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# On bounded paradoxical subsets of the plane

by

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Abstract. We give a precise lower bound for the number of pieces required in a bounded paradoxical subset of the plane.

Intuitively, a subset X of a metric space is said to be paradoxical if it admits a partition  $X = A \cup B$  such that each of the sets A, B can be subdivided into finitely many pieces which can be reassembled via isometries to produce X; if A is subdivided into n pieces and B is subdivided into n pieces, the set X is said to be (m, n)-paradoxical.

The Sierpiński--Mazurkiewicz paradox is that there is a (1,1)-paradoxical subset of the plane [MS]. Hadwiger, Debrunner and Klee [HDK, p. 80] have shown that a bounded (m, n)-paradoxical subset of the plane must satisfy m+n>2. A bounded (1, 3)-paradoxical subset of the plane has recently been constructed by Just [J].

Our main purpose here is to show that there is no bounded (1,2)-paradoxical subset of the plane. This improves the result of Hadwiger, Debrunner and Klee, and renders optimal the recent construction of Just. We also construct here a bounded (2,2)-paradoxical subset of the plane.

DEFINITION 1. X is an (m, n)-paradoxical subset of the plane if X is nonempty, and there are subsets  $C_1, \ldots, C_m, D_1, \ldots, D_n$  of X and planar isometries  $G_1, \ldots, G_m, H_1, \ldots, H_n$ , such that  $P_1 = \{C_i\}$ ,  $P_2 = \{D_j\}$  and  $P_3 = \{G_i(C_i)\} \cup \{H_j(D_j)\}$  are each partitions of X.

DEFINITION 2. Let X be an (m, n)-paradoxical subset of the plane whose paradoxical decomposition is witnessed by subsets  $C_1, \ldots, C_m, D_1, \ldots, D_n$  and planar isometries  $G_1, \ldots, G_m, H_1, \ldots, H_n$ . Write  $\mathscr{C} = \{C_1, \ldots, C_m\}$ ,  $\mathscr{D} = \{D_1, \ldots, D_n\}$ ,  $\mathscr{G} = \{G_1, \ldots, G_m\}$ , and  $\mathscr{H} = \{H_1, \ldots, H_n\}$ . We define the associated directed graph  $\Gamma = \Gamma(\mathscr{C}, \mathscr{D}, \mathscr{G}, \mathscr{H})$  of the decomposition.  $\Gamma$  is an infinite directed graph with vertex set  $V(\Gamma) = X$ . The set of darts (i.e. directed edges) of  $\Gamma$  consists of all pairs  $(x, G_i(x))$  and  $(x, H_i(x))$ , where  $x \in C_i \cap D_i$ .

It is helpful, when drawing diagrams, to label each dart of  $\Gamma$  with the planar isometry that determined its second coordinate.

Observe that every x in  $V(\Gamma)$  has invalency 1 and outvalency 2.

LEMMA 1. Let  $\Gamma$  be an infinite directed graph with invalency 1 at each vertex, and suppose furthermore that  $\Gamma$  is connected. Then  $\Gamma$  contains at most one cycle.

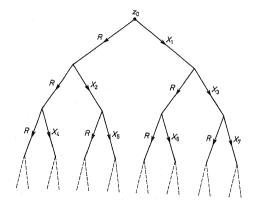
Proof. Easy.

THEOREM 1. There is no bounded (1,2)-paradoxical subset of the plane

Our proof is based on the method of Hadwiger, Debrunner and Klee [HDK, p. 80].

Proof. Suppose X is a (1,2)-paradoxical subset of the plane. Then there are subsets  $D_1$ ,  $D_2$  of X, and planar isometries R, F and G, such that  $P_1 = \{X\}$ ,  $P_2 = \{D_1, D_2\}$  and  $P_3 = \{R(X), F(D_1), G(D_2)\}$  are partitions of X. We show that X is not bounded.

Let  $\Gamma$  be the associated directed graph of this decomposition. If every component of  $\Gamma$  contains a cycle, let c be a vertex in some cycle, and choose  $z_0$  such that  $(c, z_0)$  is a dart of  $\Gamma$  not in the cycle. Otherwise, let  $z_0$  be any vertex of an acyclic component. Let  $\Delta$  be the smallest subgraph of  $\Gamma$  which contains the vertex  $z_0$  and every directed path which has initial vertex  $z_0$ . Then  $\Delta$  is acyclic by Lemma 1. The labelled subgraph  $\Delta$  is shown in the figure below, where each  $X_i \in \{F, G\}$ ,



Since  $R(z_0)$ ,  $R^2(z_0)$ ,  $R^3(z_0)$ , ... are the final vertices of distinct paths of  $\Delta$  (having initial vertex  $z_0$ ), they are all different. Therefore, R is not a reflection or a rotation of finite order.

Now suppose X is bounded, then so is the set  $\{R(z_0), R^2(z_0), R^3(z_0), \ldots\}$ . Therefore, R is not a translation or a glide reflection, so R must be a rotation of infinite order. Let O be the fixed point of R, and let D be the smallest closed disc with center O that contains all the vertices of  $\Delta$ .

Note that the entire boundary of D is contained in the topological closure of the vertex set of  $\Delta$ . (Since R has infinite order, each R-orbit is dense in a circle centered at O, so  $\operatorname{cl}(V(\Delta))$  is a union of circles centered at O. By the minimality of D, one such circle coincides with  $\partial D$  so  $\partial D \subset \operatorname{cl}(V(\Delta))$ .)

The proof now breaks into six essentially different cases.

Case 1.  $F(O) \neq O$  and  $G(O) \neq O$ . Clearly, the boundary of a disc of radius r cannot be covered by two discs also of radius r, unless at least one of the covering discs coincides with the covered disc. Thus  $F^{-1}(D) \cup G^{-1}(D)$  does not cover  $\partial D$ . Since

 $\partial D \subset \operatorname{cl}(V(\Delta))$ , there is a vertex v of  $\Delta$  not in  $F^{-1}(D) \cup G^{-1}(D)$ , but this contradicts the fact that one of the points F(v), G(v) is a vertex of  $\Delta$ .

Case 2.  $F(O) \neq O$  and G is a rotation fixing O. Since  $F^{-1}(D)$  does not cover  $\partial D$  and  $\partial D \subset \operatorname{cl}(V(\Delta))$ , there is a vertex v of  $\Delta$  not in  $F^{-1}(D)$ . Since the point F(v) is not a vertex of  $\Delta$ , the point G(v) is a vertex of  $\Delta$ . Let  $k \geq 1$ . Exactly one of the points  $FR^k(v)$ ,  $GR^k(v)$  is a vertex of  $\Delta$ . If  $GR^k(v) \in V(\Delta)$ , then  $GR^k(v)$  and  $R^kG(v)$  are the final vertices of different paths having initial vertex v, so they should be different. But  $GR^k$  and  $R^kG$  are equal as planar isometries. Hence  $GR^k(v)$  is not a vertex of  $\Delta$ . Therefore  $FR^k(v) \in V(\Delta)$ . This is true for all  $k \geq 1$ . But now we have

$$v \in \operatorname{cl}(\{R^k(v)\}_{k=1}^{\infty}) \subset \operatorname{cl}(F^{-1}(V(\Delta))) \subset \operatorname{cl}(F^{-1}(D)) = F^{-1}(D)$$

contradicting our choice of v.

Case 3.  $F(O) \neq O$  and G is a reflection fixing O. Since  $F^{-1}(D)$  does not cover  $\partial D$  and  $\partial D \subset \operatorname{cl}(V(\Delta))$ , there is a vertex v of  $\Delta$  not in  $F^{-1}(D)$ , and G(v) is a vertex of  $\Delta$  as in case 2. Let  $k \geq 1$ . Exactly one of the points  $FR^kG(v)$ ,  $GR^kG(v)$  is a vertex of  $\Delta$ . If  $GR^kG(v)$  is a vertex of  $\Delta$ , then so is  $R^kGR^kG(v)$ ;  $R^kGR^kG(v)$  is the final vertex of a path having initial vertex v and so should be different from v, but  $R^kGR^kG$  is equal to the identity as a planar isometry. Hence  $GR^kG(v)$  is not a vertex of  $\Delta$  so  $FR^kG(v)$  is. This is true for all  $k \geq 1$ , but now we have

$$v \in \operatorname{cl}\left(\left\{R^k G(v)\right\}_{k=1}^{\infty}\right) \subset \operatorname{cl}\left(F^{-1}\left(V(\varDelta)\right)\right) \subset \operatorname{cl}\left(F^{-1}(D)\right) = F^{-1}(D)$$

(since v and G(v) are equidistant from O), and this  $\Delta$  contradicts the choice of v.

Case 4. F and G are rotations fixing O. For some X, Y,  $Z \in \{F, G\}$ , the points  $R^2X(z_0)$ ,  $RYR(z_0)$  and  $ZR^2(z_0)$  are vertices of  $\Delta$ . These are the final vertices of three different paths having initial vertex  $z_0$ , so they should be all different, but at least two of the maps  $R^2X$ , RYR,  $ZR^2$  are equal as planar isometries.

Case 5. F and G are reflections fixing O. For some U, V, W, X, Y,  $Z \in \{F, G\}$ , the points  $R^2UV(z_0)$ ,  $RWXR(z_0)$ ,  $YZR^2(z_0)$ , and  $R^2(z_0)$  are vertices of  $\Delta$ , and should be all different. If U = V, then  $R^2UV = R^2$ , so we must have  $U \neq V$  and similarly  $W \neq X$ ,  $Y \neq Z$ . Thus the three rotations UV, WX, YZ must lie in the set  $\{FG, GF\}$ . So at least two of the maps  $R^2UV$ , RWXR,  $YZR^2$  are equal.

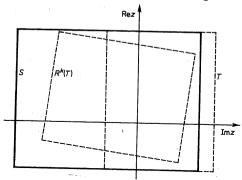
Case 6. F is a rotation fixing O and G is a reflection fixing O. For some U, V, W, X, Y,  $Z \in \{F, G\}$ , the points  $R^2VU(z_0)$ ,  $RWRU(z_0)$ ,  $RU(z_0)$ ,  $XR(z_0)$ ,  $RYXR(z_0)$ ,  $ZRXR(z_0)$ , and  $R^2(z_0)$  are vertices of  $\Delta$ . These points and  $z_0$  should be all different. If U = G, then V = F (otherwise  $R^2VU = R^2$ ) and W = F (otherwise RWRU is the identity), but then  $R^2VU = RWRU$ . If U = F then X = G (otherwise RU = XR), so Y = F (otherwise  $RYXR = R^2$ ) and Z = F (otherwise ZRXR is the identity), but then RYXR = ZRXR.

THEOREM 2. There is a bounded (2,2)-paradoxical subset X of the plane.

Proof. We define the planar isometries R and F, and a subset E of C, exactly as in [MS]:  $R(z) = e^i z$ , F(z) = z + 1 and E consists of the point O together with all the images of O under the action of the semigroup generated by R and F.

The (2, 2)-paradoxical subset X will be contained in E and also in the rectangular subset S = [-8, 4] + i [-3, 6] of the complex plane.

Let T = [-2, 5] + i[-3, 6]. Fix k > 0 such that  $R^k(T) \subset S$ . The rotation  $R^k$  is then approximately a quarter turn counter-clockwise. See the figure below.



Let P = [-8, -2] + i [-3, 6], and let Q = (-2, 4] + i [-3, 6]. Then  $\{P, Q\}$  is a partition of S. Note that Q, Q+1, P+6 and P+7 are all subsets of T, so since  $R^k(T) \subset S$ , it follows that  $R^k(Q)$ ,  $R^kF(Q)$ ,  $R^kF^6(P)$  and  $R^kF^7(P)$  are all subsets of S. We define  $X = \bigcup_{n=0}^{\infty} X_n$  as follows.

Let  $X_0 = \{0\}$ ,  $X_1 = \{R^k F(0)\}$ . Define  $X_2$ ,  $X_3$ , ... inductively. Suppose  $n \ge 1$ , and we have defined  $X_n$ . For each point z in  $X_n$ , assume inductively that  $z \in S = P \cup Q$ . If  $z \in P$ , put  $R^k F^6(z)$  and  $R^k F^7(z)$  into  $X_{n+1}$ .

If  $z \in Q$ , put  $R^k(z)$  and  $R^kF(z)$  into  $X_{n+1}$ .

This completes the definition of X. To show that X is (2, 2)-paradoxical we argue that  $P_1 = P_2 = \{X \cap P, X \cap Q\}$  and  $P_3 = \{R^k F^6(X \cap P), R^k(X \cap Q), R^k F^7(X \cap P), R^k F^7(X \cap P)\}$  are partitions of X.  $P_1 = P_2$  is clearly a partition of X. It is clear from the construction that  $X = \bigcup P_3$  so it remains to show that  $P_3$  is disjoint. Since  $e^i$  is transcendental, each point x in E other than 0 has a unique representation  $E_1 = E_2$ . Then  $E_2 = E_3 = E_3$  is the suppose  $E_3 = E_3 = E_3$ . Then  $E_3 = E_3 = E_3$  is the suppose  $E_3 = E_3 = E_3$ . Then  $E_3 = E_3 = E_3$  is the suppose  $E_3 = E_3$  in  $E_$ 

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