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## A topological collapse number for all spaces

by

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**Abstract.** We here assign to each topological  $X$  a symbol  $C_T(X)$ , the collapse number of  $X$ , that may be a non-negative integer or  $\infty$ . In calculating  $C_T(X)$  we permit in a space  $Y$  with at least two points two possible operations at each stage. These are a pseudo-isotopy of  $Y$  to a compact set  $K$ , say, such that  $K$  is pointwise fixed throughout the deformation or one may remove a point from  $Y$  prior to performing the pseudo-isotopy. If  $X$  is an arbitrary space such that a finite number of such operations terminates in a point  $X$ , then  $X$  has a finite collapse number,  $C_T(X)$ , and this number is the least number of nonidentity pseudo-isotopies required to "shrink"  $X$  to a point. If  $X$  has but one point  $C_T(X) = 0$ , while all other spaces without a finite  $C_T(X)$  are given the collapse number  $\infty$ .

It is pointed out here that  $C_T(X)$  has been defined in a purely topological manner and that restriction of the above deformations could be made to the PL category  $C_{PL}(X)$  or the various differential ones. Further an analogous notion could be defined using homotopies with weaker restrictions.

**THEOREM 1.**  $C_T(X)$  is a topological invariant, but  $C_T(X)$  is not an invariant of simple homotopy type or homotopy type.

**Proof.** That  $C_T(X)$  is a topological invariant follows from its definition. The rest comes from the following observation. Both the closed 3-cell  $I^3$  and the dunce cap  $D$  [2] are of the same simple homotopy. One has  $C_T(I^3) = 1$ . Since there is no pseudo-isotopy shrinking  $D$  to a point, one must first remove a point of  $D$  to begin the collapsing. Regardless of the point  $p$  removed,  $D-p$  is no longer homologically trivial. Thus  $C_T(D) > 1$ .

**EXAMPLE 1.** Let  $X$  be the 1-point union of  $r$  circles ( $r \geq 2$ ) and let  $Y$  be the space got by attaching to a closed 2-cell  $r$  arcs in such a way that each arc meets the 2-cell at its endpoints in two fixed points of the boundary of the 2-cell, but are otherwise disjoint in pairs. Then  $X$  and  $Y$  are the same simple homotopy type. Upon removing from  $Y$  one of the two boundary fixed points, the resulting space shrinks to a point by pseudo-isotopy and  $C_T(Y) = 1$ . Now  $C_T(X) = r$ .

\* Reference [2] could as well be K. Borsuk, *Über das Phänomen der Unzerlegbarkeit in der Polyeden Topologie*, Comm. Math. Helv. 8 (1935), pp. 142-148.

**THEOREM 2.** *Let  $M^2$  be a closed 2-manifold. Then  $C_T(M^2) \leq 2$ .*

**Proof.** Upon removing a point from  $M^2$  one can pseudo-isotop the resulting space to a copy of  $Y$  in Example 1. Hence  $C_T(M^2) \leq 2$ .

**COROLLARY.** *The 2-sphere is characterized among closed 2-manifolds by having collapse number 1.*

The corollary to Theorem 2 generalizes in all dimensions.

**THEOREM 3.** *Let  $M^n$  be a closed  $n$ -manifold. Then  $M^n$  is an  $n$ -sphere if and only if  $C_T(M^n) = 1$ .*

**Proof.** Certainly  $C_T(S^n) = 1$ . Hence assume  $C_T(M^n) = 1$ . This means that  $M^n - p$  (for some point  $p$ ) shrinks by pseudo-isotopy to a point  $x$  in  $M^n - p$  with  $x$  fixed throughout the deformation. The given any compact set  $C$  in  $M^n - p$  and any  $\varepsilon > 0$  there is a stage in the pseudo-isotopy such that  $C$  is in the  $\varepsilon$ -neighborhood of  $x$ . If for  $C$  one selects the residual set in a standard decomposition it follows that  $C$  has a euclidean neighborhood in  $M^n$  and  $M^n$  is thus a sphere [1].

There is a matter not settled by Theorem 3 and it is the following. Is there an AR in  $E^3$  (topologically embedded) that will serve as a residual set for a counter-example to the Poincaré conjecture. A similar question may be asked in dimension 4.

**THEOREM 4.** *If  $K$  is a finite simplicial complex then if  $K$  is connected  $0 \leq C_T(K) < \infty$ .*

**Proof.** One notes that  $K$  can certainly be "shrunk" to a point by a finite number of removals of points from principal simplices of dimension at least two so that eventually a graph or point is obtained. If a graph results that is not a tree, either a point or tree may be got in a finite number of steps. Hence  $C_T(K)$  is finite.

**THEOREM 5.** *If  $X$  is a space with a finite number of components,  $\{C_i\}$ , while at least one component is not a point and has a finite collapse number, while all others have a finite collapse number, then  $X$  has a finite collapse number (and conversely).*

**Proof.** That infinitely many components are impossible is a matter of the definition of  $C_T(X)$ .

Thus it is sensible to consider only the category of connected spaces with a finite collapse number. There exist continua  $X$  with  $C_T(X) = 1$  while their euler characteristics are infinite. A simple example is the suspension of the sequence  $\{1/n\}$  plus its limit 0. Even for connected spaces path connectedness is not required. An example of this is the graph in  $E^2$  of  $f(x) = \sin(1/x)$  ( $0 < x < 1$ ) plus the point  $(0, 0)$ . For upon removal of  $(0, 0)$  from this space one has an open interval topologically. The original space has two path components. For an arbitrary connected space  $X$  with infinitely many path components  $C_T(X) = \infty$  for

if  $C_T(X)$  were finite our admissible operations would not permit collapsing in a finite number of steps. Thus it appears that the essential questions about spaces  $X$ ,  $C_T(X)$  finite, should be asked within the category of path connected spaces. A special case in this category is the subcategory  $S_1$  of those spaces for which  $C_T(X) = 1$ .

$S_1$  splits into two parts, that is, the contractible spaces and those spaces that become contractible upon removal of a single point. Here, of course, the contractibility must be achieved by a pseudo-isotopy. Furthermore, in the general case if  $C_T(X) < \infty$ , the last step in shrinking takes place in this category.

Thus let  $S_1$  be the category of spaces that contain at least two points and may be shrunk to a point by pseudo-isotopy with or without excision. If  $X$  is in  $S_1$  let  $w$  be a point not in  $X$  and assume  $Y$  is some space formed by annexing  $w$  to  $X$ . Regardless of the neighborhoods of  $w$  in  $Y$  we note that  $Y - w = X$  and  $C(Y) < \infty$ . There are cases in which the proper annexation of  $w$  to  $X$  above results in spaces  $Y$  that is topologically  $X$ . It is well known that this occurs in such a frequently used space as  $L^2$ . So it is not difficult in the language of categories to characterize those spaces with  $C_T(X) = 1$ .

Proceeding inductively, let  $S_2$  be those path connected spaces  $X$  for which  $C_T(X) = 2$ . If  $X$  is in  $S_2$ , the first pseudo-isotopy yields a space  $X_1$  in  $S_1$  where  $X_1$  must be compact. From the definition of  $C_T(X) < \infty$  one notes that the step of going from  $X$  to  $X_1$  by allowable moves is typical of the inductive process for  $C_T(X) = n \geq 2$ . If  $X$  is in  $S_n$ , then one obtains after one pseudo-isotopy an element  $X_{n-1}$  in  $S_{n-1}$  that is compact.

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