce scalar products

$$(x,y)_{\varepsilon}=\int\limits_{D}x(z_1,\ldots,z_k)\overline{y(z_1,\ldots,z_k)}\ dx_1\ldots dx_kdy_1\ldots dy_k,$$

where $z_j = x_j + iy_j$ for j = 1, ..., k, and the integral is taken over the domain D in a 2k-dimensional real Euclidean space ([10], p. 119).

The pseudonorms $\|x\|_{\epsilon} = 1/(\overline{x,x})_{\epsilon}$ $(0 < \epsilon < 1)$ give a topology equivalent to the almost uniform convergence, because

$$\|D_{arepsilon}\|^{-1}\|x\|_{arepsilon}\leqslant \sup_{z \in D_{arepsilon}}\|x(z)\| \leqslant \pi^{-1}r_{arepsilon arepsilon'}^{-k}|x|_{arepsilon'},$$

where $|D_{\epsilon}|$ is the volume of D_{ϵ} and $T_{\epsilon\epsilon'}$, is the distance between the set D_{ϵ} and the complement of $D_{\epsilon'}$ ([10], p. 120).

For the scalar product $(x, y)_0$ we can construct an orthonormal basis (e_n) constituted from homogeneous polynomials ([10], p. 132). The number of elements of the basis which are polynomials of degree j is equal to $\begin{bmatrix} j \\ k \end{bmatrix}$. Since e_n are homogeneous polynomials, we have $(e_r, e_s)_e = 0$ for $r \neq s$, $(e_r, e_r)_e = (1 - \varepsilon)^j ||e_r||_0$, where j is the degree of the polynomial e_r . Let $\varepsilon_a = 1 - \exp(-1/a)$. Then $||e_n||_{e_a} = ||e_n||_0 \exp(-j/a)$,

⁽⁸⁾ A denotes the closure of the set A.

where i is the degree of the polynomial e_n . Now, applying Theorem 1.1 and Lemma 3.1, we obtain $\mathcal{H}(D) \approx \mathcal{M}(\exp(-\sqrt[k]{n+k/a}))$. But this space is trivially isomorphic to the space $\mathcal{M}(\exp(-\sqrt[k]{n}/a))$, q. e. d.

THEOREM 3.3. Let D be a bounded domain in C^k such that (33) there are positive integers p_1, \ldots, p_k such that for every real t

$$\{(z_1 \exp i p_1 t, \dots, z_k \exp i p_k t) \colon (z_1, \dots, z_k) \in D\} \subset D,$$

$$(34) \qquad \qquad \overline{tD} \subset D \text{ for each } 0 < t < 1.$$

Then $\mathcal{H}(D) \approx \mathcal{M}(\exp(-\sqrt[k]{n}/a))$.

Proof. Let $\Phi(z) = (z_1^{p_1}, \ldots, z_k^{p_k})$. It follows from (33) and (34) that the domain $D^* = \Phi^{-1}(D)$ fulfills condition (32). Let us assign to any function $x(z) \in \mathcal{H}(D)$ the function $(Ux)(z) = x(\Phi(z))$ with $z \in D^*$. It is easy to verify that U is an isomorphic mapping from $\mathcal{H}(D)$ onto a subspace X of the space $\mathcal{H}(D^*)$.

In the same way as in the proof of Theorem 3.2 we can construct a basis of X chosen from the homogeneous polynomials. The elements of this basis are sums of mononomials $z_1^{n_1} \dots z_n^{n_k}$ such that n_i is divisible by p_i for i = 1, 2, ..., k. Let τ_i denote the number of such mononomials of degree not greater than j. As in Lemma 3.1 we can prove that there are positive constants A and B such that $Aj^k \leq s_i \leq Bj^k$. From this inequality follows the assertion of the theorem.

Theorem 3.4. Let $\mu(\varepsilon,z) = \exp\left(-\sum_{i=1}^{n} (\tau_i + \varepsilon) |z_j|^{p_j}\right), \quad \tau_1,\ldots,\tau_r = 0$, $\tau_{r+1}, \ldots, \tau_k > 0, \ p_j > 0; \ then \ \mathscr{H}_u \approx \mathscr{M} \left(\exp(\alpha(n_1 + \ldots + n_r) - \frac{1}{r_r} (n_{r+1} + \ldots + n_r) \right)$ $+\ldots+n_k))$.

The isomorphic mapping from \mathscr{H}_{μ} onto $\mathscr{M}(\exp(a(n_1+\ldots+n_r) \frac{1}{n}(n_{r+1}+\ldots+n_k))$ is of the form

(35)
$$T \sum_{n_0 \cdot \ell'^k} c_n z^n = (d_n c_n), \text{ where } d_n = \left(\prod_{j=1}^k (n_j/p_j)^{n_j/p_j} \right) \exp\left(- \sum_{j=1}^k n_j/p_j \right).$$

Proof. We have

$$\begin{split} \|z^{\mathbf{n}}\|_{\varepsilon} &= \max_{z_{\varepsilon}C^n} |z^{\mathbf{n}}| \exp\left(-\sum_{j=1}^k (\tau_j + \varepsilon) |z_j|^{p_j}\right) \\ &= \max_{t_j > 0} \exp\left(\sum_{j=1}^k n_j \log t_j - \sum_{j=1}^k (\tau_j + \varepsilon) t_j^{p_j}\right). \end{split}$$
 Let
$$f(t_1, \ldots, t_k) &= \sum_{j=1}^k n_j t_j - \sum_{j=1}^k (\tau_j + \varepsilon) t_j^{p_j}.$$



Solving the equations $\partial f/\partial t_i=0$ we find that the function f has its maximum for $t_i = \sqrt[p_j]{n_i/(p_j(\tau_j + \varepsilon))}, j = 1, ..., k$, whence

$$\|z^{\mathbf{n}}\|_{\epsilon} = \left(\prod_{j=1}^{k} \left(\frac{n_{j}/p_{j}}{\tau_{j} + \epsilon}\right)^{n_{j}/p_{j}}\right) \exp\left(-\sum_{j=1}^{k} n_{j}/p_{j}\right).$$

Thus the formula $U\sum\limits_{n\in\mathbb{Z}^k}c_nz^n=(c_n)$ gives an isomorphic mapping from \mathscr{H}_{μ} onto $\mathscr{M}\left(d_n \exp\left(\alpha(n_1+\ldots+n_r)-\frac{1}{\alpha}(n_{r+1}+\ldots+n_k)\right)\right)$, where d_n are given by formula (35). This is equivalent to the assertion of the theorem.

Theorem 3.5. Let $\mu(\varepsilon, z) = \exp\left(-\sum_{z=1}^{n} (\tau_i + \varepsilon) \left|\log|z|_j\right|^{p_j}\right)$, where $p_j > 1$, $\tau_1, \ldots, \tau_r = 0, \ \tau_{r+1}, \ldots, \tau_k > 0, \ \text{and let} \ q_i = p_i / (p_i - 1), \ j = 1, \ldots, k.$ Then $\mathscr{H}_{\mu} \approx \mathscr{M}\left(\exp\left(\alpha\left(n_1^{q_1} + \ldots + n_r^{q_r}\right) - \frac{1}{\sigma}\left(n_{r+1}^{q_{r+1}} + \ldots + n_k^{q_k}\right)\right)\right).$

Proof. In the same way as in the preceding proof we obtain

$$|z^n|_{arepsilon} = \prod_{j=1}^{i} A_{arepsilon_j}^{n_{qj}}, \quad ext{ where } \quad A_{arepsilon_j} = \exp\left(\left(rac{1}{(au_j + arepsilon)p_j}
ight)^{q_j}q_j^{-1}
ight).$$

If $au_j=0$, then $\lim_{\epsilon \to 0} A_{\epsilon j}=\infty;$ if $au_j>0$, then $\lim_{\epsilon \to 0} A_{\epsilon j}=A_j.$ From Theorem 1.6 it follows that $\mathscr{H}_{\nu} \approx \mathscr{M}(|z^{n}|_{\epsilon_{n}})$, where (ε_{n}) is an arbitrary sequence tending to zero. The transformation

$$U(\xi_{m n}) = (d_{m n} \xi_{m n}), \quad ext{where} \quad \dot{d}_{m n} = \prod_{j=r+1}^k A_j^{n_j^{q_j}} \quad ext{ for } \quad {m n} \, \epsilon \mathcal{N}^k,$$

maps this space onto the space given in the assertion of Theorem 3.5.

Remark 3.1. The space \mathcal{H}_u considered in Theorem 3.5 is isomorphic to the space $F_{p\tau}^k$ of all holomorphic functions x(z) which are periodic with the period 2π with respect to every variable and such that

$$||x||_{\varepsilon} = \sup |x(z)| \exp \left(-\sum_{j=1}^{k} (\tau_j + \varepsilon) |\operatorname{Im} z_j|^{p_j}\right) < \infty.$$

The isomorphic mapping from \mathcal{H}_{μ} onto $F_{p\tau}^k$ is given by the formula $(Ux)(z) = x(\exp iz_1, \ldots, \exp iz_k).$

THEOREM 3.6. Let

$$\mu(\varepsilon,z) = \exp\left(-\varepsilon \sum_{j=1}^k \left(\log \frac{1}{|z_j|}\right)^{-s_j}\right), \quad s_j > 0.$$

Then

$$\mathscr{H}_{\mu}(C_0^k) \eqsim \mathscr{M}\left(\exp\left(-\frac{1}{a}\sum_{j=1}^k n_j^{q_j}\right)\right), \quad \textit{where} \quad q_j = s_j/(1+s_j).$$

This isomorphism is realized by the transformation $T\left(\sum_{\mathbf{n}\in\mathcal{N}^k}c_{\mathbf{n}}z^{\mathbf{n}}\right)=(c_{\mathbf{n}}).$

Proof. We have

$$||z^n||_{\varepsilon} = \exp\left(-\sum_{j=1}^k \left(\frac{n_j}{\varepsilon s_j}\right)^{-1/(s_j+1)} (n_j+\varepsilon)\right).$$

Hence if |n| is sufficiently large, then

$$\exp\left(-2\max_{x}(\varepsilon s_{j})^{-1/s_{j}+1}\sum_{j=1}^{k}n_{j}^{q_{j}}\leqslant \|z^{n}\|_{\varepsilon}\leqslant \exp\left(-\frac{1}{2}\min_{j}(\varepsilon_{j}s)^{-1/s_{j}+1}\sum_{j=1}^{k}n_{j}^{q_{j}}\right).$$

This inequality gives us the assertion of the theorem (9).

Remark 3.2. Let $\mu(\varepsilon,z)$ be the function defined in Theorem 3.6 and let $\mu_1(\varepsilon,z) = \exp\left(-\varepsilon \sum\limits_{j=1}^k (1-|z_j|)^{-s_j}\right)$. Then $\mathscr{H}_{\mu} = \mathscr{H}_{\mu_1}$.

This follows immediately from the fact that

$$\lim_{t\to 1-}\frac{1/(1-t)}{1/\log(1/t)}=1.$$

2. Matrix form $\mathscr{M}((n_1^{n_1} \dots n_r^{n_r})^a \cdot (n_{r+1}^{n_{r+1}} \dots n_k^{n_k})^{-1/a})$. Now we prove Theorem 3.7. Let $\mu(\varepsilon, z) = \exp\left(-\sum_{j=1}^{n} |z_j|^{p_j+\varepsilon}\right)$, where $p_1, \dots, p_r = 0$, $p_{r+1}, \dots, p_k > 0$. Then $\mathscr{H}_{\mu} \approx \mathscr{M}((n_1^{n_1} \dots n_r^{n_r})^a \cdot (n_{r+1}^{n_{r+1}} \dots n_k^{n_k})^{-1/a})$.

$$\|z^n\|_{\epsilon} = \prod_{j=1}^k n_j^{n_j/(p_j+\epsilon)} (p_j+\varepsilon)^{-n_j/(p_j+\epsilon)} \cdot \exp\left(-n_j/(p_j+\varepsilon)\right).$$

Hence for arbitrary $\eta > 0$

$$\prod_{j=1}^k n_j^{n_j/(p_j+\epsilon+\eta)} \leqslant \|z^n\|_\epsilon \leqslant \prod_{j=1}^k n_j^{n_j/(p_j+\epsilon-\eta)}$$

for sufficiently large |n|. Therefore $\mathscr{H}_{\mu} \approx \mathscr{M}(\prod_{j=1}^k n_j^{n_j/(p_j+1/a)})$, by Theo-

rem 1.6. But this space may be isomorphically mapped onto the space given in the assertion of the theorem by the transformation

$$T(c_n) = (d_n c_n), \quad ext{where} \quad d_n = \prod_{j=r+1}^k n_j^{n_j/p_j}.$$

3. Matrix form $\mathscr{M}(\exp(n_1^a + \ldots + n_r^a + n_{r+1}^{q_r+1^{-1/a}} + \ldots + n_k^{q_{k-1/a}}))$. Now we prove.

THEOREM 3.8. Let $\mu(\varepsilon, z) = \exp\left(-\sum_{j=1}^k \log|z_j|^{p_j+\varepsilon}\right)$, where $p_1, \dots, p_r = 1$, $p_{r+1}, \dots, p_k > 1$. Then $\mathscr{H}_{\mu} \approx \mathscr{M}\left(\exp\left(n_1^a + \dots + n_r^a + n_{r+1}^{q_r+1-1/a} + \dots + n_k^{q_k-1/a}\right)\right)$, $q_j = p_j/(p_j - 1)$

Proof. We have

$$\|z^{m{n}}\|_{arepsilon} = \prod_{j=1}^k \expig((n_j/(p_j+arepsilon))^{(p_j+arepsilon)/(p_j+arepsilon-1)} \cdot (p_j+arepsilon-1)/(p_j+arepsilon)ig).$$

Hence, for every $\eta > 0$,

$$\prod_{j=1}^k \exp n_j^{(p_j+\epsilon-\eta)/(p_j+\epsilon-\eta-1)} \leqslant \|z^{\mathbf{n}}\|_{\epsilon} \leqslant \exp n_j^{(p_j+\epsilon+\eta)/(p_j+\epsilon+\eta-1)}$$

for sufficiently large |n|. Hence, by Theorem 1.6, we obtain the assertion of our theorem.

§ 4, Approximative dimension

1. Space $\mathscr{M}\left(\exp\left(a(n_1^{q_1}+\ldots+n_r^{q_r})-\frac{1}{a}(n_{r+1}^{q_{r+1}}+\ldots+n_k^{q_k})\right)\right)$. Now we prove

THEOREM 4.1. Let $X \approx \mathcal{M}\left(\exp\left(\alpha(n_1^{q_1} + \ldots + n_r^{q_r}) - \frac{1}{a}(n_{r+1}^{q_{r+1}} + \ldots + n_k^{q_k})\right)\right)$, with $q_i > 0$; $s = \sum_{i=1}^k q_i^{-1}$. Then

$$arPhi(X) = egin{dcases} \left\{arphi: \lim\left(\lograc{1}{arepsilon}
ight)^{s+1} \middle/ \logarphi(arepsilon) = 0
ight\}, & if & r = 0, \ \left\{arphi: \overline{\lim}\left(\lograc{1}{arepsilon}
ight)^{s+1} \middle/ \logarphi(arepsilon) < \infty
ight\}, & if & r > 0. \end{cases}$$

Proof. Put $a_{an}^{(j)}=\exp(an^{q_j})$ for $j=1,\ldots,r,$ $a_{an}^{(j)}=\exp(-n^{q_j}/a)$ for $j=r+1,\ldots,k$. Since, for any q>0,

$$\exp(an^q)/\exp(\beta n^q) \geqslant \varepsilon$$
 if and only if $n \leqslant \left(\frac{1}{\beta - a}\log\frac{1}{\varepsilon}\right)^{1/a}$

and

⁽⁹⁾ It is enough to notice that Theorem 1.6 holds true if we replace spaces $\mathscr{H}_{\mu}(C)$ by $\mathscr{H}_{\mu}(C_0)$.

$$\exp\left(-\frac{n^q}{a}\right) \Big/ \exp\left(-\frac{n^q}{\beta}\right) \geqslant \varepsilon \text{ if and only if } n \leqslant \left((1/a - 1/\beta)^{-1} \log \frac{1}{\varepsilon}\right)^{1/q},$$

we obtain

$$N_{aeta j}(arepsilon) = egin{cases} 1 + \mathrm{E}igg(rac{1}{eta - a} \log rac{1}{arepsilon}igg)^{1/a} & ext{for} \quad j = 1, \ldots, r, \ 1 + \mathrm{E}igg((1/a - 1/eta)^{-1} \log rac{1}{arepsilon}igg)^{1/a} & ext{for} \quad j = r + 1, \ldots, k. \end{cases}$$

Hence, for sufficiently small ε ,

and

$$\prod_{j=1}^k \, N_{a\beta j}(\varepsilon) \, \leqslant 2^k (\beta-a)^{-s'} (1/a - 1/\beta)^{s''} \left(\log \frac{1}{\varepsilon}\right)^s,$$

where $s' = 1/q_1 + \ldots + 1/q_r$, $s'' = 1/q_{r+1} + \ldots + 1/q_k$, s = s' + s''. Thus, according to Theorem 1.3, for sufficiently small ε we have

$$\begin{split} (41) & \quad \frac{1}{2k} (\beta - \alpha)^{-s'} (1/\alpha - 1/\beta)^{s''} \bigg(\log \frac{1}{\varepsilon} \bigg)^{s+1} \leqslant \log M_{\alpha\beta}(\varepsilon) \\ & \quad \leqslant 2^{k+1} (\beta - \alpha)^{-s'} (1/\alpha - 1/\beta)^{s''} \bigg(\log \frac{1}{\varepsilon} \bigg)^{s+1}. \end{split}$$

In virtue of the definition of M(A,B), $\varphi \in M(K_{\beta},K_{\alpha})$ (1) if and only if there exists $\varepsilon_0>0$ such that

$$\log \varphi(\varepsilon) \geqslant \log M_{\alpha\beta}(X; \varepsilon)$$
 for every $\varepsilon < \varepsilon_0$.

Hence, by (41),

$$2^{k+1}\overline{\lim_{\varepsilon\to 0}}\bigg((\beta-\alpha)^{-s'}(1/\alpha-1/\beta)^{s''}\bigg(\log\frac{1}{\varepsilon}\bigg)^s\bigg)/\log\varphi\left(\varepsilon\right)<1$$

implies

$$\varphi \in M(K_{\beta}, K_{\alpha})$$

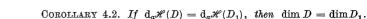
which implies

$$\frac{1}{2k}\overline{\lim_{\varepsilon\to 0}}\left((\beta-\alpha)^{-s'}(1/\alpha-1/\beta)^{s''}\left(\log\frac{1}{\varepsilon}\right)^{s}\right)/\log\varphi(\varepsilon)<1.$$

Now Theorem 1.2 gives us the assertion of the theorem.

Corollary 4.1. If $0 < r \leqslant k$, then $\mathrm{d}_a \mathscr{H}(C^r \times C_0^{k-r}) = \mathrm{d}_a \mathscr{H}(C^k) < \mathrm{d}_a \mathscr{H}(C_0^k)$.

$$(1) \ K_{\alpha} = \{x : ||x||_{\alpha} < 1\}, \ K_{\beta} = \{x : ||x||_{\beta} < 1\}.$$



COROLLARY 4.3. If D is an arbitrary bounded domain of the k-dimensional Euclidean complex space, then

$$\varPhi\big(\mathscr{H}(D)\big) = \bigg\{\varphi \colon \lim_{\varepsilon \to 0} \bigg(\log \frac{1}{\varepsilon}\bigg)^{k+1} / \log \varphi(\varepsilon) \, = \, 0\bigg\}.$$

These corollaries follow from Theorems 1.5, 2.4, 2.5 and 2.6.

2. Space $\mathcal{M}((n_1^{n_1} \dots n_r^{n_r})^a \cdot (n_{r+1}^{n_{r+1}} \dots n_r^{n_k})^{-1/a})$. Now we prove

Theorem 4.2. If $X = \mathcal{M}((n_1^{n_1} \dots n_r^{n_r})^a (n_{r+1}^{n_r+1} \dots n_k^{n_k})^{-1/a})$, then $\varphi \in \Phi(X)$ if and only if

$$\frac{\overline{\lim}}{\frac{1}{\varepsilon \to 0}} \frac{\left(\log \frac{1}{\varepsilon}\right)^{k+1} / \left(\log \log \frac{1}{\varepsilon}\right)^k}{\log \varphi(\varepsilon)} \left\{ \begin{array}{l} = 0 & \text{in the case where } r = 0, \\ < +\infty & \text{in the case where } r > 0. \end{array} \right.$$

Proof. Put $a_n^{(j)}=n^{an}$ for $j=1,\ldots,r,\ a_n^{(j)}=n^{-n/a}$ for $j=r,\ \ldots,\ k$. It is easy to verify that

$$N_{aeta j}(arepsilon) = egin{cases} \mathbb{E} arkappa igg(rac{1}{eta-a} \log rac{1}{arepsilon}igg) + 1 & ext{for} & j \leqslant r, \ \mathbb{E} arkappa igg((1/a - 1/eta)^{-1} \log rac{1}{arepsilon}igg) + 1 & ext{for} & j > r, \end{cases}$$

where $\varkappa(t)$ is the function inverse to the function $f(t) = t \log t$.

Since

$$\lim_{t\to 0}\frac{\varkappa(t)}{t/{\log t}}=1,$$

for sufficiently small ε , we have $\frac{1}{2}\,A_{a\beta j}\log\frac{1}{\varepsilon}\,/\log\log\frac{1}{\varepsilon}\leqslant N_{a\beta j}(\varepsilon)\leqslant 2A_{a\beta j}\log\frac{1}{\varepsilon}/\log\log\frac{1}{\varepsilon}$, where $A_{a\beta j}=1/(\beta-a)$ for $j=1,\ldots,r,\ A_{a\beta j}=(1/a-1/\beta)^{-1}$ for $j=r+1,\ldots,k.$ Therefore, for sufficiently small ε ,

$$\prod_{j=1}^k N_{\alpha\beta j} (\stackrel{2k}{V}_{\varepsilon}) \geqslant \left(\frac{1}{2}\right)^{3k^2} (\beta - \alpha)^{-r} (1/\alpha - 1/\beta)^{r-k} \left(\log \frac{1}{\varepsilon}/\log \log \frac{1}{\varepsilon}\right)^k$$

and

$$\prod_{i=1}^k N_{\alpha\beta i}(\varepsilon) \leqslant 2^k (\beta - \alpha)^{-r} (1/\alpha - 1/\beta)^{r-k} \left(\log \frac{1}{\varepsilon} / \log \log \frac{1}{\varepsilon}\right)^k.$$

Now in the same way as in the preceding section one can deduce the assertion of the theorem. **3. Space** $\mathscr{M}(\exp(n_1^a + \ldots + n_r^a + n_{r+1}^{q_{r+1}-1/a} + \ldots + n_k^{q_{k}-1/a}))$. We now prove

Theorem 4.3. If $X \approx \mathcal{M}(\exp{(n_1^a + \ldots + n_r^a + n_{r+1}^{q_r + 1^{-1/a}} + \ldots + n_k^{q_{k-1/a}})}$, then

$$\Phi(X) = \{\varphi \colon \lim_{\epsilon \to 0} (\log 1/\epsilon)^{s+1+\eta} / \log \varphi(\epsilon) = 0 \text{ for some } \eta > 0\},$$

where $s = 1/q_{r+1} + ... + 1/q_k$.

Proof. Let $a_n^{(j)} = \exp n^a$ for j = 1, ..., r, $a_n^{(j)} = \exp n^{a_j - 1/a}$ for j = r + 1, ..., k. It is easily seen that, for $a < \beta$,

$$\frac{\exp n^a}{\exp n^\beta} \geqslant \varepsilon \text{ if and only if } n \leqslant \lambda_{a\beta} \Big(\!\log \frac{1}{\varepsilon}\!\Big),$$

and

$$\frac{\exp n^{q-1/\alpha}}{\exp n^{q-1/\beta}} \geqslant \varepsilon \ \text{if and only if} \ n \leqslant \lambda_{q-\frac{1}{\alpha},q-\frac{1}{\beta}} \Big(\log \frac{1}{\varepsilon} \Big),$$

where $\lambda_{a\beta}(t)$ is the function inverse to the function $f(t)=t^{\beta}-t^{\alpha}$ $(\alpha<\beta)$. Hence

$$N_{aeta j}(arepsilon) = egin{cases} \mathbb{E} \lambda_{aeta} \Big(\log rac{1}{arepsilon} \Big) & ext{for} & j \leqslant r, \ & \mathbb{E} \lambda_{a_j - rac{1}{lpha}, a_j - rac{1}{eta}} \Big(\log rac{1}{arepsilon} \Big) & ext{for} & j > r. \end{cases}$$

Since $\lim_{t\to\infty}\lambda_{a\beta}(t)/t^{1/\beta}=1$, we obtain, for sufficiently small ε ,

and

Therefore, according to Theorem 3.1, we obtain

$$A_k \left(\log \frac{1}{\varepsilon}\right)^{(r/\beta + \sum (a_j - 1/\beta)^{-1}) + 1} \leqslant M_{\alpha\beta}(\varepsilon) \leqslant B_k \left(\log \frac{1}{\varepsilon}\right)^{(r/\beta + \sum (a_j - 1/\beta)^{-1}) + 1},$$

where A_k and B_k are constants.

From the last formula follows the assertion of Theorem 4.3, because

$$\lim_{\beta\to\infty} \left(r/\beta + \sum_{j=1}^{n} (q_j - 1/\beta)^{-1}\right) = s.$$

§ 5. Power spaces. Single matrix representations. Examples of non-isomorphic spaces having the same approximative dimension

1. Definition. Nuclear Köthe spaces of the forms $\mathcal{M}(a_n^a)$ and $\mathcal{M}(b_n^{1/a})$ will be called *power spaces of infinite or finite type*, respectively.

From Theorem 1.1 it follows that in the case of power spaces

(51) There exist $\beta > 0$ such that $\sum_n a_n^{\beta} < \infty$; for every t > 0, $\sum_n b_n^t < \infty$.

Without loss of generality it may be assumed that

$$(52) 1 \leqslant a_0 \leqslant a_1 \leqslant \ldots; 1 \geqslant b_0 \geqslant b_1 \geqslant \ldots$$

Let $\varphi(\varepsilon)$ and $\psi(\varepsilon)$ be functions defined for $\varepsilon > 0$. If there exists $\varepsilon_0 > 0$ such that $\varphi(\varepsilon) \geqslant \psi(\varepsilon)$ (resp. $\varphi(\varepsilon) > \psi(\varepsilon)$), for $\varepsilon < \varepsilon_0$ we shall write

$$\varphi(\varepsilon) \geqslant \psi(\varepsilon)$$
 (resp. $\varphi(\varepsilon) \stackrel{\cdot}{>} \psi(\varepsilon)$).

Let $X = \mathcal{M}(a_n^a)$, $Y = \mathcal{M}(b_n^{1/a})$, with (a_n) and (b_n) satisfying conditions (51) and (52). Put

$$M_{a}(X;arepsilon) = \prod_{n=0}^{\infty} \mathrm{E}\left(1 + 1/(arepsilon a_{n}^{a})
ight), ~~ ilde{M}_{a}(Y;arepsilon) = \prod_{n=0}^{\infty} \mathrm{E}\left(1 + b_{n}^{1/a}/arepsilon
ight),$$

and

$$\begin{split} & \textit{$M_{a}(X)$} = \{\varphi: \varphi(\varepsilon) \geqslant \textit{$M_{a}(X;\varepsilon)$}\}, \quad & \tilde{\textit{$M_{a}(Y)$}} = \{\varphi: \varphi(\varepsilon) \geqslant \tilde{\textit{M}}(Y;\varepsilon)\} \\ & \text{for $a=1,2,\dots$} \end{split}$$

Theorem 5.1.
$$\Phi(X) = \bigcup_{\alpha=1}^{\infty} M_{\alpha}(X), \quad \Phi(Y) = \bigcap_{\alpha=1}^{\infty} \tilde{M}_{\alpha}(Y).$$

This theorem is a simple consequence of Theorem 1.2.

THEOREM 5.2. Let $X = \mathcal{M}(a_n^a)$ and $Y = \mathcal{M}(b_n^{1/a})$ be power spaces of infinite type and of finite type, respectively. Then $d_a X \neq d_a Y$; therefore $X \neq Y$.

Proof. Suppose that

$$(53) \Phi(X) \supset \Phi(Y).$$

We shall prove that in this case $\Phi(X) \supseteq \Phi(Y)$.

From the definition of functions $M_{a}(X;\varepsilon)$ and $\tilde{M}_{a}(Y;\varepsilon)$ it follows that

$$(54) \qquad \ldots < M_2(X;\varepsilon) < M_1(X;\varepsilon); \qquad \tilde{M}_1(Y;\varepsilon) < \tilde{M}_2(Y;\varepsilon) < \ldots,$$

whence, by Theorem 5.1 and by formula (53), we have

(55)
$$\tilde{M}_{a}(Y; \varepsilon) < M_{a}(X; \varepsilon) \quad (\alpha = 1, 2, ...).$$

Inequalities (54) and (55) imply the existence of a decreasing sequence (ε_k) , with $\lim_{k \to \infty} \varepsilon_k = 0$, such that

$$egin{aligned} M_1(X;\,arepsilon) > M_2(X;\,arepsilon) > M_k(X;\,arepsilon) > & ilde{M}_k(Y;\,arepsilon) > & ilde{M}_k(Y;\,arepsilon) > & ilde{M}_1(Y;\,arepsilon) & ext{for} & arepsilon < arepsilon_k. \end{aligned}$$

Put

$$arphi(arepsilon) = egin{cases} 1 & ext{for} & arepsilon \geqslant arepsilon_1, \ rac{1}{2} \left(M_k(X; arepsilon) + ilde{M}_k(Y; arepsilon)
ight) & ext{for} & arepsilon_k > arepsilon \geqslant arepsilon_{k+1}. \end{cases}$$

We have

$$M_k(X; \varepsilon) \stackrel{.}{>} \varphi(\varepsilon) \stackrel{.}{>} \tilde{M_k}(Y; \varepsilon);$$

this means, according to Theorem 5.1, that $\Phi(X) \neq \Phi(Y)$, q.e.d. 2. Lemma 5.1. Let X be a nuclear space that satisfy the following condition:

(56) $\varphi \in \Phi(X)$ if and only if $\varphi^2 \in \Phi(X)$.

$$\begin{array}{ll} If \ \ X = \mathscr{M}(a_n^a), \ \ then \ \ \varPhi(X) = \bigcup_a \left\{ \varphi : \log \varphi(\varepsilon) / \log \frac{1}{\varepsilon} \ \geqslant N(\sqrt[a'/\varepsilon) \right\}; \\ if \ \ X = \mathscr{M}(b_n^{1/a}), \ then \ \ \varPhi(X) = \bigcap_a \left\{ \varphi : \log \varphi(\varepsilon) \log \frac{1}{\varepsilon} \ \geqslant \tilde{N}(\varepsilon^a) \right\}, \ \ where \ \ N(\varepsilon) = \overline{\overline{\{n : a_n \leqslant 1/\varepsilon\}}}, \quad \tilde{N}(\varepsilon) = \overline{\overline{\{n : b_n \geqslant \varepsilon\}}}. \end{array}$$

Proof. 1° $X = \mathcal{M}(a_n)$. Theorem 1.3, for k = 1, gives us

$$2N(\sqrt[a]{\varepsilon})\log\frac{1}{\varepsilon} \geqslant \log M_a(X;\varepsilon) \geqslant \frac{1}{2}N(\sqrt[2a]{\varepsilon})\log\frac{1}{\varepsilon}.$$

Let $\varphi \in \Phi(X)$. Then, by (56), $\sqrt{\varphi} \in \Phi(X)$ and, according to Theorem 5.1, we have

$$\varphi \, \epsilon \, \bigcup_a \left\{ \! \varphi \colon \tfrac{1}{2} \! \log \! \varphi (\varepsilon) \stackrel{.}{\geqslant} \tfrac{1}{2} N(\! \sqrt[a]{\varepsilon}) \! \log \frac{1}{\varepsilon} \! \right\}.$$

On the other hand, if $\varphi \in \bigcup_{a} \left\{ \varphi : 2\log \varphi(s) \geqslant 2N \left(\bigvee^{a} \varepsilon \right) \log \frac{1}{\varepsilon} \right\}$, then $\varphi^{2} \in \Phi(X)$ and, by (56), $\varphi \in \Phi(X)$.

 $2^{\circ} X = M(b_n^{1/a})$. The proof in this case is based on the inequality

$$2\, ilde{N}(arepsilon^a)\!\lograc{1}{arepsilon} \geqslant \log\, ilde{M}_a\!(X\,;\,arepsilon) \geqslant rac{1}{2}\, ilde{N}(arepsilon^{a/2})\lograc{1}{arepsilon}.$$

Remark 5.1. It is easily seen that in Lemma 5.1 assumption (56) may be replaced by " $\psi \in \bigcup_a \{ \psi : \psi(\varepsilon) \geqslant \tilde{N}(\tilde{V}\varepsilon) \text{ (resp. } \psi \in \bigcup_a \{ \psi : \psi(\varepsilon) \geqslant \tilde{N}(\varepsilon^a) \} \text{)}$ if and only if $2\psi \in \bigcup_a \{ \psi : \psi(\varepsilon) \geqslant \tilde{N}(\tilde{V}\varepsilon) \} \text{ (resp. } 2\psi \in \bigcap_a \{ \psi : \psi(\varepsilon) \geqslant \tilde{N}(\varepsilon^a) \} \text{)"}$.

THEOREM 5.3. Let X and X_1 be power spaces satisfying condition (56) and let $d_aX=d_aX_1$. Then the spaces X and X_1 are isomorphic.

Proof. 1° $X = \mathcal{M}(a_n^a)$, $X_1 = \mathcal{M}(c_n^a)$. Suppose that conditions (51) and (52) are satisfied. Let $N(\varepsilon)$ and $N_1(\varepsilon)$ be functions defined in Lemma 5.1, for the spaces X and X_1 , respectively. By Lemma 5.1, we have

$$\bigcup_a \left\{ \psi : \psi(\varepsilon) \geqslant N(\stackrel{a}{V} \overline{\varepsilon}) \right\} = \bigcup_a \left\{ \psi : \psi(\varepsilon) \geqslant N_1(\stackrel{a}{V} \overline{\varepsilon}) \right\},$$

whence $N(\varepsilon) \in \bigcup_a \{ \psi : \psi(\varepsilon) \geqslant N_1(\sqrt[q]{\varepsilon}) \}$ and $N_1(\varepsilon) \in \bigcup_a \{ \psi : \psi(\varepsilon) \geqslant N(\sqrt[q]{\varepsilon}) \}$. Thus there exist positive integers a_0 and β_0 such that $N(\varepsilon) \geqslant N_1(\sqrt[q]{\varepsilon})$, $N_1(\varepsilon) \geqslant N(\sqrt[q]{\varepsilon})$. Sequences (a_n) , (c_n) being non-decreasing, this implies that, for sufficiently large n, $a_n \leqslant c_n^{e_0}$ and $a_n \leqslant c_n^{e_0}$, i. e. the identical mapping $T(\xi_n) = (\xi_n)$ is the required isomorphism from X onto X_1 . $2^o X = \mathcal{M}(b_n^{1/a}), X_1 = \mathcal{M}(d_n^{1/a})$. Let (b_n) and (d_n) satisfy conditions (51) and (52). Denote by $\tilde{N}(\varepsilon)$ and $\tilde{N}_1(\varepsilon)$ the function defined in Lemma 5.1 for the spaces X and X_1 , respectively. By Lemma 5.1

(57)
$$\bigcap \{ \psi : \psi(\varepsilon) \geqslant \tilde{N}(\varepsilon^{\alpha}) \} = \bigcap \{ \psi : \psi(\varepsilon) \geqslant \tilde{N}_{1}(\varepsilon^{\alpha}) \}.$$

We shall show that there exists a positive integer α_0 such that $\tilde{N}(\varepsilon^{a_0}) \geqslant \tilde{N}_1(\varepsilon)$.

In fact, if the last inequality held for no α , then there would exist a decreasing sequence (ε_a) , with $\lim_{a\to 0}\,\varepsilon_a=0$, such that $\tilde{N}(\varepsilon_a^a)<\tilde{N}_1(\varepsilon_a)$. Let

$$\psi(arepsilon) = egin{cases} 1 & ext{for} & arepsilon > arepsilon_1, \ ilde{N}(arepsilon^a) & ext{for} & arepsilon_a \geqslant arepsilon > arepsilon_{a+1}. \end{cases}$$

Then $\psi \in \bigcap_{a} \{ \psi : \psi(\varepsilon) \geqslant \tilde{N}(\varepsilon^{a}) \}$ and $\psi \in \bigcap_{a} \{ \psi : \psi(\varepsilon) \geqslant \tilde{N}_{1}(\varepsilon) \}$, which contradicts formula (57).

Now $\tilde{N}(\varepsilon_n^{a_0}) \geqslant \tilde{N}_1(\varepsilon)$ implies that, for sufficiently large $n, d_n \geqslant b_n^{a_0}$. The assumption of the theorem being symmetric with respect to X and X_1 , we have also $b_n \geqslant d_n^{b_0}$ for sufficiently large n. Hence the mapping $T(\xi_n) = (\xi_n)$ is the required isomorphism from X onto X_1 , q. e. d.

Since nuclear Köthe spaces of type $\mathscr{M}(a_n^a)$, $\mathscr{M}(b_n^{1/a})$ are isomorphic to power spaces, we have

COROLLARY 5.1. If $X = \mathcal{M}(a_n^a)$, $X_1 = \mathcal{M}(c_n^a)$, $Y = \mathcal{M}(b_n^{1/a})$, $Y_1 = \mathcal{M}(d_n^{1/a})$ are nuclear Köthe spaces satisfying condition (56) and $d_a X = d_a X_1$, $d_a Y = d_a X_1$, then $X = X_1$, $Y = Y_1$.

Spaces considered in \S 2.3, sections 1 and 2, satisfy condition (56). Hence

COROLLARY 5.2. Let

$$X = \mathcal{M}\left(\exp\left(a(n_1^{q_1} + \ldots + n_r^{q_r}) - \frac{1}{a}(n_{r+1}^{q_r+1} + \ldots + n_r^{q_r})\right)\right)$$

with $q_i > 0$, and let $q = (1/q_1 + \ldots + 1/q_k)^{-1}$. Then if r = 0, then $X = M(\exp - n^q/a)$; if r = k, then $X = M(\exp an^q)$.

COROLLARY 5.3. Let $X = \mathcal{M}((n_1^{n_1} \dots n_r^{n_r})^a \cdot (n_{r+1}^{n_{r+1}} \dots n_k^{n_k})^{-1/a})$. If r = 0, then $X = \mathcal{M}(n^{-Vn/a})$; if r = k, then $X \approx \mathcal{M}(n^{aVn})$.

To prove these two corollaries we apply Theorems 4.2 and 4.3 for an arbitrary k and for k=1 and verify that suitable spaces have an equal approximative dimension.

3. In general, Köthe spaces with the same approximative dimension need not be isomorphic.

Example 5.1. Let $X=\mathcal{M}(\exp an), Y=(X\times X\times\ldots)_s.$ Then $d_aX=d_aY,$ but $X\neq Y.$

The quality of approximative dimensions follows from Theorem 1.5. $X \neq Y$, because there exist continuous (homogeneous) norms defined on X; in the space s (of all numerical sequences), which is isomorphically contained in Y, no continuous pseudonorm is a norm.

The next example will concern the spaces in which there are continuous norms.

Example 5.2. Let $X=\mathscr{H}(C_0),\ Y=\mathscr{H}(C_0)\times\mathscr{H}(C).$ Then $\mathrm{d}_aX=\mathrm{d}_aY,\ but\ X\neq Y.$

The equality of d_a follows from the inclusions $X \approx X \times X \supset Y \supset X$ (see Theorems 2.2 and 2.4).

To prove that X and Y are not isomorphic, we shall apply the following result of Dragilev [7]:

Every basis (e_n) of the space $\mathscr{H}(C_0)$ is c-equivalent to the basis (z^n) , i. e. there exist a sequence (τ_n) of positive numbers and a permutation (p_n) of indices such that the series $\sum\limits_n t_n(\tau_n e_{p_n})$ converges if and only if the series $\sum\limits_n t_n z_n$ converges.

If X = Y then the space $\mathscr{H}(C_0)$ would be isomorphic to the space $\mathscr{M}(c_{an})$, where $c_{an} = \exp an$ for n = 2m-1, $c_{an} = \exp -n/a$ for n = 2m. Now according to the theorem of Dragilev there would exist an increa-

sing sequence (k_n) of non-negative integers such that $\mathcal{M}(\exp a, n) \approx \mathcal{M}(\exp - k_n/a)$, which contradicts Theorem 5.2.

4. General remarks. Let

(58)
$$\Psi(X) = \left\{ \psi(\varepsilon) = \log \varphi(\varepsilon) / \log \frac{1}{\varepsilon} : \varphi \, \epsilon \, \varPhi(X) \right\}.$$

Condition (56) formulated in terms of $\Psi(X)$ has a form

(56') $\psi \in \Psi(X)$ if and only if $2\psi \in \Psi(X)$.

It is easy to prove the following

THEOREM 5.4. Let X and Y be power spaces satisfying condition (56'). Then $\Psi(X \times Y) = \{ \psi = \psi_1 + \psi_2 : \psi_1 \epsilon \Psi(X), \quad \psi_2 \epsilon \Psi(Y) \}, \quad \Psi(X \hat{\otimes} Y) = \{ \psi = \psi_1 \cdot \psi_2 : \psi_1 \epsilon \Psi(X), \quad \psi_2 \epsilon \Psi(Y) \}.$

All the spaces considered in § 4 are tensor products of k copies of single Köthe spaces; the results of § 4 are illustrations of Theorem of § 4.

The theorem of Dragilev cited in section 3 has been generalized by Mitiagin [20] in the following way:

In an arbitrary power space all bases are c-equivalent.

Applying this theorem, by the same consideration as in Example 5.2 we obtain

COROLLARY 5.4. If X and Y are power spaces of finite and of infinite type, respectively, then $X \times Y \ddagger X$, $X \times Y \ddagger Y$; $X \hat{\otimes} Y \ddagger X$, $X \hat{\otimes} Y \ddagger Y$.

In particular we have

Example 3. Let $X_i = \mathcal{M}\left(\exp\left(a(n_1^{q_1} + \ldots + n_{r_i}^{q_{r_i}}) - \frac{1}{a}(n_{r_i+1}^{q_{r_i+1}} + \ldots + n_{r_i+1}^{q_{r_i}})\right)$, $Y_i = \mathcal{M}\left((n_1^{n_1} \ldots n_{r_i}^{n_{r_i+1}} \cdot (n_{r_i+1}^{n_{r_i+1}} \ldots n_k^{n_k})^{-1/a})$ for i = 1, 2 be spaces of type considered in §§ 3, 4, sections 2 and 3. If $r_1 = 1, r_2 < k$, then $d_a X_1 = d_a X_2$, $d_a Y_1 = d_a Y_2$. If $r_1 = 1, r_2 > 1$ or $r_1 < k$, $r_2 = k$, then $X_1 \neq X_2$ and $Y_1 \neq Y_2$.

We do not know whether (56') is true in the case where $1 < r_1 < < r_2 < k$; in particular we do not know whether $H(C_0 \times C^2) \neq H(C_0^2 \times C)$? This is obviously connected with the following

Conjecture. Let X_1 and Y_1 be power spaces of infinite type, let X_2 and Y_2 be power spaces of finite type and let X_1 , Y_1 , X_2 , Y_2 satisfy condition (56). If $X_1 \neq Y_1$ or $X_2 \neq Y_2$, then $X_1 \hat{\otimes} X_2 \neq Y_1 \hat{\otimes} Y_2$ (cf. Problem 2.1).

§ 6. Estimation of Taylor coefficients

Let $\boldsymbol{n}=(n_1,\ldots,n_k)$. We shall write $|\boldsymbol{n}|=n_1+\ldots+n_k$. Theorem 6.1. Let q>0. $(\xi_n)\epsilon\,\mathcal{M}(\exp\alpha\,|\boldsymbol{n}|^q)$ if and only if $\lim_{|\boldsymbol{n}|\to\infty}\sqrt{|\xi_n|}=0$. $(\xi_n)\epsilon\,\mathcal{M}(\exp\alpha\,|\boldsymbol{n}|^q)$ if and only if $\lim_{|\boldsymbol{n}|\to\infty}\sqrt{|\xi_n|}\leqslant 1$.

Proof. 1º The following conditions are equivalent:

(a1)
$$(\xi_n) \in \mathcal{M}(\exp \alpha |n|^q),$$

(a2)
$$\lim_{|n|\to\infty} |\xi_n| \exp \alpha |n|^q = 0 \quad \text{ for } \quad \alpha = 1, 2, ...,$$

(a3)
$$\lim_{|n|\to\infty} (\log |\xi_n| + \alpha |n|^q) = -\infty \quad \text{for} \quad \alpha = 1, 2, \dots,$$

(a4)
$$\overline{\lim_{|n|\to\infty}} (\log |\xi_n| + \alpha |n|^a) < 0 \quad \text{ for } \quad \alpha = 1, 2, ...,$$

$$\lim_{|n|\to\infty}\frac{\log\xi_n}{|n|^q}=-\infty,$$

$$\overline{\lim_{\substack{|n|\to\infty}}} |\xi_n|^{1/|n|^q} = 0.$$

2° The following conditions are equivalent:

(b1)
$$(\xi_n) \in \mathcal{M}\left(\exp\left(-|\boldsymbol{n}|^q/\alpha\right)\right),$$

(b3)
$$\lim_{|\boldsymbol{n}|\to\infty} (\log|\xi_{\boldsymbol{n}}| - |\boldsymbol{n}|^{a}/a) = -\infty \quad \text{ for } \quad a = 1, 2, \ldots,$$

$$\overline{\lim_{|n|\to\infty}} \frac{\log \xi_n}{|n|^q} = 0,$$

$$\overline{\lim}_{|n| \to \infty} |\xi_n|^{1/|n|^q} \leqslant 1,$$

q. e. d.

Applying Theorems 3.1, 3.4, 3.6 we obtain

Corollary 6.1. $\sum_{n \in \mathcal{N}^k} c_n z^n \in \mathcal{H}(C^k)$ if and only if $\lim_{n \to \infty} \sqrt[|n|]{c_n} = 0$.

 $\sum_{\boldsymbol{n}e,\boldsymbol{r}'^k} c_{\boldsymbol{n}} z^{\boldsymbol{n}} \in \mathscr{H}(C_0^k) \text{ if and only if } \lim_{\substack{\boldsymbol{v} \in \mathcal{F}^k \\ \boldsymbol{\sigma}^{\boldsymbol{n}} = z_1^{n_1} \dots z_k^{n_k} \rangle}.$ (where $\boldsymbol{n} = (n_1, \dots, n_k)$,

COROLLARY 6.2. Let $\mu(\varepsilon, z) = \exp\left(-(\tau_1 + \varepsilon)|z_1|^{p_1} - \dots - (\tau_k + \varepsilon)|z_k|^{p_k}\right)$ with $\tau_i \geqslant 0$, $p_i > 0$. If $\tau_1 = \dots = \tau_k = 0$, then $\sum_{n \in \mathcal{N}^k} c_n z^n \in \mathcal{H}_{\mu}$ if and only

if $\overline{\lim_{n \in \mathcal{N}} V c_n d_n} = 0$. If all $\tau_i > 0$, then $\sum_{n \in \mathcal{N}} c_n c_n^n \in \mathcal{H}_{\mu}$ if and only if $\overline{\lim_{n \in \mathcal{N}} V c_n d_n} \leq 1$, where d_n are given by formula (35).

Corollary 6.3. Let $\mu(\varepsilon,z)=\exp\left(-\varepsilon(\log 1/z)^{-s}\right)$, with s>0. Then $\sum_{n=0}^{\infty}c_nz^n\,\varepsilon\,\mathscr{H}_{\mu}(C_0)\ \ \text{if and only if}\ \ \overline{\lim} \stackrel{n^2}{Vc_n}\leqslant 1,\ \ \text{where}\ \ q=s/(s+1).$

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Bases, lacunary sequences and complemented subspaces in the spaces L_p

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M. I. KADEC (Kharkov) and A. PEŁCZYŃSKI (Warszawa)

In this paper we investigate the isomorphic structure (invariants of linear homeomorphisms) of subspaces of the space L_p $(1 \le p < +\infty)$. We consider especially the properties of basic sequences (bases in subspaces), as well as the properties of subspaces complemented in L_p . These properties are connected with classical problems concerning lacunary series. We explain them in a more detailed way.

Let p>2 and let (q_n) be an orthonormal system. Then

$$\left(\int\limits_{0}^{1} \Big| \sum_{i=1}^{n} t_{i} \varphi_{i}(t) \Big|^{p} dt \right)^{1/p} \geqslant \left(\int\limits_{0}^{1} \Big| \sum_{i=1}^{n} t_{i} \varphi_{i}(t) \Big|^{2} dt \right)^{1/2} = \left(\sum_{i=1}^{n} |t_{i}|^{2} \right)^{1/2}$$

for any scalars $t_1, t_2, ..., t_n$ (n = 1, 2, ...).

An orthonormal system is said to be p-lacunary iff (1) the converse inequality

$$\left(\int_{0}^{1} \left| \sum_{i=1}^{n} t_{i} \varphi_{i}(t) \right|^{p} dt \right)^{1/p} \leqslant C \left(\sum_{i=1}^{n} |t_{i}|^{2} \right)^{1/2}$$

holds for some C depending only on (φ_n) and for any t_1, t_2, \ldots, t_n $(n = 1, 2, \ldots)$.

In the language of the functional analysis this means that there is an isomorphism (linear homeomorphism) of Hilbert space l_2 onto the closed linear manifold in L_p spanned on the functions φ_n . Under this isomorphism the unit vectors in l_2 correspond the functions φ_n , i. e. the basic sequence (φ_n) is equivalent to the unit vector basis in l_2 (see the definition in section 1). Moreover, the operator $T\colon x\to (\int\limits_0^1 x(t)\,\varphi_n(t)\,dt)$ is a projection of L_p onto this manifold.

⁽¹⁾ We write "iff" instead of "if and only if". Studia Mathematica XXI