

(a) La droite  $L$  est une droite d'appui de  $\Gamma_1$ . En vertu de (2), on a  $L\Gamma_1 = \Gamma(L\cap E) = \Gamma(L\cap E)$ , et, puisque  $L\Gamma_1 = \{x\}$ , on voit que  $L\cap E = \{x\}$ .

(b) La droite  $L$  divise le domaine  $\Gamma_1$ . Comme  $L\Gamma_1 = \{x\}$ , l'ensemble convexe  $\Gamma_1$  est dans ce cas un segment rectiligne, dont les extrémités  $a$  et  $b$  se trouvent dans  $\Pi$  aux côtés différents de  $L$ . Une parallèle  $L_1$  à  $L$ , menée par le point  $a$ , est alors droite d'appui de  $\Gamma_1$ , et, puisque  $L_1\Gamma_1 = \{a\}$ , on est ramené au cas précédent.

**6.** Toute direction singulière par rapport à  $E$  étant aussi, d'après 5, singulière par rapport à  $\Gamma(E)$ , il suffit d'établir notre théorème pour les domaines convexes.

Soit d'abord  $\Gamma$  un domaine convexe contenu dans un plan  $\Pi$ . Toute direction  $\lambda$  singulière par rapport à  $\Gamma$  est nécessairement celle d'un faisceau de droites de  $\Pi$ . Par conséquent, il existe, dans le plan  $\Pi$ , une droite d'appui  $L$  de  $\Gamma$  ayant la direction singulière  $\lambda$ . L'ensemble  $L\Gamma$ , n'étant pas vide, contient plus d'un point;  $L$  est, par suite, droite d'appui singulière de  $\Gamma$ . L'ensemble des directions singulières par rapport à  $\Gamma$  a donc une puissance au plus égale à la puissance de l'ensemble des droites d'appui singulières de  $\Gamma$ ; il est, par suite, tout au plus dénombrable.

Considérons enfin un domaine convexe  $\Gamma$  quelconque. Supposons que les droites  $L_1$  et  $L_2$  aient des directions différentes  $\lambda_1, \lambda_2$  singulières par rapport à  $\Gamma$ . Il existe alors un plan d'appui  $\Pi$  de  $\Gamma$  parallèle à  $L_1$  et  $L_2$ . Les directions  $\lambda_1, \lambda_2$  sont aussi singulières par rapport au domaine convexe  $\Pi\Gamma$ , donc, celui-ci n'est pas situé sur une droite;  $\Pi$  est, par suite, plan d'appui singulier de  $\Gamma$ . Nous constatons ainsi, que toute direction singulière par rapport à  $\Gamma$  (s'il y en a au moins deux) est direction singulière par rapport à un ensemble  $\Pi\Gamma$ , où  $\Pi$  est un plan d'appui singulier de  $\Gamma$ .

Mais l'ensemble des plans d'appui singuliers de  $\Gamma$  est tout au plus dénombrable; d'autre part, l'ensemble des directions singulières par rapport à un domaine convexe plan l'est aussi. Donc, l'ensemble des directions singulières par rapport à  $\Gamma$  est tout au plus dénombrable.

La démonstration est ainsi achevée. Il est à remarquer que le théorème s'étend sans difficulté à l'espace euclidien à  $n > 3$  dimensions.

### On the distinct sums of $\lambda$ -type transfinite series obtained by permuting the elements of a fixed $\lambda$ -type series.

By

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Sierpiński [1] has demonstrated: (1) that the number of distinct sums of all  $\omega$ -type transfinite series which are permutations of the elements of a fixed  $\omega$ -type series, is finite; and (2) that the sum of any  $\omega$ -type series which is a permutation of the elements of a fixed, non-decreasing  $\omega$ -type sequence, is independent of the permutation. The purpose of this note is to generalize those results. In particular we show: a) that for any  $\omega_q$ -type series  $\sum_{\xi < \omega_q} a_\xi$ , where  $\omega_q > \omega$  is a regular ordinal, the number of distinct sums of all the  $\omega_q$  series obtained by permuting the elements of  $\sum a_\xi$ , is equal to or smaller than

$$\aleph_q^{\aleph_q} = \sum_{\xi < \omega_q} \aleph_\xi^{\aleph_\xi};$$

and  $\beta$ ) that (2) is still true when  $\omega$  is replaced by  $\omega_q$ .

Let  $N(\sum_{\xi < \lambda} a_\xi)$  be the number of distinct sums of all the  $\lambda$ -type series obtained by permuting the elements of the series  $\sum a_\xi$ . Then

**Theorem 1.** If  $\omega_q, q > 0$ , is a regular ordinal, then  $N(\sum_{\xi < \omega_q} a_\xi) \leq \aleph_q^{\aleph_q}$ ;

furthermore, if  $\omega_q = \omega_{\alpha+1}$ , then there exists an  $\omega_q$  series,  $\sum a_\xi$ , such that  $N(\sum a_\xi) = \aleph_q$ .

**Proof.** An element,  $a_\xi$ , will be said to have property  $P$  [1], whenever

$$\overline{\{a_\xi, a_\xi \geq a_{\xi_0}, \xi \geq \xi_0\}} < \aleph_q.$$

By generalizing Sierpiński's argument we will show that the elements  $\{a_{\nu(\mu)}, \mu < \lambda$  which have property  $P$ , form a sequence of order type less than  $\omega_q$ . Assume the contrary, i. e., assume that  $\lambda = \omega_q$ . To  $a_{\nu(0)} = a_{\tau(0)}$  there corresponds a  $\nu^*(0)$  such that  $a_\xi < a_{\nu(0)}$  for  $\xi \geq \nu^*(0)$ . As  $\{a_{\nu(\xi)}\}$  is an  $\omega_q$  sequence there exists a  $\tau(1) \geq \nu^*(0)$  such

that  $a_{\tau(\xi)} < a_{\tau(0)}$  for  $\tau(\xi) \geq \tau(1)$ . By induction we can define an  $\omega$  sequence,  $\{a_{\tau(n)}\}$ , with  $a_{\tau(n)} < a_{\tau(n-1)}$ , a well known impossibility. Thus  $\lambda < \omega_\rho$ .

If  $\sum_{\xi < \omega_\rho} a_\xi = k_1 + \omega^\delta$ , then for some  $\rho_0$ ,

$$\sum_{\xi \geq \rho_0} a_\xi = \omega^\delta.$$

Let  $\{b_\xi\}_{\xi < \omega_\rho}$  be any permutation of the elements of  $\{a_\xi\}$ . As  $\omega_\rho$  is regular, we are able to repeat the procedure given in [1] and find a  $\theta_0$  so that

$$\sum_{\xi \geq \theta_0} b_\xi = \omega^\delta.$$

Thus the value of  $\sum_{\xi < \omega_\rho} b_\xi$  is determined by calculating the value of  $\sum_{\xi < \theta_0} b_\xi$ . For each  $\theta_0$  there are  $\aleph_{\theta_0}^{\bar{\theta}_0}$  different subsets of  $\{a_\xi\}$  of power  $\bar{\theta}_0[2]$ , and  $\bar{\theta}_0^{\bar{\theta}_0}$  permutations of the elements of each set. Hence

$$N(\sum_{\xi < \omega_\rho} a_\xi) \leq \sum_{\theta_0 < \omega_\rho} \aleph_{\theta_0}^{\bar{\theta}_0} \bar{\theta}_0^{\bar{\theta}_0} = \aleph_{\theta_0}^{\aleph_{\theta_0}^{\bar{\theta}_0}}.$$

Suppose  $\aleph_\rho = \aleph_{\rho+1}$ . Let  $a_\xi = \omega_{\rho+1}$  for  $\xi < \omega_\rho$ , and  $a_\xi = 1$  for  $\xi \geq \omega_\rho$ . Then  $N(\sum a_\xi) = \aleph_{\rho+1}$  and the theorem is proved.

**Theorem 2.** *If  $\omega_\rho$  is a regular ordinal and  $\{a_\xi\}_{\xi < \omega_\rho}$  is a non-decreasing transfinite sequence of ordinals, then  $N(\sum a_\xi) = 1$ .*

*Proof.* Let  $\omega_\rho$  be regular and  $\{a_\xi\}$  non-decreasing. For  $\{b_\xi\}_{\xi < \omega_\rho}$  a permutation of the elements of  $\{a_\xi\}$ , let  $b_{\tau(0)} = b_0 \geq a_0$  and suppose defined  $\{b_{\tau(\xi)}\}_{\xi < \theta < \omega_\rho}$ . Let  $\lambda_\theta$  be the smallest ordinal  $\lambda$ ,  $\lambda \geq \tau(\xi)$ ,  $\xi < \theta$ . Since  $\omega_\rho$  is regular, and since there are  $\aleph_\rho$  elements  $a_\mu$ ,  $a_\mu \geq a_\theta$ , we can find a  $b_{\tau(\theta)} \geq a_\theta$ , with  $\tau(\theta) \geq \lambda_\theta$ . Therefore

$$\sum a_\xi \leq \sum b_{\tau(\xi)} \leq \sum b_\xi.$$

A similar procedure yields  $\sum b_\xi \leq \sum a_\xi$ , so that the equality sign holds.

In conclusion we remark that if  $\lambda$  is a non-regular limit number, then there exists an increasing sequence  $\{a_\xi\}_{\xi < \lambda}$  and a permutation  $\{b_\xi\}_{\xi < \lambda}$  such that  $\sum a_\xi < \sum b_\xi$ .

**Bibliography.**

[1] W. Sierpiński, *Sur les séries infinies de nombres ordinaux*, Fund. Math. **36** (1949), p. 248-253.  
 [2] A. Tarski, *Sur les classes d'ensembles closes par rapport à certaines opérations élémentaires*, Fund. Math. **16** (1930), p. 181-304.

On models of axiomatic systems.

By

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This paper is devoted to a discussion of various notions of models which appear in the recent investigations of formal systems. The discussion will be applied to the study of the following problem: Given a formal system  $S$  based on an infinite number of axioms  $A_1, A_2, A_3, \dots$  is it possible to prove in  $S$  the consistency of the system based on a finite number  $A_1, A_2, \dots, A_n$  of these axioms?

**1. Notations and definitions.** We shall consider two systems  $S$  and  $s$  based on the functional calculus of the first order<sup>1)</sup>. We shall not describe these systems in detail but give only some definitions which will be required later.

System  $s$ . We assume that the following symbols occur among the primitive signs of  $s$ :

1. Variables:  $x_1, x_2, x_3, \dots, x, y, z, \dots$
2. Individual constants:  $f_1, \dots, f_\alpha$ .
3. Functors (i. e. symbols for functions from individuals to individuals):  $g_1, \dots, g_\beta$ . We denote by  $g_j$  the number of arguments of  $g_j$  ( $j=1, \dots, \beta$ ).
4. Predicates (i. e. symbols for relations):  $r_1, \dots, r_\gamma$ . We denote by  $r_i$  the number of arguments of  $r_i$  ( $i=1, \dots, \gamma$ ).
5. Propositional connectives and quantifiers. We use the symbol  $|$  for the "stroke function" and define other connectives in terms of the stroke. Quantifiers are denoted by symbols  $(\exists x_i)$  and  $(x_i)$ .

Among expressions which can be constructed from these signs we distinguish the following:

6. Terms. Variables and individual constants are terms. If  $T_1, \dots, T_{g_j}$  are terms, then so is  $g_j(T_1, \dots, T_{g_j})$ ,  $j=1, \dots, \beta$ .

Terms will be denoted by the letters  $T, T_1, T_2, \dots$

<sup>1)</sup> For the functional calculus of the first order see e. g. Church [1], Chapter II.