

Operator fractional-linear transformations: convexity and compactness of image; applications

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Abstract. The present paper consists of two parts. In Section 1 we consider fractional-linear transformations (f.-l.t. for brevity) F in the space $\mathcal{L}(\mathcal{X}_1, \mathcal{X}_2)$ of all linear bounded operators acting from \mathcal{X}_1 into \mathcal{X}_2 , where $\mathcal{X}_1, \mathcal{X}_2$ are Banach spaces. We show that in the case of Hilbert spaces $\mathcal{X}_1, \mathcal{X}_2$ the image $F(\mathcal{B})$ of any (open or closed) ball $\mathcal{B} \subset D(F)$ is convex, and if \mathcal{B} is closed, then $F(\mathcal{B})$ is compact in the weak operator topology (w.o.t.) (Theorem 1.2). These results extend the corresponding results on compactness obtained in [3], [4] under some additional restrictions imposed on F . We also establish that the convexity of the image of f.-l.t. is a characteristic property of Hilbert spaces, that is, if for the f.-l.t. $F : K \rightarrow (I + K)^{-1}$ the image $F(\mathcal{K})$ of the open unit ball \mathcal{K} of the space $\mathcal{L}(\mathcal{X})$ is convex, then \mathcal{X} is a Hilbert space (Theorem 1.3).

In Section 2 we apply the compactness of $F(\overline{\mathcal{K}})$ for the closed unit operator ball $\overline{\mathcal{K}}$ to the study of the behavior of solutions to evolution problems in a Hilbert space \mathcal{H} . Namely, we establish the exponential dichotomy of solutions for the so-called hyperbolic case (such that the evolution operator is invertible). This is an extension of Theorem 1.1 of [5], where the corresponding assertion was established for the particular case of a Pontryagin space \mathcal{H} .

1. Fractional-linear transformations. For Banach spaces $\mathcal{X}_1, \mathcal{X}_2$ let $\mathcal{L}(\mathcal{X}_1, \mathcal{X}_2)$ be the space of all bounded linear operators from \mathcal{X}_1 to \mathcal{X}_2 . For any operator matrix $V = (V_{ij}), i, j = 1, 2, V_{ij} \in \mathcal{L}(\mathcal{X}_j, \mathcal{X}_i)$, the formula

$$F(K) = (V_{21} + V_{22}K)(V_{11} + V_{12}K)^{-1}$$

defines the f.-l.t. $F = F_V : D(F) \rightarrow \mathcal{L}(\mathcal{X}_1, \mathcal{X}_2)$, where

$$D(F) = \{K \in \mathcal{L}(\mathcal{X}_1, \mathcal{X}_2) : V_{11} + V_{12}K \text{ is invertible}\}$$

(see [2], [3]).

For any (open or closed) ball $\mathcal{B} \subset D(F)$ in $\mathcal{L}(\mathcal{X}_1, \mathcal{X}_2)$ we set $F(\mathcal{B}) = \{F(K) : K \in \mathcal{B}\}$.

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LEMMA 1.1. Let $\mathcal{X}_1, \mathcal{X}_2$ be Hilbert spaces and $\mathcal{Y} = \mathcal{Y}(R, P, Q)$ be the set of all operators $Y \in \mathcal{L}(\mathcal{X}_1, \mathcal{X}_2)$ satisfying the inequality

$$(1) \quad YRY^* + PY^* + YP^* + Q \leq 0,$$

where $R \in \mathcal{L}(\mathcal{X}_1), P \in \mathcal{L}(\mathcal{X}_1, \mathcal{X}_2), Q \in \mathcal{L}(\mathcal{X}_2), R \geq 0$ and $Q^* = Q$. Then \mathcal{Y} is convex and closed in the w.o.t. of the space $\mathcal{L}(\mathcal{X}_1, \mathcal{X}_2)$.

PROOF. The closedness of \mathcal{Y} follows immediately from the fact that $(R\xi, \xi) \leq \liminf (R\xi_n, \xi_n)$ for any sequence ξ_n weakly converging to ξ . To prove convexity we assume at first that R is invertible. Then (1) can be rewritten in the form

$$(YR^{1/2} + PR^{-1/2})(YR^{1/2} + PR^{-1/2})^* \leq T,$$

where $T = PR^{-1}P^* - Q$. So \mathcal{Y} is convex as the preimage of the convex set $S = \{S : SS^* \leq T\}$ under the affine transformation $Y \rightarrow YR^{1/2} + PR^{-1/2}$.

In the general case one can use the evident equality

$$\mathcal{Y}(R, P, Q) = \bigcup_{\lambda > 0} \bigcap_{\varepsilon > 0} \mathcal{Y}(R + \varepsilon I, P, Q - \varepsilon \lambda I).$$

THEOREM 1.2. If $\mathcal{X}_1, \mathcal{X}_2$ are Hilbert spaces, then $F(\mathcal{B})$ is convex for any ball $\mathcal{B} \subseteq D(F)$. For \mathcal{B} closed, $F(\mathcal{B})$ is w.o.t.-compact.

PROOF. Let $\mathcal{B} = \{K \in \mathcal{L}(\mathcal{X}_1, \mathcal{X}_2) : \|K - K_0\| \leq r\}$ be a closed ball contained in $D(F)$. Dilating and translating \mathcal{B} if necessary (and changing F accordingly) we may suppose that \mathcal{B} is the unit ball:

$$\mathcal{B} = \mathcal{B}_0 = \{K \in \mathcal{L}(\mathcal{X}_1, \mathcal{X}_2) : \|K\| \leq 1\}.$$

Since $0 \in \mathcal{B}_0 \subset D(F)$ the operator V_{11} is invertible, hence

$$F(K) = (V_{21} + V_{22}K)(I + V_{11}^{-1}V_{12}K)^{-1}V_{11}^{-1}$$

and $\|V_{11}^{-1}V_{12}\| < 1$ (in the other case $D(F)$ would not contain \mathcal{B}_0). So it is sufficient to prove the convexity and w.o.t.-compactness of the image of \mathcal{B}_0 under any map F of the form

$$F(K) = (B + CK)(I + DK)^{-1}$$

with $\|D\| \leq 1$. In this case the equality $Y = F(K)$ is equivalent to

$$(2) \quad (YD - C)K = B - Y.$$

Hence $Y \in F(\mathcal{B}_0)$ when (2) is satisfied for some $K \in \mathcal{B}_0$. It is known (see, for example, [8]) that this is the case when

$$(3) \quad (YD - C)(YD - C)^* \geq (B - Y)(B - Y)^*.$$

But (3) coincides with (1) if we take $R = I - DD^*, P = CD^* - B$ and $Q = BB^* - CC^*$. Now Lemma 1 implies that $F(\mathcal{B}_0)$ is a convex and w.o.t.-closed subset of $\mathcal{L}(\mathcal{X}_1, \mathcal{X}_2)$. Since $\|F(K)\| \leq (\|B\| + \|C\|)(1 - \|D\|)^{-1}$ for $K \in \mathcal{B}_0$, $F(\mathcal{B}_0)$ is bounded and weakly compact (by the Banach-Alaoglu

theorem). The convexity of the image of an open ball now follows from the fact that

$$\{K : \|K - K_0\| < r\} = \bigcup_{0 < \lambda < 1} \{K : \|K - K_0\| \leq \lambda r\}.$$

Let us show that the convexity of the image of the open unit ball under the f.l.t. $K \rightarrow (I + K)^{-1}$ characterizes Hilbert spaces in the class of all Banach spaces.

THEOREM 1.3. If the image of the open unit ball of $\mathcal{L}(\mathcal{X})$ under the map $K \rightarrow (I + K)^{-1}$ is convex then \mathcal{X} is a Hilbert space.

PROOF. Let $\mathcal{P} = \{(I + K)^{-1} : \|K\| < 1\}$. Since \mathcal{P} is convex by assumption, $\mathcal{P}\xi = \{A\xi : A \in \mathcal{P}\}$ is convex for any $\xi \in \mathcal{X}$. If $\xi \neq 0$ then $\mathcal{P}\xi = \{\eta \in \mathcal{X} : (I + K)\eta = \xi, \|K\| < 1\} = \{\eta \in \mathcal{X} : \|\xi - \eta\| < \|\eta\|\}$. The convexity of $\mathcal{P}\xi$ implies the convexity of the set

$$\mathcal{K}(\xi) = \{\eta \in \mathcal{X} : \|\xi - \eta\| < \|\xi + \eta\|\}$$

since $\mathcal{K}(\xi) = 2\mathcal{P}\xi - \xi$.

Let $\eta \in \mathcal{K}(\xi)$ and $\lambda \in (0, 1)$. Since $\mathcal{K}(\xi)$ is open there exists $0 < \varepsilon < 1$ such that the vector

$$\eta(\varepsilon) = \varepsilon\xi + \lambda^{-1}(\lambda\eta - \varepsilon\xi)$$

belongs to $\mathcal{K}(\xi)$. Since $\varepsilon\xi \in \mathcal{K}(\xi)$ the convexity of $\mathcal{K}(\xi)$ implies

$$\lambda\eta = \lambda\eta(\varepsilon) + (1 - \lambda)\varepsilon\xi \in \mathcal{K}(\xi).$$

We have proved that the inequality

$$(4) \quad \|\xi - \eta\| < \|\xi + \eta\|$$

implies

$$(5) \quad \|\xi - \lambda\eta\| < \|\xi + \lambda\eta\|$$

for $\lambda \in (0, 1)$. Interchanging the roles of ξ and η in (4) we get

$$\|\lambda\xi - \eta\| < \|\lambda\xi + \eta\|$$

for $\lambda \in (0, 1)$. This is equivalent to the validity of (5) for $\lambda > 1$. Hence $\lambda\mathcal{K}(\xi) = \mathcal{K}(\xi)$ for any $\lambda > 0$. It follows that the set

$$\mathcal{T}(\xi) = \{\eta \in \mathcal{X} : \|\eta - \xi\| = \|\eta + \xi\|\}$$

is also invariant under multiplication by $\lambda > 0$ (indeed, if $\lambda\eta$ does not belong to $\mathcal{T}(\xi)$, then $\lambda\eta \in \mathcal{K}(\xi) \cup \mathcal{K}(-\xi)$, hence $\eta \in \lambda^{-1}\mathcal{K}(\xi) \cup \lambda^{-1}\mathcal{K}(-\xi) = \mathcal{K}(\xi) \cup \mathcal{K}(-\xi)$, and therefore η does not belong to $\mathcal{T}(\xi)$). Hence $\lambda\mathcal{T}(\xi) \subset \mathcal{T}(\xi)$ for any $\lambda > 0$. By James' Theorem [2] the last means that \mathcal{X} is a Hilbert space.

COROLLARY 1.4. *If the image of the closed unit ball of $\mathcal{L}(\mathcal{X})$ under the mapping $K \rightarrow (\lambda I + K)^{-1}$ is convex for each $\lambda > 0$, then \mathcal{X} is a Hilbert space.*

Proof. It is sufficient to notice that

$$\begin{aligned} \{(I + K)^{-1} : \|K\| < 1\} &= \bigcup_{\varepsilon > 0} \{(I + K)^{-1} : \|K\| \leq 1 - \varepsilon\} \\ &= \bigcup_{\lambda > 1} \{\lambda(\lambda I + X)^{-1} : \|X\| < 1\} \end{aligned}$$

is a convex set by Theorem 1.3.

2. Applications to evolution problems. Let

$$(6) \quad \frac{dx}{dt} = A(t)x$$

be a differential equation in a Hilbert space \mathcal{H} with a scalar product (\cdot, \cdot) , and for $t \in \mathbb{R}^+ = [0, \infty)$, let $A(t)$ be selfadjoint operators in \mathcal{H} with a common dense domain \mathcal{D} . The Cauchy problem for equation (6) is assumed to be uniformly well-posed. Therefore there exists a bounded linear operator $U(t)$ in \mathcal{H} (called an *evolution operator*) such that for every solution $x(t)$ for (6) with $x(0) = x_0 \in \mathcal{D}$ we have $x(t) = U(t)x_0$. If y_0 does not belong to \mathcal{D} we will call $y(t) = U(t)y_0$ a *generalized solution*.

Let $\mathcal{L}_{2,w}(\mathbb{R}^+, \mathcal{H})$ be the set of functions $x : \mathbb{R}^+ \rightarrow \mathcal{H}$ Bochner square integrable with respect to a strictly positive locally integrable weight $w = w(t)$. Let \mathcal{N} denote the set of generalized solutions belonging to $\mathcal{L}_{2,w}(\mathbb{R}^+, \mathcal{H})$. Set $\mathcal{N}_0 = \{h \in \mathcal{H} : h = y(0), y \in \mathcal{N}\}$.

Consider the following indefinite metric on \mathcal{H} depending on t :

$$[x, y]_t = (J(t)x, y),$$

where $J(t) = P_1(t) - P_2(t)$, $P_1(t) = \int_{+0}^{+\infty} dE_\lambda(t)$, $P_2(t) = \int_{-\infty}^0 dE_\lambda(t)$, $E_\lambda(t)$ being the spectral function of $A(t)$.

The following sets (called *bicones*) will be used below:

$$C_t^- = \{y_0 \in \mathcal{H} : [U(t)y_0, U(t)y_0]_t \leq 0\}, \quad t \in \mathbb{R}^+.$$

A bicone C_t^- is said to be of *rank* $r \leq \infty$ if it contains a subspace $\mathcal{L} \subset \mathcal{H}$ with $\dim \mathcal{L} = r$, and does not contain subspaces of greater dimensions (see [6]; note that in [6] the case of $r < \infty$ was studied only).

Suppose that $J(t)$ is strongly differentiable. Consider the derivative of the solution $x(t)$ for (6) along the trajectory:

$$(J(t)x(t), x(t))' = 2 \operatorname{Re}(J(t)A(t)x(t), x(t)) + (J(t)'x(t), x(t)).$$

We will assume below that $(J(t)x(t), x(t))'$ is qualified positive and that the evolution problem is hyperbolic, that is, the operator $U(t)$ is invertible for all $t \in \mathbb{R}^+$.

THEOREM 2.1. *Suppose the Cauchy problem for the equation (6) is uniformly well-posed and the metric $[\cdot, \cdot]$ satisfies the following conditions:*

(a) *$J(t)$ is strongly differentiable, the limit $\lim_{t \rightarrow \infty} \dim P_2(t) = d_-$ exists and*

$$(7) \quad \inf_{\|\xi\|=1} \{ \operatorname{Re}[A(t)\xi, \xi]_t + \frac{1}{2}(J(t)'\xi, \xi) \} \geq w(t), \quad t \in \mathbb{R}^+;$$

(b) *the evolution operator is invertible for each $t \in \mathbb{R}^+$ and*

$$(8) \quad [U^*(t)z, U^*(t)z]_0 \geq 0$$

for every $t \in \mathbb{R}^+$ and for each $z \in \mathcal{H}$ such that $[z, z]_t \geq 0$.

Then the generalized solutions $y(t) = U(t)y_0$, $y_0 \in \mathcal{H}$, have the following properties:

- 1) $\mathcal{N}_0 \supset C_\infty^- = \bigcap_{t \in \mathbb{R}^+} C_t^-$, where C_∞^- is a bicone of rank d_- ;
- 2) for any $y(t) \in \mathcal{N}$,

$$(9) \quad \int_t^\infty w(s)\|y(s)\|^2 ds \leq I(y) \exp\left(-2 \int_0^t w(s) ds\right),$$

where $I(y) = \int_0^\infty w(s)\|y(s)\|^2 ds$;

- 3) for any $y_0 \in \mathcal{H} \setminus C_\infty^-$,

$$(10) \quad \|y(t)\| \geq [y_0, y_0]_0 \exp\left(2 \int_0^t w(s) ds\right), \quad t \in \mathbb{R}^+.$$

COROLLARY 2.1. *Under the conditions of Theorem 2.1 let*

$$(11) \quad \int_0^\infty w(t) dt = \infty.$$

Then all the statements 1)-3) are true, and moreover, \mathcal{N}_0 is a closed subspace of \mathcal{H} with $\dim \mathcal{N}_0 = d_-$.

Before we prove Theorem 2.1 we should recall that in the case $\dim P_1(t) < \infty$, $t \in \mathbb{R}^+$, condition (8) is automatically satisfied (see [7]). Then if $J(t) = J = \text{const}$, we have: (7) is equivalent to $\operatorname{Re}[A(t)\xi, \xi]_t \geq w(t)\|\xi\|^2$, $\xi \in \mathcal{D}$.

Proof of Theorem 2.1. With the help of (7) we get, for any $\tau < t \in \mathbb{R}^+$ and $y_0 \in \mathcal{D}$,

$$(12) \quad [U(t, \tau)y_0, U(t, \tau)y_0]_t - [y_0, y_0]_\tau \geq 2 \int_\tau^t w(s)\|U(s, \tau)y_0\|^2 ds,$$

where $U(t, \tau)$ is the operator assigning to each $y_0 \in \mathcal{D}$ the value $y(t, s)$ of the solution for equation (6) which satisfies the initial condition $y(\tau, \tau) = y_0$

(so that $U(t)$ is the brief notation for $U(t, 0)$). By continuity of $U(t, \tau)$ the inequality (12) holds for any $y_0 \in \mathcal{H}$. Hence we obtain (keeping in mind $\|U(t)y_0\|^2 \geq [U(t)y_0, U(t)y_0]_t$ and setting $y(t) = U(t)y_0$)

$$(13) \quad \|y(t)\|^2 \geq 2 \int_0^t w(s) \|y(s)\|^2 ds + [y_0, y_0]_0,$$

where $y(t) = U(t)y_0$. Taking $y_0 \in \mathcal{H} \setminus C_0^-$ and arguing as in the Bellman-Gronwall lemma (see [1], Chapt. II) we get (10). Namely, from (13) we have

$$\frac{\|y(t)\|^2 w(t)}{2 \int_0^t w(s) \|y(s)\|^2 ds + [y_0, y_0]_0} \geq w(t).$$

Hence integrating from 0 to t we obtain the required inequality.

From (12) it is easy to see that

$$C_t^- \subset C_\tau^- \quad \text{for } t > \tau, \quad t, \tau \in \mathbb{R}^+.$$

It follows from the condition (b) that the operator $U^{-1}(t)$ generates a fractional-linear transformation

$$F_{U^{-1}(t)}(K(t)) = (U_{11}^{-1}(t) + U_{12}^{-1}(t)K(t))(U_{12}^{-1}(t) + U_{22}^{-1}(t)K(t))^{-1}$$

of the closed unit operator ball $\mathcal{K}(t) \subset \mathcal{L}(P_2(t)\mathcal{H}, P_1(0)\mathcal{H})$ such that

$$\begin{aligned} U^{-1}(t) : \mathcal{H}_t &\rightarrow \mathcal{H}_0, \\ \mathcal{H}_0 &= P_1(0)\mathcal{H} \oplus P_2(0)\mathcal{H} = \mathcal{H}_1^0 \oplus \mathcal{H}_2^0, \\ \mathcal{H}_t &= P_1(t)\mathcal{H} \oplus P_2(t)\mathcal{H} = \mathcal{H}_1^t \oplus \mathcal{H}_2^t, \\ U_{ij}^{-1}(t) : \mathcal{H}_j^t &\rightarrow \mathcal{H}_j^0, \quad i, j = 1, 2; \quad K(t) \in \mathcal{K}(t). \end{aligned}$$

By Lemma 1.1 all the bicones $C_t^-, t \in \mathbb{R}^+$, are convex and closed. Since they are evidently bounded, they are w.o.t.-compact. Hence using the property of $\dim P_2(t)$ (see the condition (a)) it is easy to check by letting $t \rightarrow \infty$ that C_∞^- is a bicone of rank d_- .

Now let us prove $C_\infty^- \subset \mathcal{N}_0$. Take $z \in C_\infty^-$. From (13) we obtain

$$2 \int_0^\infty \|y(t)\|^2 ds \leq -[z, z]_0.$$

This means that $y(t) = U(t)z \in \mathcal{N}$. So 1) is proved. Then setting $y_0 = y(\tau)$ in (12) and letting $t \rightarrow \infty$ we get (9). So 2) is proved.

Proof of Corollary 2.1. Let (11) hold. From (10)–(11) it follows that $[y_0, y_0] \leq 0$ for all $y_0 \in \mathcal{N}_0$. In view of 1) we hence obtain $\mathcal{N}_0 = C_\infty^-$ and the statement is proved.

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