

*REPRESENTING IDEMPOTENTS AS A SUM OF TWO
NILPOTENTS—AN APPROACH VIA MATRICES
OVER DIVISION RINGS*

BY

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1. Introduction. It was proved in [3] that the Koethe conjecture is equivalent to the problem of determining whether a ring which is a sum of a nil subring and a nilpotent subring must be nil. A similar problem, whether a ring that is a sum of two locally nilpotent subrings must be nil, has a negative solution (see [8]). A simpler example of this type was then constructed in [11]. Therefore one may ask whether such a ring can contain a nonzero idempotent. This naturally leads to the following problem investigated in [4]: can a nonzero idempotent e be represented as a sum $e = x + y$ of two nilpotent elements x, y ? It was proved there that this is impossible if the nilpotency degrees of x and y are ≤ 3 and ≤ 5 respectively (or ≤ 2 and any $n \in \mathbb{N}$) provided that the characteristic is equal to zero. If the characteristic is positive, examples of this type are easy to find (see [4]), whence in this paper we restrict our attention to algebras over a field of characteristic zero.

We show that idempotents of such type exist if the nilpotency degrees of x, y are both 4, or 3 and 6 respectively. This is done by investigating representations in matrices over division rings. In this context, the first Weyl algebra appears unexpectedly and unavoidably, as shown by our main results: Theorems 8 and 12. In particular, we prove that $M_4(D)$ contains a nonzero idempotent with zero diagonal if and only if D contains a copy of the first Weyl algebra.

It was shown in [4] that the identity element may be represented as a sum of four nilpotent elements of nilpotency degree 2. We prove that the identity element can also be a sum of three nilpotent elements of nilpotency degree 3. This is used to construct an example with $0 \neq e = e^2 = x + y$ and $x^3 = y^6 = 0$.

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Finally, we give an application to a problem closely connected to Kegel's theorem asserting that a ring which is a sum of two nilpotent subrings must be nilpotent (see [6, 7]).

It might seem possible that the diamond lemma (see [1]) can be applied to construct examples of the above types; however, it leads to very complex computations, which are not conclusive.

Throughout the paper D (K respectively) denotes a skew field (resp. a field) of characteristic zero. All spaces will be left spaces over D (resp. K). We denote by v_1, \dots, v_n the standard basis of D^n ; $M_n(D) = \text{End}_D(D^n)$ stands for the ring of $n \times n$ matrices over D , and I for the identity element of $M_n(D)$. The mappings $\pi_i \in \text{End}_D(D^n)$ ($1 \leq i \leq n$) are defined by $\pi_i(v_i) = 0$ and $\pi_i(v_j) = v_j$ for $i \neq j$. If A is a K -algebra, then $\text{GKdim}(A)$ and $\mathcal{J}(A)$ denote the Gelfand–Kirillov dimension and the Jacobson radical of A respectively.

2. Idempotents with zero diagonal in $M_4(D)$. As explained above, our approach to the problem proposed in [4] is based on matrix algebras $M_n(D)$. Their multiplicative structure was investigated in [10]. We describe all idempotents with zero diagonal in $M_4(D)$; clearly such an element is a sum of two nilpotents. If $n < 4$, then $M_n(D)$ does not contain such idempotents. A similar problem for $M_n(D)$, $n \geq 5$, seems to be difficult. First we need some preparatory results.

LEMMA 1. *Let V be a linear space over D . Assume that $W_1 \subseteq \dots \subseteq W_n = V$ and $Z_1 \subseteq \dots \subseteq Z_m = V$ are chains of subspaces of V . Then we can find subspaces $Y_{i,j}$ of V such that $W_i \cap Z_j = \bigoplus_{k \leq i, l \leq j} Y_{k,l}$ for all $i = 1, \dots, n$, $j = 1, \dots, m$.*

Proof. Choose subspaces $Y_{i,j}$ satisfying

$$(1) \quad Y_{i,j} \oplus (W_i \cap Z_{j-1} + W_{i-1} \cap Z_j) = W_i \cap Z_j$$

where $W_0 = Z_0 = 0$. Consider the order on the set of all pairs (i, j) defined by:

$$(i, j) \leq (i', j') \quad \text{if and only if} \quad i \leq i' \quad \text{and} \quad j \leq j'.$$

By induction we prove that $W_i \cap Z_j = \bigoplus_{k \leq i, l \leq j} Y_{k,l}$. By the induction hypothesis we get

$$(2) \quad W_i \cap Z_{j-1} = \bigoplus_{r \leq i, s \leq j-1} Y_{r,s},$$

$$(3) \quad W_{i-1} \cap Z_j = \bigoplus_{p \leq i-1, q \leq j} Y_{p,q}.$$

Hence

$$\begin{aligned} W_i \cap Z_j &= Y_{i,j} \oplus (W_i \cap Z_{j-1} + W_{i-1} \cap Z_j) \\ &= Y_{i,j} \oplus \left(\bigoplus_{r \leq i, s \leq j-1} Y_{r,s} + \bigoplus_{p \leq i-1, q \leq j} Y_{p,q} \right) = \sum_{r \leq i, s \leq j} Y_{r,s}. \end{aligned}$$

Now we prove that this sum is direct. Let $y_{r,s} \in Y_{r,s}$, where $r \leq i$ and $s \leq j$, be such that $\sum_{r \leq i, s \leq j} y_{r,s} = 0$. By (1), $y_{i,j} = 0$, hence

$$\sum_{r \leq i, s \leq j-1} y_{r,s} = - \sum_{k \leq i-1} y_{k,j} \in (W_i \cap Z_{j-1}) \cap (W_{i-1} \cap Z_j) = W_{i-1} \cap Z_{j-1}.$$

This implies

$$- \sum_{k \leq i-1} y_{k,j} = \sum_{p \leq i-1, q \leq j-1} \bar{y}_{p,q} \quad \text{for some } \bar{y}_{p,q} \in Y_{p,q}.$$

By (3) we get $y_{k,j} = 0$ for $k \leq i-1$. Hence

$$\sum_{r \leq i, s \leq j-1} y_{r,s} = - \sum_{k \leq i-1} y_{k,j} = 0.$$

By (2), $y_{r,s} = 0$ for $r \leq i$ and $s \leq j-1$. So we have proved that $y_{r,s} = 0$ for all r, s . ■

LEMMA 2. *An element $e \in M_n(D)$ is a sum of two nilpotent elements if and only if e has zero diagonal in some basis of D^n .*

Proof. Assume that $e = x + y$ where $x^n = y^n = 0$. Define $W_i = \text{Ker}(x^i)$ and $Z_j = \text{Ker}(y^j)$, $1 \leq i, j \leq n$. Choose subspaces $Y_{i,j}$ as in Lemma 1 and take a basis which is the union of some bases of all nonzero $Y_{i,j}$. It is easy to see that e has zero diagonal in this basis.

Conversely, assume that the diagonal of e is zero. Then e can be represented as a sum of a strictly upper triangular and a strictly lower triangular matrices, which are clearly nilpotent. ■

LEMMA 3. *Every idempotent e of rank 1 in $M_n(D)$ has a nonzero diagonal.*

Proof. Suppose that e is an idempotent of rank 1 with zero diagonal. Changing the order of v_1, \dots, v_n we can assume that $v_1, \dots, v_k \in \text{Ker}(e)$, $v_{k+1}, \dots, v_n \notin \text{Ker}(e)$ for some $1 \leq k \leq n$. Let $\text{Im}(e) = \text{Lin}_D(v)$ for some $v \in D^n$. By the assumption $e(v_j) \in \text{Lin}_D\{v_l : l \neq j\}$ for $j > k$, hence $v \in \text{Lin}_D\{v_l : l \neq j\}$. Clearly $\bigcap_{j > k} \text{Lin}_D\{v_l : l \neq j\} = \text{Lin}_D(v_1, \dots, v_k)$. This implies that $\text{Im}(e) = \text{Lin}_D(v) \subseteq \text{Lin}_D(v_1, \dots, v_k) \subseteq \text{Ker}(e)$, a contradiction. ■

LEMMA 4. *Assume that $n > 1$. Then every idempotent of rank $n-1$ in $M_n(D)$ has a nonzero diagonal.*

Proof. Let $e = e^2 \in M_n(D)$ be an idempotent of rank $n - 1$. Suppose e has zero diagonal. Let $f = I - e$ and $\text{Im}(f) = \text{Lin}_D(v)$ for some $v \in D^4$. Then $f(v_i) = \alpha_i v$ for some $\alpha_i \in D$ and $f(v_i) = v_i + w_i$ for some $w_i \in \text{Lin}_D\{v_j : j \neq i\}$ by the assumptions on e . This implies that $v = \sum_i \alpha_i^{-1} v_i$ ($\alpha_i \neq 0$ in particular) and $f(v_i) = \alpha_i \sum_j \alpha_j^{-1} v_j$. Hence

$$\begin{aligned} f(v_i) &= f(f(v_i)) = f\left(\alpha_i \sum_j \alpha_j^{-1} v_j\right) = \sum_j \alpha_i \alpha_j^{-1} f(v_j) \\ &= \sum_j \alpha_i \alpha_j^{-1} \alpha_j v = n f(v_i). \end{aligned}$$

So $f(v_i) = 0$ and $f = 0$, a contradiction. ■

LEMMA 5. *Assume that $e \in M_n(D)$ is an idempotent and $e(v_i) \neq 0$ for some $i \in \{1, \dots, n\}$. Then $\pi_i(\text{Ker}(e)) \cap \text{Im}(e) \neq 0$ if and only if $e(v_i) \in \text{Lin}_D\{v_j : j \neq i\}$.*

Proof. (\Rightarrow) Assume that $\pi_i(v) = e(w) \neq 0$ and $e(v) = 0$ for some $v, w \in D^n$. Let $v = \alpha v_i + \pi_i(v)$ for some $\alpha \in D$. Then $0 = e(v) = \alpha e(v_i) + e(\pi_i(v))$. Hence $-\alpha e(v_i) = e(\pi_i(v)) = e(e(w)) = e(w) = \pi_i(v)$. If $\alpha = 0$, then $v = \pi_i(v) = e(w)$. Hence $0 = e(v) = e^2(w) = e(w)$, a contradiction. So $\alpha \neq 0$ and $e(v_i) = -\alpha^{-1} \pi_i(v) \in \text{Lin}_D\{v_j : j \neq i\}$.

(\Leftarrow) Assume that $e(v_i) \in \text{Lin}_D\{v_j : j \neq i\}$. We claim that

$$[\text{Ker}(e) + \text{Lin}_D(v_i)] \cap \text{Im}(e) \subseteq \pi_i(\text{Ker}(e)) \cap \text{Im}(e).$$

Any vector of $[\text{Ker}(e) + \text{Lin}_D(v_i)] \cap \text{Im}(e)$ can be written in the form $v + \alpha v_i = e(w)$, where $v, w \in D^n$, $e(v) = 0$ and $\alpha \in D$. Then $\pi_i(v) + \alpha \pi_i(v_i) = \pi_i(e(w))$. Hence

$$\begin{aligned} \pi_i(v) &= \pi_i(e(e(w))) = \pi_i(e(v + \alpha v_i)) = \pi_i(e(\alpha v_i)) \\ &= \alpha \pi_i(e(v_i)) = \alpha e(v_i) = e(e(w) - v) = e(w). \end{aligned}$$

This shows that $e(w) = \pi_i(v) \in \pi_i(\text{Ker}(e)) \cap \text{Im}(e)$, proving the claim.

Since $e(v_i) \neq 0$, we get $[\text{Ker}(e) + \text{Lin}_D(v_i)] \cap \text{Im}(e) \neq 0$. Hence $\pi_i(\text{Ker}(e)) \cap \text{Im}(e) \neq 0$, as desired. ■

LEMMA 6. *Let $e \in M_4(D)$ be an idempotent of rank 2 with zero diagonal. Then $\text{Ker}(e) \cap \text{Lin}_D(v_i, v_j) = 0$ for any $i \neq j$, $i, j \in \{1, 2, 3, 4\}$.*

Proof. First suppose that there exist $\alpha, \beta \in D \setminus \{0\}$ such that $\alpha v_i + \beta v_j \in \text{Ker}(e)$. Hence $\alpha e(v_i) + \beta e(v_j) = 0$. Since e has zero diagonal, $e(v_i), e(v_j) \in \text{Lin}_D(v_k, v_l)$ whenever $\{i, j, k, l\} = \{1, 2, 3, 4\}$. Hence the diagonal of e is zero in the basis $\alpha v_i + \beta v_j, v_j, v_k, v_l$. Let $\bar{\cdot} : D^4 \rightarrow D^4 / \text{Lin}_D(\alpha v_i + \beta v_j)$ denote the quotient map and $\bar{e} \in \text{End}_D(D^4 / \text{Lin}_D(\alpha v_i + \beta v_j))$ be defined by $\bar{e}(\bar{v}) = \overline{e(v)}$. Then \bar{e} is an idempotent of rank 2 (in $M_3(D)$) with zero diagonal in the basis $\bar{v}_j, \bar{v}_k, \bar{v}_l$. This contradicts Lemma 4.

It remains to consider the case when $v_i \in \text{Ker}(e)$ or $v_j \in \text{Ker}(e)$. Let for example $v_i \in \text{Ker}(e)$. Then considering $\bar{\cdot} : D^4 \rightarrow D^4 / \text{Lin}_D(v_i)$ and \bar{e} we get a contradiction as above. ■

LEMMA 7. *Let $V, W \subseteq D^4$ be subspaces such that $\dim V = \dim W = 2$ and $V \cap \text{Lin}_D(v_i, v_j) = 0$ for all $i \neq j$. If $\pi_i(V) \cap W \neq 0$ for all i , then $V = W$ or $V \cap W = 0$.*

PROOF. Suppose that $V \cap W \neq 0$ and $V \neq W$. Fix some i . We claim that either $V \cap W \subseteq \text{Lin}_D\{v_j : j \neq i\}$ or $W \subseteq \text{Lin}_D(v_i) + V$.

Assume that $W \not\subseteq \text{Lin}_D(v_i) + V$. Since $\dim(\text{Lin}_D(v_i) + V) = 3$ and $\dim W = 2$ by hypothesis, $(\text{Lin}_D(v_i) + V) \cap W \neq 0$. Hence $\dim(\text{Lin}_D(v_i) + V) \cap W = 1$. Since $\pi_i(V) \subseteq \text{Lin}_D(v_i) + V$, we have $0 \neq \pi_i(V) \cap W \subseteq (\text{Lin}_D(v_i) + V) \cap W$. Therefore $(\text{Lin}_D(v_i) + V) \cap W = \pi_i(V) \cap W$. Similarly $0 \neq V \cap W \subseteq (\text{Lin}_D(v_i) + V) \cap W$ yields $V \cap W = (\text{Lin}_D(v_i) + V) \cap W$. This implies $V \cap W = \pi_i(V) \cap W \subseteq \text{Lin}_D\{v_j : j \neq i\}$, proving the claim.

If $W \subseteq \text{Lin}_D(v_i) + V$ and $W \subseteq \text{Lin}_D(v_j) + V$ for some $i \neq j$ then $V + W \subseteq (\text{Lin}_D(v_i) + V) \cap (\text{Lin}_D(v_j) + V)$. Since $\dim(V + W) = 3$, we get equality and so $\text{Lin}_D(v_i) + V = \text{Lin}_D(v_j) + V$. This contradicts the fact that $V \cap \text{Lin}_D(v_i, v_j) = 0$. So by the initial remark $V \cap W \subseteq \text{Lin}_D\{v_j : j \neq i\}$ for at least three values of i .

If this inclusion holds for $i = 1, 2, 3, 4$ we get $V \cap W = 0$, a contradiction. So it holds for exactly three values of i . This implies $V \cap W = \text{Lin}_D(v_i)$ for some i . Since $v_i \in V$, we get $\dim \pi_i(V) = 1$. As $\pi_i(V) \cap W \neq 0$ we have $\pi_i(V) \subseteq W$. Clearly $\pi_i(V) \subseteq \text{Lin}_D(v_i) + V = V$. This yields $\text{Lin}_D(v_i) + \pi_i(V) \subseteq V \cap W$. Since $\dim(\text{Lin}_D(v_i) + \pi_i(V)) = 2$, we conclude that $V = W$, a contradiction. ■

REMARK. It may be proved that if V, W are subspaces of D^4 , $\dim V = \dim W = 2$ and $\pi_i(V) \cap W \neq 0$ for all i , then either $V = W$ or $V \cap W = 0$ or $0 \neq V \cap W \subseteq \text{Lin}_D(v_i, v_j)$ for some $i \neq j$ or $V + W \subseteq \text{Lin}_D(v_i, v_j, v_k)$ for some distinct i, j, k . Moreover, if the first, third or fourth possibility holds, then $\pi_i(V) \cap W \neq 0$ for all i .

Denote by $A_1 = K\langle x, y : xy - yx = 1 \rangle$ the first Weyl algebra over K . It is well known that A_1 is a simple domain which has two-sided Ore fractions (see [9]). Hence the division ring D contains an isomorphic copy of $A_1 A_1^{-1}$ if and only if D contains two elements x and y satisfying $xy - yx = 1$. We are now ready to prove our first main result.

THEOREM 8. *Let D be a division ring of characteristic zero. Then there exists a nonzero idempotent $e \in M_4(D)$ which is a sum of two nilpotent elements if and only if D contains a copy of $A_1 A_1^{-1}$.*

PROOF. By Lemma 2, $e^2 = e$ is a sum of two nilpotent elements if and only if e has zero diagonal in some basis. We can assume that v_1, v_2, v_3, v_4 is the appropriate basis. Our assertion may be reformulated as follows:

There exists a nonzero idempotent with zero diagonal in $M_4(D)$ if and only if there exist two-dimensional subspaces $V, W \subseteq D^4$ such that $V \cap \text{Lin}_D(v_i, v_j) = 0$ for $i \neq j$, $\pi_i(V) \cap W \neq 0$ for all i and $V \neq W$.

Indeed, if e is a nonzero idempotent with zero diagonal, then by Lemmas 3 and 4, $\text{rank}(e) = 2$. Put $V = \text{Ker}(e)$ and $W = \text{Im}(e)$. Then by Lemma 6, $V \cap \text{Lin}_D(v_i, v_j) = 0$ for $i \neq j$. By Lemma 5(\Leftarrow), $\pi_i(V) \cap W \neq 0$. Conversely, if V and W are subspaces satisfying the above conditions then by Lemma 7, $V \cap W = 0$. Define the idempotent e by $\text{Ker}(e) = V$ and $\text{Im}(e) = W$ ($V \oplus W = D^4$). Then by Lemma 5(\Rightarrow), e has zero diagonal.

Assume that subspaces V, W are given. Then $V \not\subseteq \bigcup_i \text{Lin}_D\{v_j : j \neq i\}$. Indeed, otherwise $V \subseteq \text{Lin}_D\{v_j : j \neq i\}$ for some i , leading to $V \cap \text{Lin}_D(v_k, v_l) \neq 0$ for some $k \neq l$ and contradicting the assumption on V . Hence we can find a vector $\alpha'_1 v_1 + \dots + \alpha'_4 v_4 \in V$ with $\alpha'_1, \dots, \alpha'_4 \in D \setminus \{0\}$. Replacing the basis v_1, \dots, v_4 by $\alpha'_1 v_1, \dots, \alpha'_4 v_4$ we can assume that $v_1 + \dots + v_4 \in V$. Hence $V = \text{Lin}_D(v_1 + \dots + v_4, \alpha_1 v_1 + \dots + \alpha_4 v_4)$ for some $\alpha_i \in D$. In this situation the condition $V \cap \text{Lin}_D(v_i, v_j) = 0$ ($i \neq j$) is equivalent to $\alpha_i \neq \alpha_j$ for $i \neq j$.

Assume now that V is given and we try to find a subspace W such that $\dim W = 2$ and $\pi_i(V) \cap W \neq 0$ for all i . Note first that $\pi_i(V) \cap \pi_j(V) = 0$ for $i \neq j$. Indeed, let for example $i = 1$ and $j = 2$. Take $w \in \pi_1(V) \cap \pi_2(V)$. Then $w = \pi_1(z_1) = \pi_2(z_2) \in \text{Lin}_D(v_3, v_4)$ for some $z_1, z_2 \in V$. Moreover, $z_1 = \alpha v_1 + w$, $z_2 = \beta v_2 + w$ for some $\alpha, \beta \in D$. This gives $z_1 - z_2 \in \text{Lin}_D(v_1, v_2) \cap V = 0$. Hence $\alpha = \beta = 0$ and $z_1 = w \in V \cap \text{Lin}_D(v_3, v_4) = 0$. This proves the desired claim.

Let $w_i = p_i(\sum_{j \neq i} v_j) + q_i(\sum_{j \neq i} \alpha_j v_j) \in \pi_i(V) \cap W \setminus \{0\}$ for some $p_i, q_i \in D$, $i = 1, \dots, 4$. Then, by the last paragraph, w_i, w_j are linearly independent for any $i \neq j$. Since $w_i \in \pi_i(V)$, existence of a subspace W with the desired properties is equivalent to $\dim \text{Lin}_D\{w_i : i = 1, \dots, 4\} = 2$. The latter is equivalent to $w_3 = r w_1 + s w_2$, $w_4 = t w_1 + u w_2$ for some $r, s, t, u \in D$ (of course $r, s, t, u \neq 0$). By the definition of w_i this can be written as

$$(4) \quad \begin{cases} p_3 + q_3 \alpha_1 = s p_1 + s q_1 \alpha_1, \\ p_3 + q_3 \alpha_2 = r p_1 + r q_1 \alpha_2, \\ 0 = r p_1 + r q_1 \alpha_3 + s p_2 + s q_2 \alpha_3, \\ p_3 + q_3 \alpha_4 = r p_1 + r q_1 \alpha_4 + s p_2 + s q_2 \alpha_4, \\ p_4 + q_4 \alpha_1 = u p_2 + u q_2 \alpha_1, \\ p_4 + q_4 \alpha_2 = t p_1 + t q_1 \alpha_2, \\ p_4 + q_4 \alpha_3 = t p_1 + t q_1 \alpha_3 + u p_2 + u q_2 \alpha_3, \\ 0 = t p_1 + t q_1 \alpha_4 + u p_2 + u q_2 \alpha_4. \end{cases}$$

Now we prove that the condition $w_1, \dots, w_4 \neq 0$ can be replaced by $w_1 \neq 0$, or equivalently $(p_1, q_1) \neq (0, 0)$. Assume that $w_1 \neq 0$. If $w_2 = 0$ then $w_3 = rw_1 \neq 0$. Since $\pi_1(V) \cap \pi_3(V) \neq 0$, w_1 and w_3 are linearly independent, and we get a contradiction. Hence $w_1, w_2 \neq 0$ and w_1, w_2 are linearly independent. This implies that $w_3 = rw_1 + sw_2 \neq 0$ and $w_4 = tw_1 + uw_2 \neq 0$.

So our problem is reduced to solving (4) under the assumptions: $\alpha_i \neq \alpha_j$ for $i \neq j$, $r, s, t, u \neq 0$, $(p_1, q_1) \neq (0, 0)$ and the solution corresponds to $V \neq W$.

First assume that such a solution is given. We prove that $D \supseteq A_1 A_1^{-1}$. From the first and fifth equations of (4) we get $p_3 = sp_2 + sq_2\alpha_1 - q_3\alpha_1$ and $p_4 = up_2 + uq_2\alpha_1 - q_4\alpha_1$. Now we can eliminate p_3 and p_4 from (4) passing to

$$\begin{cases} q_3\alpha_1 + rp_1 + rq_1\alpha_2 = q_3\alpha_2 + sp_2 + sq_2\alpha_1, \\ 0 = rp_1 + rq_1\alpha_3 + sp_2 + sq_2\alpha_3, \\ sp_2 + sq_2\alpha_1 - q_3\alpha_1 + q_3\alpha_4 = rp_1 + rq_1\alpha_4 + sp_2 + sq_2\alpha_4, \\ q_4\alpha_1 + tp_1 + tq_1\alpha_2 = q_4\alpha_2 + up_2 + uq_2\alpha_1, \\ up_2 + uq_2\alpha_1 - q_4\alpha_1 + q_4\alpha_3 = tp_1 + tq_1\alpha_3 + up_2 + uq_2\alpha_3, \\ 0 = tp_1 + tq_1\alpha_4 + up_2 + uq_2\alpha_4. \end{cases}$$

By the first and fourth equations we have

$$(5) \quad \begin{cases} q_3 = (sp_2 - rp_1 + sq_2\alpha_1 - rq_1\alpha_2)(\alpha_1 - \alpha_2)^{-1}, \\ q_4 = (up_2 - tp_1 + uq_2\alpha_1 - tq_1\alpha_2)(\alpha_1 - \alpha_2)^{-1}. \end{cases}$$

So q_3 and q_4 may be eliminated:

$$\begin{cases} 0 = rp_1 + rq_1\alpha_3 + sp_2 + sq_2\alpha_3, \\ sp_2 + sq_2\alpha_1 + (sp_2 - rp_1 + sq_2\alpha_1 - rq_1\alpha_2)(\alpha_1 - \alpha_2)^{-1}(\alpha_4 - \alpha_1) \\ = rp_1 + rq_1\alpha_4 + sp_2 + sq_2\alpha_4, \\ up_2 + uq_2\alpha_1 + (up_2 - tp_1 + uq_2\alpha_1 - tq_1\alpha_2)(\alpha_1 - \alpha_2)^{-1}(\alpha_3 - \alpha_1) \\ = tp_1 + tq_1\alpha_3 + up_2 + uq_2\alpha_3, \\ 0 = tp_1 + tq_1\alpha_4 + up_2 + uq_2\alpha_4. \end{cases}$$

Multiplying the first and second (resp. third and fourth) equations on the left by s^{-1} (resp. u^{-1}) we can take $s^{-1}r$ to be “new s ” (resp. $u^{-1}t$ to be “new t ”) and hence we can assume that $s = u = 1$. From the first and fourth equations we obtain $p_2 = -(rp_1 + rq_1\alpha_3 + q_2\alpha_3) = -(tp_1 + tq_1\alpha_4 + q_2\alpha_4)$. So p_2 can be eliminated:

$$\begin{cases} rp_1 + rq_1\alpha_3 + q_2\alpha_3 = tp_1 + tq_1\alpha_4 + q_2\alpha_4, \\ q_2\alpha_1 + (-rp_1 - rq_1\alpha_3 - q_2\alpha_3 - rp_1 + q_2\alpha_1 - rq_1\alpha_2)(\alpha_1 - \alpha_2)^{-1}(\alpha_4 - \alpha_1) \\ = rp_1 + rq_1\alpha_4 + q_2\alpha_4, \\ q_2\alpha_1 + (-tp_1 - tq_1\alpha_4 - q_2\alpha_4 - tp_1 + q_2\alpha_1 - tq_1\alpha_2)(\alpha_1 - \alpha_2)^{-1}(\alpha_3 - \alpha_1) \\ = tp_1 + tq_1\alpha_3 + q_2\alpha_3. \end{cases}$$

Define $A = (\alpha_1 - \alpha_2)^{-1}(\alpha_4 - \alpha_1)$ and $B = (\alpha_1 - \alpha_2)^{-1}(\alpha_3 - \alpha_1)$. Transforming the above equations we pass to

$$\begin{cases} rp_1 + rq_1\alpha_3 + q_2\alpha_3 = tp_1 + tq_1\alpha_4 + q_2\alpha_4, \\ q_2(\alpha_1 - \alpha_3A + \alpha_1A - \alpha_4) + rp_1(-2A - 1) + rq_1(-\alpha_3A - \alpha_2A - \alpha_4) = 0, \\ q_2(\alpha_1 - \alpha_4B + \alpha_1B - \alpha_3) + tp_1(-2B - 1) + tq_1(-\alpha_4B - \alpha_2B - \alpha_3) = 0. \end{cases}$$

From the first equation we get

$$(6) \quad q_2 = (tp_1 - rp_1 + tq_1\alpha_4 - rq_1\alpha_3)(\alpha_3 - \alpha_4)^{-1}.$$

Now q_2 can be eliminated:

$$\begin{cases} (tp_1 - rp_1 + tq_1\alpha_4 - rq_1\alpha_3)(\alpha_3 - \alpha_4)^{-1}(\alpha_1 - \alpha_4 + (\alpha_1 - \alpha_3)A) \\ \quad + rp_1(-2A - 1) + rq_1(-(\alpha_2 + \alpha_3)A - \alpha_4) = 0, \\ (tp_1 - rp_1 + tq_1\alpha_4 - rq_1\alpha_3)(\alpha_3 - \alpha_4)^{-1}(\alpha_1 - \alpha_3 + (\alpha_1 - \alpha_4)B) \\ \quad + tp_1(-2B - 1) + tq_1(-(\alpha_2 + \alpha_4)B - \alpha_3) = 0. \end{cases}$$

Define

$$\begin{aligned} \bar{A} &= (\alpha_3 - \alpha_4)^{-1}(\alpha_1 - \alpha_4 + (\alpha_1 - \alpha_3)A), \\ \bar{B} &= (\alpha_3 - \alpha_4)^{-1}(\alpha_1 - \alpha_3 + (\alpha_1 - \alpha_4)B). \end{aligned}$$

After transformations we get

$$(7) \quad \begin{cases} t(p_1 + q_1\alpha_4)\bar{A} = r[p_1(\bar{A} + 2A + 1) + q_1(\alpha_3\bar{A} + (\alpha_2 + \alpha_3)A + \alpha_4)], \\ t[p_1(\bar{B} - 2B - 1) + q_1(\alpha_4\bar{B} - (\alpha_2 + \alpha_4)B - \alpha_3)] = r(p_1 + q_1\alpha_3)\bar{B}. \end{cases}$$

It is easy to see that $\bar{A} = 0$ implies $\alpha_2 = \alpha_3$, a contradiction. Hence $\bar{A} \neq 0$. Since $t, r \neq 0$, the elements

$$p_1 + q_1\alpha_4 \quad \text{and} \quad p_1(\bar{A} + 2A + 1) + q_1(\alpha_3\bar{A} + (\alpha_2 + \alpha_3)A + \alpha_4)$$

are either both zero or both nonzero. If both are zero, then by eliminating p_1 and q_1 ($(p_1, q_1) \neq (0, 0)$) we conclude that $\alpha_2 = \alpha_4$. This contradiction shows that the above two elements are nonzero. Similarly one can prove that both sides of the second equation of (7) are nonzero. Now r and t may be eliminated:

$$(8) \quad \begin{aligned} [p_1(\bar{A} + 2A + 1) + q_1(\alpha_3\bar{A} + (\alpha_2 + \alpha_3)A + \alpha_4)]\bar{A}^{-1}(p_1 + q_1\alpha_4)^{-1} \\ = (p_1 + q_1\alpha_3)\bar{B}[p_1(\bar{B} - 2B - 1) + q_1(\alpha_4\bar{B} - (\alpha_2 + \alpha_4)B - \alpha_3)]^{-1}. \end{aligned}$$

Define $X = p_1 + q_1\alpha_4$ and $Y = p_1 + q_1\alpha_3$. Then $p_1 = -X(\alpha_4 - \alpha_3)^{-1}\alpha_3 + Y(\alpha_4 - \alpha_3)^{-1}\alpha_4$ and $q_1 = (X - Y)(\alpha_4 - \alpha_3)^{-1}$. Put $\bar{X} = X(\alpha_4 - \alpha_3)^{-1}$ and $\bar{Y} = Y(\alpha_4 - \alpha_3)^{-1}$. Then $p_1 = -\bar{X}\alpha_3 + \bar{Y}\alpha_4$ and $q_1 = \bar{X} - \bar{Y}$. Substituting this to (8) we get

$$\begin{aligned} [(-\bar{X}\alpha_3 + \bar{Y}\alpha_4)(\bar{A} + 2A + 1) \\ \quad + (\bar{X} - \bar{Y})(\alpha_3\bar{A} + (\alpha_2 + \alpha_3)A + \alpha_4)]\bar{A}^{-1}(\alpha_4 - \alpha_3)^{-1}\bar{X}^{-1} \\ = \bar{Y}(\alpha_4 - \alpha_3)\bar{B}[(-\bar{X}\alpha_3 + \bar{Y}\alpha_4)(\bar{B} - 2B - 1) \\ \quad + (\bar{X} - \bar{Y})(\alpha_4\bar{B} - (\alpha_2 + \alpha_4)B - \alpha_3)]^{-1}. \end{aligned}$$

By the definition of \bar{A} and \bar{B} we obtain

$$(9) \quad \begin{aligned} & \{\bar{X}[(\alpha_2 - \alpha_3)A + (\alpha_4 - \alpha_3)] \\ & \quad + \bar{Y}[(\alpha_4 - \alpha_1) + (2\alpha_4 - \alpha_1 - \alpha_2)A]\}[(\alpha_4 - \alpha_1) + (\alpha_3 - \alpha_1)A]^{-1}\bar{X}^{-1} \\ & = \bar{Y}[(\alpha_3 - \alpha_1) + (\alpha_4 - \alpha_1)B]\{\bar{X}[(\alpha_3 - \alpha_1) + (2\alpha_3 - \alpha_1 - \alpha_2)B] \\ & \quad + \bar{Y}[(\alpha_2 - \alpha_4)B + (\alpha_3 - \alpha_4)]\}^{-1} \end{aligned}$$

Define $\beta_2 = \alpha_1 - \alpha_2$, $\beta_3 = \alpha_1 - \alpha_3$ and $\beta_4 = \alpha_1 - \alpha_4$. Then $A = -\beta_2^{-1}\beta_4$ and $B = -\beta_2^{-1}\beta_3$. So $\alpha_1, \dots, \alpha_4, A, B$ can be eliminated:

$$(10) \quad \begin{aligned} & \{\bar{X}[(\beta_3 - \beta_2)(-\beta_2^{-1}\beta_4) + (\beta_3 - \beta_4)] \\ & \quad + \bar{Y}[-\beta_4 + (\beta_2 - 2\beta_4)(-\beta_2^{-1}\beta_4)]\}[-\beta_4 - \beta_3(-\beta_2^{-1}\beta_4)]^{-1}\bar{X}^{-1} \\ & = \bar{Y}[-\beta_3 - \beta_4(-\beta_2\beta_3^{-1})]\{\bar{X}[-\beta_3 + (\beta_2 - 2\beta_3)(-\beta_2^{-1}\beta_3)] \\ & \quad + \bar{Y}[(\beta_4 - \beta_2)(-\beta_2^{-1}\beta_3) + (\beta_4 - \beta_3)]\}^{-1}. \end{aligned}$$

Multiplying by \bar{Y}^{-1} on the left and by \bar{X} on the right and setting $T = \bar{X}^{-1}\bar{Y}$ we obtain $PQ^{-1} = RS^{-1}$, where

$$\begin{aligned} P &= T^{-1}(-\beta_3\beta_2^{-1}\beta_4 + \beta_3) + (-2\beta_4 + 2\beta_4\beta_2^{-1}\beta_4), \\ Q &= -\beta_4 + \beta_3\beta_2^{-1}\beta_4, \quad R = -\beta_3 + \beta_4\beta_2^{-1}\beta_3, \\ S &= (-2\beta_3 + 2\beta_3\beta_2^{-1}\beta_3) + T(-\beta_4\beta_2^{-1}\beta_3 + \beta_4). \end{aligned}$$

Then clearly

$$(\beta_4^{-1}P\beta_4^{-1})(\beta_3^{-1}Q\beta_4^{-1})^{-1} = (\beta_4^{-1}R\beta_3^{-1})(\beta_3^{-1}S\beta_3^{-1})^{-1}.$$

But

$$\begin{aligned} \beta_4^{-1}P\beta_4^{-1} &= (\beta_4^{-1}T^{-1}\beta_3 - 2)(\beta_4^{-1} - \beta_2^{-1}), & \beta_3^{-1}Q\beta_4^{-1} &= -\beta_3^{-1} + \beta_2^{-1}, \\ \beta_4^{-1}R\beta_3^{-1} &= -\beta_4^{-1} + \beta_2^{-1}, & \beta_3^{-1}S\beta_3^{-1} &= (-2 + \beta_3^{-1}T\beta_4)(\beta_3^{-1} - \beta_2^{-1}). \end{aligned}$$

Hence

$$\begin{aligned} & (\beta_4^{-1}T^{-1}\beta_3 - 2)(\beta_4^{-1} - \beta_2^{-1})(-\beta_3^{-1} + \beta_2^{-1})^{-1} \\ & \quad = (-\beta_4^{-1} + \beta_2^{-1})(\beta_3^{-1} - \beta_2^{-1})^{-1}(\beta_3^{-1}T\beta_4 - 2)^{-1}. \end{aligned}$$

Define $Z = \beta_3^{-1}T\beta_4$ and $w_0 = (\beta_4^{-1} - \beta_2^{-1})(\beta_2^{-1} - \beta_3^{-1})^{-1}$. Then we get the equation

$$(11) \quad (z^{-1} - 2)w_0 = w_0(z - 2)^{-1}.$$

This implies $(1 - 2z)w_0(z - 2) = zw_0$. After substituting $z = t + 1$ we get $2tw_0t - tw_0 + w_0t = 0$. Hence

$$(12) \quad (2t)w_0(2t) - (2t)w_0 + w_0(2t) = 0.$$

Next we check that $t \neq 0$. If $t = 0$, then $z = 1$ and $T = \beta_3\beta_4^{-1}$. Hence $\bar{X}^{-1}\bar{Y} = \beta_3\beta_4^{-1}$. This implies

$$(\alpha_4 - \alpha_3)X^{-1}Y(\alpha_4 - \alpha_3)^{-1} = (\alpha_1 - \alpha_3)(\alpha_1 - \alpha_4)^{-1}.$$

Therefore $X^{-1}Y = 1 + (\alpha_1 - \alpha_4)^{-1}(\alpha_4 - \alpha_3)$. Since $X = p_1 + q_1\alpha_4$ and $Y = p_1 + q_1\alpha_3$,

$$(p_1 + q_1\alpha_4)[1 + (\alpha_1 - \alpha_4)^{-1}(\alpha_4 - \alpha_3)] = p_1 + q_1\alpha_3.$$

This is equivalent to $p_1 + q_1\alpha_1 = 0$. In this case $0 \neq p_1(v_1 + \dots + v_4) + q_1(\alpha_1v_1 + \dots + \alpha_4v_4) = p_1(v_2 + v_3 + v_4) + q_1(\alpha_2v_2 + \alpha_3v_3 + \alpha_4v_4) \in V \cap W$. By Lemma 7, $V = W$, a contradiction. Hence $2t \neq 0$.

Multiplying (12) by $(2tw_0)^{-1}$ on the left and by $(2t)^{-1}$ on the right we get $1 - (2t)^{-1} + w_0^{-1}(2t)^{-1}w_0 = 0$. Substituting $x = w_0$ and $y = w_0^{-1}(2t)^{-1}$ we have $1 = xy - yx$. Hence the division ring generated by x and y over K is isomorphic to $A_1A_1^{-1}$.

Now assume that D contains two elements x, y such that $xy - yx = 1$. Following the argument of the “if” part in reverse order one can construct the desired solution of (4). Namely, define $w_0 = x, t = \frac{1}{2}y^{-1}x^{-1}$ and $z = t + 1$. Then (11) is satisfied. Elements $\beta_2, \beta_3, \beta_4 \in D \setminus \{0\}$ such that $w_0 = (\beta_4^{-1} - \beta_2^{-1})(\beta_2^{-1} - \beta_3^{-1})^{-1}$ are easy to find. Define $T = \beta_3Z\beta_4^{-1}$. Choose $\bar{X}, \bar{Y} \in D$ satisfying $T = \bar{X}^{-1}\bar{Y}$. Then (10) is true.

Define $A = -\beta_2^{-1}\beta_4$ and $B = -\beta_2^{-1}\beta_3$. Choose $\alpha_1, \dots, \alpha_4 \in D$ such that $\beta_i = \alpha_1 - \alpha_i$ for $i = 2, 3, 4$. Then (9) holds.

Define also $\bar{A} = (\alpha_3 - \alpha_4)^{-1}(\alpha_1 - \alpha_4 + (\alpha_1 - \alpha_3)A)$, $\bar{B} = (\alpha_3 - \alpha_4)^{-1}(\alpha_1 - \alpha_3 + (\alpha_1 - \alpha_4)B)$, $X = \bar{X}(\alpha_4 - \alpha_3)$, $Y = \bar{Y}(\alpha_4 - \alpha_3)$, $p_1 = -\bar{X}\alpha_3 + \bar{Y}\alpha_4$ and $q_1 = \bar{X} - \bar{Y}$. Then (8) is satisfied.

Now we can find $t, r \in D \setminus \{0\}$ satisfying (7). Next q_2 can be calculated from (6). Define $p_2 = -(rp_1 + rq_1\alpha_3 + q_2\alpha_3)$. Put $s = u = 1$. Then q_3 and q_4 are given by (5). Finally, define $p_3 = sp_2 + sq_2\alpha_1 - q_3\alpha_1$ and $p_4 = up_2 + uq_2\alpha_1 - q_4\alpha_1$. In this way a solution of (4) is obtained.

Now we have to check that our solution corresponds to $V \neq W$ (the remaining conditions are easy to verify). Suppose that $V = W$. Then

$$w_1 = p_1 \sum_{j \neq 1} v_j + q_1 \sum_{j \neq 1} \alpha_j v_j \in \pi_1(V) \cap V.$$

Hence we can find $g, h \in D$ such that

$$w_1 = g \sum_j v_j + h \sum_j \alpha_j v_j.$$

Comparing both expressions one can prove that $g = p_1$ and $h = q_1$. Hence $p_1 + q_1\alpha_1 = 0$. Repeating the arguments given at the end of the proof of the “if” part in reverse order, we can prove that $t = 0$. This contradicts the choice of $t (= \frac{1}{2}y^{-1}x^{-1})$. ■

3. The identity as a sum of three nilpotents. Bokut' proved that each algebra can be embedded into a simple algebra which is a sum of three nilpotent algebras of degree 3 (see [2]). We show that the identity element of $M_3(D)$ can be represented as a sum of three nilpotent elements for certain D . The proof will be preceded by auxiliary lemmas. However, we start with a negative result concerning such representations.

PROPOSITION 9. *The equality $1 = x + y + z$ where $x^2 = y^3 = z^5 = 0$ does not hold for any K -algebra A with unit and $x, y, z \in A$.*

Proof. Consider the algebra $A = K\langle x, y, z : 1 = x + y + z, x^2 = y^3 = z^5 = 0 \rangle$. Eliminating z we get $A = K\langle x, y : x^2 = y^3 = (1 - x - y)^5 = 0 \rangle$. Since $x^2 = 0, y^3 = 0$, from $x(1 - x - y)^5x = 0$ and $x(1 - x - y)^5y = 0$ it follows that

$$(13) \quad xy^2xy^2x = -xyxyxyx + \dots,$$

$$(14) \quad xy^2xyxy = -xyxy^2xy - xyxyxy^2 + \dots,$$

where monomials of degrees ≤ 6 are not specified. Set $B = \{1, y, y^2\}$ and $E = \{1, x, xy^2, xy^2x, xy^2xy, xy^2xy^2, xy^2xyx\}$. Define also

$$V_m = \text{Lin}_K\{\text{monomials of degree } \leq m\},$$

$$Z_m = \text{Lin}_K\{b(xy)^n e' : b \in B, e' \in E, n \in \mathbb{N} \cup \{0\}$$

$$\text{and } b(xy)^n e' \text{ is of degree } \leq m\}.$$

Every nonzero monomial which cannot be written as in the definition of Z_m must be either (i) $b(xy)^n xy^2xy^2xa$ or (ii) $b(xy)^n xy^2xyxya$ for some $b \in B, n \geq 0$, and for a monomial a (maybe empty). In the first case, applying (13) we get

$$b(xy)^n xy^2xy^2xa = -b(xy)^n xyxyxyxa + \dots = -b(xy)^{n+3}xa + \dots$$

In the second case applying (14) we get

$$\begin{aligned} b(xy)^n xy^2xyxya &= -b(xy)^n xyxy^2xya - b(xy)^n xyxyxy^2a + \dots \\ &= -b(xy)^{n+1}xy^2xya - b(xy)^{n+2}xy^2a + \dots \end{aligned}$$

(monomials of smaller degrees are not specified). Repeating the above arguments for monomials of degree m we increase n . This allows us to prove that $V_m \subseteq Z_m + V_{m-1}$. Then

$$V_m \subseteq Z_m + V_{m-1} \subseteq Z_m + (Z_{m-1} + V_{m-1}) \subseteq \dots \subseteq Z_m + \dots + Z_1 = Z_m.$$

Hence $V_m \subseteq Z_m$. By the definition of Z_m we see that $\text{GKdim}(A) \leq 1$. By [12] we know that A is PI. Hence $A/J(A)$ is a subdirect product of $M_{n_i}(D_i), i \in I$, where D_i are finite-dimensional division algebras over their centers $Z(D_i)$ (see [5]). Now using the $Z(D_i)$ -linear trace function on $M_{n_i}(D_i)$ we can prove that $A = \mathcal{J}(A)$, but $1 \in A$, a contradiction. ■

A similar method can be used to prove that if $e = e^2 = x + y$ and $x^3 = y^5 = 0$ then $e = 0$. This yields a simpler proof than that given in [4]. It is easy to see that $1 = x + y + z$ and $x^2 = y^2 = z^n = 0$, $n \in \mathbb{N}$, leads to a contradiction. The next cases to be considered are those where $x^2 = y^4 = z^4 = 0$ or $x^2 = y^3 = z^6 = 0$. We conjecture that examples of algebras of these types exist.

LEMMA 10. *Assume that*

$$g \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} g^{-1} = (a_{i,j})$$

for some $g \in M_3(D)$ and $a_{i,j} \in D$ such that $a_{i,i} = 0$. Then $a_{i,j} \neq 0$ for all $i \neq j$.

PROOF. Suppose that $a_{i,j} = 0$ for some $i \neq j$. Conjugating by a permutation matrix we can assume that $a_{2,1} = 0$. Then

$$I = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ a_{3,1} & a_{3,2} & 0 \end{pmatrix} + \begin{pmatrix} 0 & a_{1,2} & a_{1,3} \\ 0 & 0 & a_{2,3} \\ 0 & 0 & 0 \end{pmatrix} - g \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} g^{-1}.$$

This contradicts Proposition 9. ■

LEMMA 11. *Under the assumptions of Lemma 10, we can find (i, j, k) such that $\{1, 2, 3\} = \{i, j, k\}$, $a_{k,j}a_{j,k} \neq 1$ and $a_{i,j}a_{j,k} + a_{i,k} \neq 0$.*

PROOF. First assume that $a_{k,j}a_{j,k} \neq 1$ for some $k \neq j$. Then we can assume that $a_{i,j}a_{j,k} + a_{i,k} = 0$ for i such that $\{1, 2, 3\} = \{i, j, k\}$. In this case $a_{j,k}a_{k,j} \neq 1$ and $a_{i,k}a_{k,j} + a_{i,j} = (-a_{i,j}a_{j,k})a_{k,j} + a_{i,j} = a_{i,j}(1 - a_{j,k}a_{k,j}) \neq 0$ by Lemma 10. Hence the triple (i, k, j) satisfies the claim.

Now, suppose that $a_{i,j}a_{j,i} = 1$ for every $i \neq j$. Let

$$h = \begin{pmatrix} 1 & 0 & 0 \\ 0 & a_{1,2} & 0 \\ 0 & 0 & a_{1,2}a_{2,3} \end{pmatrix}.$$

Then

$$(hg) \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} (hg)^{-1} = h(a_{i,j})h^{-1} = \begin{pmatrix} 0 & 1 & \lambda \\ 1 & 0 & 1 \\ \lambda^{-1} & 1 & 0 \end{pmatrix}$$

where $\lambda = a_{1,3}a_{2,3}^{-1}a_{1,2}^{-1} \neq 0$. Let

$$\begin{pmatrix} p \\ q \\ r \end{pmatrix} = hg \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \neq 0.$$

Then

$$\begin{pmatrix} 0 & 1 & \lambda \\ 1 & 0 & 1 \\ \lambda^{-1} & 1 & 0 \end{pmatrix} \begin{pmatrix} p \\ q \\ r \end{pmatrix} = \begin{pmatrix} p \\ q \\ r \end{pmatrix}.$$

This immediately implies that $\lambda = -1$. Then

$$2 = \text{rank} \left[(hg) \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} (hg)^{-1} - I \right] = \text{rank} \begin{pmatrix} -1 & 1 & -1 \\ 1 & -1 & 1 \\ -1 & 1 & -1 \end{pmatrix} = 1,$$

a contradiction. ■

THEOREM 12. *Let D be a division ring of characteristic zero. Then $M_3(D)$ contains elements x, y, z such that $I = x + y + z$ and $x^3 = y^3 = z^3 = 0$ if and only if D contains a copy of $A_1 A_1^{-1}$.*

PROOF. (\Rightarrow) By Proposition 9, x is nilpotent of index 3. So x is equal to $\begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{pmatrix}$ in a certain basis. By Lemma 2, $y + z$ has zero diagonal in some basis. Since $I - x = y + z$, we can find an invertible $g \in M_3(D)$ such that

$$g \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} g^{-1} = \begin{pmatrix} 0 & p & q \\ s & 0 & r \\ t & u & 0 \end{pmatrix}$$

for some $p, q, r, s, t, u \in D$. By Lemma 10, $p, q, r, s, t, u \neq 0$. By Lemma 11, changing the order of v_1, v_2, v_3 if necessary, we can assume that $sp \neq 1$ and $tp + u \neq 0$. Denoting

$$g = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}, \quad a, b, \dots \in D,$$

we have

$$(15) \quad \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & p & q \\ s & 0 & r \\ t & u & 0 \end{pmatrix} \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}.$$

Comparing the first columns on both sides of (15) we get

$$\begin{cases} a = pd + qg, \\ d = sa + rg, \\ g = ta + ud. \end{cases}$$

Eliminating $a = pd + qg$ we get

$$\begin{cases} (1 - sp)d = (sq + r)g, \\ (1 - tq)g = (tp + u)d. \end{cases}$$

If $g = 0$ then $d = 0$ and $a = 0$. This implies that g is not invertible, a contradiction. Hence $g \neq 0$ and $(1 - sp)^{-1}(sq + r) = (tp + u)^{-1}(1 - tq)$. Any

solution of our system of equations with respect to a, d, g looks like

$$\begin{cases} g = g, \\ d = (1 - sp)^{-1}(sq + r)g, \\ a = p(1 - sp)^{-1}(sq + r)g + qg. \end{cases}$$

Define $X = 1 - tq$, $Y = 1 - sp$, $P = sq + r$ and $Q = tp + u$. Since we have $(tq)(sq)^{-1}(sp)(tp)^{-1} = 1$ it follows that

$$(16) \quad (1 - X)(P - r)^{-1}(1 - Y)(Q - u)^{-1} = 1.$$

The previous equations can be written in the form

$$(17) \quad Y^{-1}P = Q^{-1}X \quad \text{and} \quad \begin{cases} g = g, \\ d = Y^{-1}Pg, \\ a = (pY^{-1}P + q)g. \end{cases}$$

Next we consider further equations derived from (15) (second columns):

$$\begin{cases} a + b = pe + qh, \\ d + e = sb + rh, \\ g + h = tb + ue. \end{cases}$$

By eliminating $b = pe + qh - a$ we obtain

$$\begin{cases} d + sa = (sp - 1)e + (sq + r)h, \\ g + ta = (tp + u)e + (tq - 1)h. \end{cases}$$

After eliminating e , h vanishes and we get

$$(sp - 1)^{-1}(d + sa) = (tp + u)^{-1}(g + ta).$$

By (17) we have

$$\begin{aligned} d + sa &= (Y^{-1}P + spY^{-1}P + sq)g \\ &= (Y^{-1}P + (1 - Y)Y^{-1}P + (P - r))g = (2Y^{-1}P - r)g \end{aligned}$$

and

$$g + ta = (1 + tpY^{-1}P + tq)g = (1 + (Q - u)Y^{-1}P + 1 - X)g = (2 - uY^{-1}P)g.$$

Therefore

$$(18) \quad -Y^{-1}(2Y^{-1}P - r) = Q^{-1}(2 - uY^{-1}P).$$

Any solution of the last system of equations with respect to b, e, h has the form

$$(19) \quad \begin{cases} h = h, \\ e = -Y^{-1}((2Y^{-1}P - r)g - Ph), \\ b = -pY^{-1}((2Y^{-1}P - r)g - Ph) + qh - (pY^{-1}P + q)g \\ \quad = -pY^{-1}((2Y^{-1}P - r + P)g - Ph) + q(h - g). \end{cases}$$

Now, consider the remaining equations coming from (15) (third columns):

$$\begin{cases} b + c = pf + qi, \\ e + f = sc + ri, \\ h + i = tc + uf. \end{cases}$$

By eliminating $c = pf + qi - b$ we obtain

$$\begin{cases} e + sb = (sp - 1)f + (sq + r)i, \\ h + tb = (tp + u)f + (tq - 1)i. \end{cases}$$

After eliminating f, i vanishes and we get

$$(sp - 1)^{-1}(e + sb) = (tp + u)^{-1}(h + tb).$$

By (19) we have

$$\begin{aligned} e + sb &= -Y^{-1}((2Y^{-1}P - r)g - Ph) \\ &\quad + (-sp)Y^{-1}((2Y^{-1}P - r + P)g - Ph) + sq(h - g) \\ &= -Y^{-1}((2Y^{-1}P - r)g - Ph) \\ &\quad + (Y - 1)Y^{-1}((2Y^{-1}P - r + P)g - Ph) + (P - r)(h - g) \\ &= Y^{-1}(-2(2Y^{-1}P - r) + P)g + (2Y^{-1}P - r)h \end{aligned}$$

and

$$\begin{aligned} h + tb &= h + (-tp)Y^{-1}((2Y^{-1}P - r + P)g - Ph) + tq(h - g) \\ &= h + (u - Q)Y^{-1}((2Y^{-1}P - r + P)g - Ph) + (1 - x)(h - g) \\ &= ((u - Q)Y^{-1}(2Y^{-1}P - r) + uY^{-1}P - QY^{-1}P - 1 + X)g \\ &\quad + (2 - (u - Q)Y^{-1}P - X)h \\ &= ((u - Q)Y^{-1}(2Y^{-1}P - r) + (-2 + uY^{-1}P) + 1)g \\ &\quad + (2 - (u - Q)Y^{-1}P - X)h \quad \text{by (17)} \\ &= ((u - Q)Y^{-1}(2Y^{-1}P - r) + QY^{-1}(2Y^{-1}P - r) + 1)g \\ &\quad + (2 - (u - Q)Y^{-1}P - X)h \quad \text{by (18)} \\ &= (uY^{-1}(2Y^{-1}P - r) + 1)g + (2 - (u - Q)Y^{-1}P - X)h. \end{aligned}$$

Hence

$$\begin{aligned} &-Y^{-1}[Y^{-1}(-2(2Y^{-1}P - r) + P)g + (2Y^{-1}P - r)h] \\ &= Q^{-1}[uY^{-1}(2Y^{-1}P - r + 1)g + (2 - (u - Q)Y^{-1}P - X)h]. \end{aligned}$$

By (17) and (18) we have $-Y^{-1}(2Y^{-1}P - r)h = Q^{-1}(2 - (u - Q)Y^{-1}P - X)h$. Hence $-Y^{-2}(-2(2Y^{-1}P - r) + P) = Q^{-1}(uY^{-1}(2Y^{-1}P - r) + 1)$. This implies

$$(20) \quad (2 - YQ^{-1}u)Y^{-1}(2Y^{-1}P - r) = Y^{-1}P + YQ^{-1}.$$

Set $\bar{P} = Y^{-1}P$ and $\bar{Q} = YQ^{-1}$. Then (17) becomes $X = \bar{Q}^{-1}Y\bar{P}$, and (16), (18) and (20) can be rewritten as

$$\begin{cases} (1 - \bar{Q}^{-1}Y\bar{P})(Y\bar{P} - r)^{-1}(1 - Y)(\bar{Q}^{-1}Y - u)^{-1} = 1, \\ -(2\bar{P} - r) = \bar{Q}(2 - u\bar{P}), \\ (2 - \bar{Q}u)Y^{-1}(2\bar{P} - r) = \bar{P} + \bar{Q}. \end{cases}$$

Next we will prove that $\bar{P} \neq 0$. If $\bar{P} = 0$ then

$$\begin{cases} (-r)^{-1}(1-Y)(\bar{Q}^{-1}Y-u)^{-1} = 1, \\ r = 2\bar{Q}, \\ (2-\bar{Q}u)Y^{-1}(-r) = \bar{Q}. \end{cases}$$

Eliminating r we get

$$\begin{cases} Y-1 = 2\bar{Q}(\bar{Q}^{-1}Y-u), \\ (2-\bar{Q}u)Y^{-1}(-2\bar{Q}) = \bar{Q}. \end{cases}$$

Hence $3 = 0$, a contradiction.

Our system of equations is equivalent to

$$\begin{cases} (\bar{Q}\bar{P}^{-1}-Y)(Y-r\bar{P}^{-1})(1-Y)(Y-\bar{Q}u)^{-1} = 1, \\ r\bar{P}^{-1}-2 = 2\bar{Q}\bar{P}^{-1}-\bar{Q}u, \\ (2-\bar{Q}u)Y^{-1}(2-r\bar{P}^{-1}) = 1 + \bar{Q}\bar{P}^{-1}. \end{cases}$$

Define $A = \bar{Q}\bar{P}^{-1}$, $B = r\bar{P}^{-1}$ and $C = \bar{Q}u$. Then

$$\begin{cases} (A-Y)(Y-B)^{-1}(1-Y)(Y-C)^{-1} = 1, \\ -2+B = 2A-C, \\ (2-C)Y^{-1}(2-B) = 1+A. \end{cases}$$

Substituting $A = \frac{1}{2}B + \frac{1}{2}C - 1$ we obtain

$$\begin{cases} Y - \frac{1}{2}B - \frac{1}{2}C + 1 = (Y-C)(Y-1)^{-1}(Y-B), \\ (2-C)Y^{-1}(2-B) = \frac{1}{2}B + \frac{1}{2}C. \end{cases}$$

If $B+C=0$ then $B=2$ or $C=2$. Let for example $B=2$. Then $C=-2$. Hence $(Y+1) = (Y-2)(Y-1)^{-1}(Y-2)$. This is equivalent to $0=3$, a contradiction. Hence $B+C \neq 0$. Set $S = (B+C)^{-1}$, $T = B(B+C)^{-1}$, $(1-T = C(B+C)^{-1})$ and $\bar{Y} = Y(B+C)^{-1}$. Then

$$\begin{cases} \bar{Y} + S - \frac{1}{2} = (\bar{Y} - (1-T))(\bar{Y} - S)^{-1}(\bar{Y} - T), \\ (2S - (1-T))\bar{Y}^{-1}(2S - T) = \frac{1}{2}. \end{cases}$$

Hence

$$\begin{cases} (\bar{Y} + S - \frac{1}{2})(\bar{Y} - T)^{-1} = (\bar{Y} + T - 1)(\bar{Y} - S)^{-1}, \\ \bar{Y} = \frac{1}{2}(2S - T)(2S + T - 1). \end{cases}$$

The first equation will be transformed equivalently:

$$\begin{aligned} ((\bar{Y} - T) + (T + S - \frac{1}{2}))(\bar{Y} - T)^{-1} &= ((\bar{Y} - S) + (T + S - 1))(\bar{Y} - S)^{-1}, \\ (T + S - \frac{1}{2})(\bar{Y} - T)^{-1} &= (T + S - 1)(\bar{Y} - S)^{-1}, \\ (\bar{Y} - T)(T + S - \frac{1}{2})^{-1} &= (\bar{Y} - S)(T + S - 1)^{-1}, \\ \bar{Y}((T + S - \frac{1}{2})^{-1} - (T + S - 1)^{-1}) &= T(T + S - \frac{1}{2})^{-1} - S(T + S - 1)^{-1}, \\ \bar{Y}((T + S - \frac{1}{2})^{-1}(T + S - 1) - 1) &= T(T + S - \frac{1}{2})^{-1}(T + S - 1) - S, \\ \bar{Y}[(T + S - \frac{1}{2})^{-1}((T + S - \frac{1}{2}) - \frac{1}{2}) - 1] &= T(T + S - \frac{1}{2})^{-1}((T + S - \frac{1}{2}) - \frac{1}{2}) - S, \end{aligned}$$

$$\begin{aligned}\bar{Y}(-\tfrac{1}{2})(T+S-\tfrac{1}{2})^{-1} &= T(1-\tfrac{1}{2}(T+S-\tfrac{1}{2})^{-1})-S, \\ (-\tfrac{1}{2}\bar{Y}+\tfrac{1}{2}T)(T+S-\tfrac{1}{2})^{-1} &= T-S.\end{aligned}$$

Substituting $\bar{Y} = \frac{1}{2}(2S-T)(2S+T-1)$ we have

$$\begin{aligned}-\tfrac{1}{4}(2S-T)(2S+T-1)+\tfrac{1}{2}T &= (T-S)(T+S-\tfrac{1}{2}), \\ -\tfrac{3}{4}T^2+\tfrac{1}{2}ST-\tfrac{1}{2}TS+\tfrac{3}{4}T &= 0, \\ -\tfrac{3}{4}T+\tfrac{1}{2}(ST^{-1})T-\tfrac{1}{2}T(ST^{-1})+\tfrac{3}{4} &= 0, \\ (\tfrac{2}{3}ST^{-1})(T-1)-(T-1)(\tfrac{2}{3}ST^{-1}) &= T-1.\end{aligned}$$

If $T = 1$ then $0 = C = \bar{Q}u = YQ^{-1}u$, a contradiction. Hence $T - 1 \neq 0$ and we have

$$[(\tfrac{2}{3}ST^{-1})(T-1)^{-1}](T-1)-(T-1)[(\tfrac{2}{3}ST^{-1})(T-1)^{-1}] = 1$$

Define $M = (\frac{2}{3}ST^{-1})(T-1)^{-1}$ and $N = T-1$. Then $MN - NM = 1$. Hence D contains a copy of $A_1A_1^{-1}$.

(\Leftarrow) Let $M, N \in D$ be such that $MN - NM = 1$. We will find a solution of the system of equations arising from (15). This may be done by following the argument of the proof of (\Rightarrow) in reverse order. If $M = \frac{2}{3}ST^{-1}(T-1)^{-1}$ and $N = T-1$ then $T = N+1$ and $S = \frac{3}{2}MN(N+1)$. Hence $\bar{Y} = \frac{1}{2}(2S-T)(2S+T-1)$. Now we get $B = \bar{T}S^{-1}, C = (1-T)S^{-1}$ and $A = \frac{1}{2}B + \frac{1}{2}C - 1$. Put $\bar{P} = 1$. Then $\bar{Q} = A, r = B, u = A^{-1}C$. Moreover, $P = Y\bar{P}, Q = \bar{Q}^{-1}Y$ and $X = \bar{Q}^{-1}Y\bar{P}$. We have defined X, Y, P, Q, r, u such that (16), (18) and (20) are satisfied.

Next we use (16) to define p, q, s, t . Put $p = 1$. Then $s = 1 - Y, q = s^{-1}(P - r)$ and $t = Q - u$. Now, the proof of (\Rightarrow) yields a solution of the system of equations arising from (15), with p, q, r, s, t, u given. For example let $g = 1, d = Y^{-1}Pg$ and $a = (pY^{-1}P + q)g$. From (19) we can read h, e, b (h can be chosen arbitrary), and so forth.

Now we have to prove that the solution just constructed leads to an invertible matrix g . Let

$$W = \left\{ \begin{pmatrix} p \\ q \\ r \end{pmatrix} : p, q, r \in D, g \begin{pmatrix} p \\ q \\ r \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right\}.$$

Then by (15), $\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} W \subseteq W$. Hence if $W \neq 0$ then $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \in W$ and the first column of g is zero, a contradiction. Therefore $W = 0$ and g is invertible. Hence

$$I = g \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{pmatrix} g^{-1} + \begin{pmatrix} 0 & 0 & 0 \\ s & 0 & 0 \\ t & u & 0 \end{pmatrix} + \begin{pmatrix} 0 & p & q \\ 0 & 0 & r \\ 0 & 0 & 0 \end{pmatrix}$$

is the desired decomposition. ■

It is easy to see that the assertions of Theorems 8 and 12 remain true, with the same proofs, if D is any division ring of characteristic $\neq 2, 3$.

Now we can give an example of an idempotent e such that $e = x + y$ and $x^3 = y^6 = 0$. The assertion of Theorem 12 will be used in the construction.

EXAMPLE 13. Let T, T^1 be the free semigroup, respectively monoid, generated by $1, 1', 2, 2', 3, 3'$. Put $X = \{1, 2, 3\}$, $X' = \{1, 1', 2, 2', 3, 3'\}$ and define an order $<$ on X' by $1 < 1' < 2 < 2' < 3 < 3'$. In a vector space over K consider the following system of equations in unknowns v_r for $r \in T$:

$$(21) \quad \begin{cases} \sum_{i \in X'} v_{r_1 i r_2} = v_{r_1 r_2} & \text{where } r_1, r_2 \in T, \\ v_{r_1 i i r_2} = 0 & \text{where } r_1, r_2 \in T^1, i \in X', \\ v_{r_1 i i' r_2} = 0 & \text{where } r_1, r_2 \in T^1, i \in X. \end{cases}$$

We will find a solution of (21) which satisfies the condition

$$(22) \quad \sum_{i \in X'} v_{1i} \neq 0.$$

Assume that D is a division ring such that $A_1 A_1^{-1} \subseteq D$. From Theorem 12 we know that there exist $b_1, b_2, b_3 \in M_3(D)$ such that $I = b_1 + b_2 + b_3$ and $b_1^3 = b_2^3 = b_3^3 = 0$. Each b_i can be written as

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

in some basis of D^3 . Hence we can find $a_i, a_{i'} \in M_3(D)$ such that $b_i = a_i + a_{i'}$ and $a_i^2 = a_i a_{i'} = a_{i'}^2 = 0$. Let $v \in D^3 \setminus \{0\}$ be such that $a_1 v \neq 0$. Define $v_{i_k \dots i_1} = a_{i_k} \dots a_{i_1} v$ for $i_1, \dots, i_k \in X'$. If $r_1 = i_j i_{j-1} \dots i_{k+1}$ and $r_2 = i_k i_{k-1} \dots i_1$ for $i_1, \dots, i_j \in X'$, then

$$\begin{aligned} \sum_{i \in X'} v_{r_1 i r_2} &= \sum_{i \in X'} a_{i_j} \dots a_{i_{k+1}} a_i a_{i_k} \dots a_{i_1} v = a_{i_j} \dots a_{i_{k+1}} \left(\sum_{i \in X'} a_i \right) a_{i_k} \dots a_{i_1} v \\ &= a_{i_j} \dots a_{i_{k+1}} a_{i_k} \dots a_{i_1} v = v_{r_1 r_2}, \\ v_{r_1 i i r_2} &= a_{i_j} \dots a_{i_{k+1}} a_i a_i a_{i_k} \dots a_{i_1} v = 0, \\ v_{r_1 i i' r_2} &= 0 \quad \text{similarly.} \end{aligned}$$

Hence (21) is satisfied. Since $\sum_{i \in X'} v_{1i} = \sum_{i \in X'} a_1 a_i v = a_1 v \neq 0$, (22) holds. Let \bar{V} be a linear space (over K) spanned by the vectors v_r ($r \in T$), subject to the relations given in (21). Define $e, x, y \in \text{End}_K(\bar{V})$ by

$$x(v_{ri}) = \sum_{j \in X': j > i} v_{rj}, \quad y(v_{ri}) = \sum_{j \in X': j < i} v_{rj} \quad \text{for } r \in T^1, \quad e = x + y.$$

Then x, y are indeed well defined since they preserve the relations defining

\bar{V} . For example: if $r_2 = r'_2 k$ for $r'_2 \in T^1$ and $k \in X'$, then

$$\begin{aligned} x \left(\sum_{i \in X'} v_{r_1 i r'_2 k} \right) - x v_{r_1 r'_2 k} &= \left(\sum_{i, j \in X': j > k} v_{r_1 i r'_2 k j} \right) - \left(\sum_{j \in X': j > k} v_{r_1 r'_2 k j} \right) \\ &= \sum_{j \in X': j > k} \left[\left(\sum_{i \in X'} v_{r_1 i (r'_2 k j)} \right) v_{r_1 (r'_2 k j)} \right] = 0. \end{aligned}$$

Moreover, e is a nonzero idempotent because

$$e(ev_r) = e \left(\sum_{i \in X'} v_{ri} \right) = \sum_{i, j \in X'} v_{rij} = \sum_{j \in X'} \left(\sum_{i \in X'} v_{rij} \right) = \sum_{j \in X'} v_{rj} = ev_r$$

for $r \in T$ and $e(v_1) = \sum_{i \in X'} v_{1i} \neq 0$. Let $r' \in T^1$ and $i \in X'$. It is easy to see that

$$x^3(v_{r'i}) = \sum_{j_1, j_2, j_3 \in X': i < j_1 < j_2 < j_3} v_{r'ij_1j_2j_3}.$$

Since certain neighbouring elements of the sequence i, j_1, j_2, j_3 are equal to k, k' for some $k \in X$, from (21) it follows that $v_{r'ij_1j_2j_3} = 0$. This proves that $x^3 = 0$. Similarly one can show that $y^6 = 0$.

Examples of the following two types were constructed in [4]: an identity element which is a sum of four nilpotent elements of degree 2, and a nonzero idempotent which is a sum of three nilpotent elements of degree 2. Another construction of this type can be obtained from [1, Prop. 2.2.1]. Here we give new examples by considering $M_2(D)$. As in the preceding constructions, this leads to the first Weyl algebra.

PROPOSITION 14. *There exists an idempotent $e \in M_2(D) \setminus \{0\}$ which is a sum of three nilpotent elements if and only if D contains a copy of $A_1 A_1^{-1}$.*

PROOF. (\Rightarrow) Let $e = x + y + z$ where $x, y, z \in M_2(D)$ are nilpotent. Then $x^2 = y^2 = z^2 = 0$. Since $e - z$ is a sum of two nilpotent elements, by Lemma 2 we can assume (changing the basis) that $e - z = \begin{pmatrix} 0 & q \\ p & 0 \end{pmatrix}$ for some $p, q \in D$. Let $z = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$, $a, b, c, d \in D$. Since $z^2 = 0$ and $z \neq 0$, either $b \neq 0$ or $c \neq 0$.

Let for example $b \neq 0$. From $z^2 = 0$ we get $a^2 + bc = 0$. Hence $c = -b^{-1}a^2$. Also $ab + bd = 0$, so that $d = -b^{-1}ab$. (It is easy to see that

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a & b \\ -b^{-1}a^2 & -b^{-1}ab \end{pmatrix}$$

is nilpotent). Therefore

$$e = \begin{pmatrix} a & b+q \\ p-b^{-1}a^2 & -b^{-1}ab \end{pmatrix}.$$

Define $\bar{p} = p - b^{-1}a^2$ and $\bar{q} = b + q$. Then

$$e = \begin{pmatrix} a & \bar{q} \\ \bar{p} & -b^{-1}ab \end{pmatrix}.$$

If $\bar{p} = \bar{q} = 0$ then from $e^2 = e$ we get $a^2 = a$ and $b^{-1}a^2b = -b^{-1}ab$. Hence $a = 0$ and $e = 0$, a contradiction.

So suppose for example that $\bar{p} \neq 0$. Then $e^2 = e$ implies $\bar{p}a + (-b^{-1}ab)\bar{p} = \bar{p}$. Hence $(ab\bar{p})(\bar{p}^{-1}b^{-1}) - (\bar{p}^{-1}b^{-1})(ab\bar{p}) = 1$. Defining $x = ab\bar{p}$ and $y = \bar{p}^{-1}b^{-1}$ we obtain $xy - yx = 1$. Therefore D contains a copy of $A_1A_1^{-1}$.

(\Leftarrow) Assume that $x, y \in D$ such that $xy - yx = 1$ are given. Let $a = xy$, $b = y^{-1}$, $\bar{p} = 1$ and $\bar{q} = xy - (xy)^2$. Then

$$e = \begin{pmatrix} a & \bar{q} \\ \bar{p} & -b^{-1}ab \end{pmatrix}$$

is a nonzero idempotent. Put $p = \bar{p} + b^{-1}a^2 = 1 + yxyxy$ and $q = \bar{q} - b = xy - (xy)^2 - y^{-1}$. Then

$$e = \begin{pmatrix} 0 & 0 \\ p & 0 \end{pmatrix} + \begin{pmatrix} 0 & q \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} a & b \\ -b^{-1}a^2 & -b^{-1}ab \end{pmatrix}$$

is a sum of three nilpotent elements. ■

PROPOSITION 15. $I \in M_2(D)$ can be represented as a sum of four nilpotent elements if and only if D contains a copy of $A_1A_1^{-1}$.

Proof. (\Rightarrow) Let $I = x + y + z + t$ where $x, y, z, t \in M_2(D)$ are nilpotent. By Lemma 2 we can assume that $z + t = \begin{pmatrix} 0 & q \\ p & 0 \end{pmatrix}$ for some $p, q \in D$. Similarly there exists an invertible $A \in M_2(D)$ and $r, s \in D$ such that

$$x + y = A \begin{pmatrix} 0 & s \\ r & 0 \end{pmatrix} A^{-1}.$$

Hence

$$A = A \begin{pmatrix} 0 & s \\ r & 0 \end{pmatrix} + \begin{pmatrix} 0 & q \\ p & 0 \end{pmatrix} A.$$

Assume that $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$, $a, b, c, d \in D$. Then our equality is equivalent to

$$(23) \quad \begin{cases} a = br + qc, \\ b = as + qd, \\ c = dr + pa, \\ d = cs + pb. \end{cases}$$

If one of p, q, r, s is zero then I can be represented as a sum of three nilpotent elements of degree 2. This contradicts [4]. Hence $p, q, r, s \neq 0$.

Next we show that $a, b, c, d \neq 0$. Let for example $a = 0$. Then we get

$$\begin{cases} 0 = br + qc, \\ b = qd, \\ c = dr, \\ d = cs + pb. \end{cases}$$

Substituting $b = qd$ and $c = dr$ to the first equation we get $0 = 2qdr$. Hence $d = 0$ and $b = qd = 0$, $c = dr = 0$, a contradiction (A is invertible). The proof that $b, c, d \neq 0$ is similar.

Now we eliminate q from the first and second equations of (23) and p from the third and fourth equations of (23):

$$\begin{cases} (a - br)c^{-1} = (b - as)d^{-1}, \\ (c - dr)a^{-1} = (d - cs)b^{-1}. \end{cases}$$

Defining $f = b^{-1}a$ and $g = d^{-1}c$ we get

$$\begin{cases} f - r = (1 - fs)g, \\ g - r = (1 - gs)f. \end{cases}$$

After eliminating r we obtain $-f + g - fsg = -g + f - gsf$. Define h by $g = f + h$ and substitute it to the previous equation. We get $2h = fsh - hsf$. If $h = 0$ then $b^{-1}a = d^{-1}c$ and A is not invertible. Hence $h \neq 0$. Therefore $1 = (\frac{1}{2}h^{-1}f)(sh) - (sh)(\frac{1}{2}h^{-1}f)$. Put $x = \frac{1}{2}h^{-1}f$ and $y = sh$. Then $1 = xy - yx$. Hence $D \supseteq A_1A_1^{-1}$.

(\Leftarrow) Assume that $x, y \in D$ such that $1 = xy - yx$ are given. Put $h = 1$. Then reading the proof of (\Rightarrow) in reverse direction we have $f = 2hx = 2x$, $s = yh^{-1} = y$, $g = f + h = 2x + 1$ and $r = f - (1 - fs)g = -1 + 2xy + 4xyx$. Put also $b = d = 1$. Then $a = bf = 2x$, $c = dg = 2x + 1$, $q = (a - br)c^{-1} = 1 - 2xy$ and $p = (c - dr)a^{-1} = 1 + x^{-1} - xyx^{-1} + 2xy$. The elements a, b, c, d, p, q, r, s just found satisfy (23) and A is invertible because $h \neq 0$. This gives the desired decomposition of I . ■

4. An application. In [6, 7] Kegel proved that a ring R which is a sum of two nilpotent subrings R_1 and R_2 must be nilpotent. If R is an algebra over a field K , then we may assume that $R \subseteq \text{End}_K(V)$, where V is a K -linear space. Define $W_i = \{v \in V : R_1^i v = 0\}$ and $Z_j = \{v \in V : R_2^j v = 0\}$ and $i, j = 1, 2, \dots$. Then $W_1 \subseteq \dots \subseteq W_n = V$ and $Z_1 \subseteq \dots \subseteq Z_m = V$ where n, m are the nilpotency degrees of R_1, R_2 respectively. By Lemma 1 we can find subspaces $Y_{i,j} \subseteq V$ such that $W_k = \bigoplus_{i \leq k} Y_{i,j}$ and $Z_l = \bigoplus_{j \leq l} Y_{i,j}$. Since $R_1 W_i \subseteq W_{i-1}$, $R_2 Z_j \subseteq Z_{j-1}$ for $i, j = 1, 2, \dots$ ($W_0 = Z_0 = 0$) and $R = R_1 + R_2$ we have

$$R(Y_{i,j}) \subseteq W_{i-1} + Z_{j-1} \subseteq \bigoplus_{(k,l) \neq (i,j)} Y_{k,l}.$$

So it is natural to consider the following problem. Let $V = \bigoplus_{i=1}^n V_i$ where V_i are subspaces of a K -linear space V and let $R \subseteq \text{End}_K(V)$ be a subalgebra satisfying $R(V_i) \subseteq \bigoplus_{j \neq i} V_j$. Is R necessarily nilpotent?

The answer is negative in general by Theorem 8 (take $R = \text{Lin}_K(e)$). Hence we shall discuss the case where V is finite-dimensional. Then R must be nilpotent since $\text{tr}(R) = 0$. The natural question that arises here is whether the nilpotency degree of R is bounded by a function depending on n only (as in Kegel's theorem). We answer this question in the more convenient setting of a semigroup R (clearly, if R satisfies the desired conditions, then the linear span of R also satisfies them).

PROPOSITION 16. *Let $V = \bigoplus_{i=1}^n V_i$, $\dim_K(V) < \infty$ and let $S \subseteq \text{End}_K(V)$ be a semigroup satisfying $S(V_i) \subseteq \bigoplus_{j \neq i} V_j$. Then*

- (a) if $n = 2$ then $S^2 = 0$,
- (b) if $n = 3$ then $S^4 = 0$.

On the other hand, if $n = 4$ then S may have an arbitrarily large nilpotency degree.

PROOF. (a) For any $s \in S$ we have $s(V_1) \subseteq V_2$ and $s(V_2) \subseteq V_1$. Let $s_1, s_2 \in S$. Then $s_1 s_2(V_1) \subseteq s_1(V_2) \subseteq V_1$ and $s_1 s_2(V_2) \subseteq s_1(V_1) \subseteq V_2$. Since $s_1 s_2 \in S$, we have $s_1 s_2(V_1) \subseteq V_1 \cap V_2 = 0$ and $s_1 s_2(V_2) \subseteq V_2 \cap V_1 = 0$. This implies $s_1 s_2 = 0$. Hence $S^2 = 0$.

(b) First we show that it is sufficient to prove the claim for semigroups S generated by one element. Let $s_1, \dots, s_4 \in S$. Consider $\bar{s} \in \text{End}_K(V^5)$ defined by $\bar{s}(v_1, v_2, v_3, v_4, v_5) = (s_1 v_2, s_2 v_3, s_3 v_4, s_4 v_5, 0)$ for any $v_i \in V$. Then the condition $s_1 \dots s_4 = 0$ is equivalent to $\bar{s}^4 = 0$. Moreover, $V^5 = \bigoplus_{i=1}^4 V_i^5$ and $\bar{s}^k(V_i^5) \subseteq \bigoplus_{j \neq i} V_j^5$ for $k = 1, 2, \dots$. Hence it is enough to consider the semigroup generated by \bar{s} . So we can indeed assume that S is generated by some $s \in S$.

Let $v_1 \in V_1$. Then $s(v_1) = v_2 + v_3$ for some $v_2 \in V_2$ and $v_3 \in V_3$. Similarly $s(v_2) = v'_1 + v'_3$, $s(v_3) = v''_1 + v'_2$ for some $v'_1, v''_1 \in V_1$, $v'_2 \in V_2$ and $v'_3 \in V_3$. Since

$$s^2(v_1) = s(v_2 + v_3) = (v'_1 + v''_1) + v'_2 + v'_3 \in V_2 \oplus V_3,$$

we get $v''_1 = -v'_1$. Moreover, $s(v'_1) = \bar{v}_2 + \bar{v}_3$, $s(v'_2) = \bar{v}_1 + \bar{v}_3$ and $s(v'_3) = \bar{v}_1 + \bar{v}_2$ for some $\bar{v}_1, \bar{v}_1 \in V_1$, $\bar{v}_2, \bar{v}_2 \in V_2$ and $\bar{v}_3, \bar{v}_3 \in V_3$. Now

$$s^2(v_2) = s(v'_1 + v'_3) = \bar{v}_1 + (\bar{v}_2 + \bar{v}_2) + \bar{v}_3 \in V_1 \oplus V_3$$

implies that $\bar{v}_2 = -\bar{v}_2$. Since

$$s^2(v_3) = s(-v'_1 + v'_2) = \bar{v}_1 - \bar{v}_2 + (-\bar{v}_3 + \bar{v}_3) \in V_1 \oplus V_2,$$

we get $\bar{v}_3 = \bar{v}_3$. Similarly

$$s^3(v_1) = s(v'_2 + v'_3) = (\bar{v}_1 + \bar{v}_1) + \bar{v}_2 + \bar{v}_3 \in V_2 \oplus V_3$$

implies that $\bar{v}_1 = -\tilde{v}_1$. We also have $s(\bar{v}_1) = \tilde{v}_2 + \tilde{v}_3$, $s(\bar{v}_2) = \tilde{v}_1 + \hat{v}_3$ and $s(\bar{v}_3) = \hat{v}_1 + \hat{v}_2$ for some $\tilde{v}_i, \hat{v}_i \in V_i$, $i = 1, 2, 3$. Since

$$s^2(v'_1) = s(\bar{v}_2 + \bar{v}_3) = (\tilde{v}_1 + \hat{v}_1) + \hat{v}_2 + \hat{v}_3 \in V_2 \oplus V_3,$$

it follows that $\hat{v}_1 = -\tilde{v}_1$. From

$$s^2(v'_2) = s(\bar{v}_1 + \bar{v}_3) = \hat{v}_1 + (\tilde{v}_2 + \hat{v}_2) + \tilde{v}_3 \in V_1 \oplus V_3$$

it follows that $\hat{v}_2 = -\tilde{v}_2$. Similarly

$$s^2(v'_3) = s(-\bar{v}_1 - \bar{v}_2) = -\tilde{v}_1 - \tilde{v}_2 + (-\tilde{v}_3 - \hat{v}_3) \in V_1 \oplus V_2$$

leads to $\hat{v}_3 = -\tilde{v}_3$.

Next note that

$$s^3(v_2) = s(-\bar{v}_1 + \bar{v}_3) = \hat{v}_1 + (-\tilde{v}_2 + \hat{v}_2) - \tilde{v}_3 = -\tilde{v}_1 - 2\tilde{v}_2 - \tilde{v}_3 \in V_1 \oplus V_3,$$

and consequently $\tilde{v}_2 = 0$. Since

$$s^3(v_3) = s(\bar{v}_1 - \bar{v}_2) = -\tilde{v}_1 + \tilde{v}_2 + (\tilde{v}_3 - \hat{v}_3) = -\tilde{v}_1 + \tilde{v}_2 + 2\tilde{v}_3 \in V_1 \oplus V_2,$$

we also get $\tilde{v}_3 = 0$. Finally,

$$s^4(v_1) = s(-\bar{v}_2 + \bar{v}_3) = (-\tilde{v}_1 + \hat{v}_1) + \hat{v}_2 - \hat{v}_3 = -2\tilde{v}_1 - \tilde{v}_2 + \tilde{v}_3 \in V_2 \oplus V_3,$$

so that $\tilde{v}_1 = 0$. This implies $s^4(v_1) = 0$ because $\tilde{v}_i = 0$ for $i = 1, 2, 3$. Similarly one can prove that $s^4|_{V_i} = 0$ for $i = 2, 3$. Hence $s^4 = 0$, as desired.

To prove the remaining assertion, fix some $n \in \mathbb{N}$. Let T be the free monoid generated by $1, 2, 3, 4$. We denote by $|w|$ the length of a word $w \in T$. Put $X = \{1, 2, 3, 4\}$. Consider the system of linear equations with unknown vectors v_r , where $r \in T$, and $|r| \leq n$,

$$(24) \quad \sum_{r \in T: |r|=k} v_{r_1 i r_2} = 0 \quad \text{for } r_1, r_2 \in T, i \in X, k \in \mathbb{N} \cup \{0\}$$

such that $|r_1 i r_2| \leq n$.

We show that there exists a solution of (24) satisfying

$$(25) \quad \sum_{r \in T: |r|=n} v_r \neq 0.$$

Let $e \in M_4(D)$ be an idempotent with zero diagonal arising from Theorem 8. Let $e_i \in M_4(D)$ denote the projection on the i th coordinate in D^4 , $i = 1, 2, 3, 4$. Define $v_1 = (1, 0, 0, 0)$, $v_2 = v_3 = v_4 = 0 \in D^4$ and $v_{i_1 \dots i_k} = (e_{i_k} e) \dots (e_{i_2} e) v_{i_1}$ for $k \geq 2, i_1, \dots, i_k \in X$. We check that (24) is satisfied.

Let $r_1 = i_1 \dots i_p$ and $r_2 = j_1 \dots j_q$. Then

$$\begin{aligned} & \sum_{r \in T: |r|=k} v_{r_1 i r_2} \\ &= \sum_{z_1, \dots, z_k \in X} (e_{j_q} e) \dots (e_{j_1} e) (e_i e) [(e_{z_k} e) \dots (e_{z_1} e)] (e_i e) (e_{i_p} e) \dots (e_{i_2} e) v_{i_1} \end{aligned}$$

$$\begin{aligned}
&= (e_{j_q}e) \dots (e_{j_1}e)(e_i e) \left(\sum_{i=1}^4 e_i e \right)^k (e_i e)(e_{i_p}e) \dots (e_{i_2}e)v_{i_1} \\
&= (e_{j_q}e) \dots (e_{j_1}e)(e_i e e_i e)(e_{i_p}e) \dots (e_{i_2}e)v_{i_1} = 0
\end{aligned}$$

because $e_i e e_i = 0$ and $e_i e v_i = 0$ if $|r_1| = 0$. Moreover,

$$\sum_{r \in T: |r|=n} v_r = \sum_{i_1, \dots, i_n \in X} (e_{i_n}e) \dots (e_{i_2}e)v_{i_1} = \left(\sum_{i=1}^4 (e_i e) \right)^{n-1} v_1 = e v_1 \neq 0.$$

This yields (25).

Let \bar{V}_n be the K -linear space spanned by the vectors $v_t, (t \in T)$ subject to relations (24) and $v_t = 0$ for $|t| \geq n + 1$. Define $s \in \text{End}_K(\bar{V}_n)$ by $s(v_r) = \sum_{i=1}^n v_{ri}$ for $|r| \leq n - 1$ and $s(v_r) = 0$ for $|r| \geq n$. Then s is indeed well defined since it preserves the defining relations of \bar{V}_n . Namely,

$$s \left(\sum_{r \in T: |r|=k} v_{r_1 i r_2} \right) = \sum_{r \in T: |r|=k} \sum_{j=1}^4 v_{r_1 i r_2 j} = \sum_{j=1}^4 \left(\sum_{r \in T: |r|=k} v_{r_1 i r_2 j} \right) = 0$$

and $s(v_t) = \sum_{i=1}^4 v_{ti} = 0$ for $t \in T$ such that $|t| \geq n + 1$. Let $\bar{V}_{n,i} = \text{Lin}_K\{v_{ri} : r \in T\}, i \in X$. Since the defining relations of \bar{V}_n are homogeneous with respect to the last letter of the index $r \in T$ of v_r , it follows that $\bar{V}_n = \bigoplus_{i=1}^4 \bar{V}_{n,i}$.

We check that $s^m(\bar{V}_{n,i}) \subseteq \bigoplus_{j \neq i} \bar{V}_{n,j}$. Let $r_1 \in T$. Then

$$\begin{aligned}
s^m(v_{r_1 i}) &= \sum_{i_1, \dots, i_m \in X} v_{r_1 i i_1 \dots i_m} \\
&= \sum_{i_1, \dots, i_{m-1}} v_{r_1 i i_1 \dots i_{m-1} i} + \sum_{i_1, \dots, i_m: i_m \neq i} v_{r_1 i i_1 \dots i_{m-1} i_m} \\
&= \sum_{i_1, \dots, i_m: i_m \neq i} v_{r_1 i i_1 \dots i_{m-1} i_m} \in \bigoplus_{j \neq i} \bar{V}_{n,j}.
\end{aligned}$$

Moreover, $s^n(v_{r_1}) = \sum_{i_1, \dots, i_n \in X} v_{r_1 i_1 \dots i_n} = 0$ and

$$s^{n-1}(v_1 + \dots + v_4) = \sum_{r \in T: |r|=n} v_{i_1 \dots i_n} \neq 0$$

because there exists a solution of (24) satisfying (25). Hence s is nilpotent of degree n and the semigroup generated by s has the desired properties. ■

Our final example shows that the bound on the nilpotency degree of the semigroup S in Proposition 16(b) cannot be improved.

EXAMPLE 17. Let v_1, \dots, v_9 be a basis of a K -linear space V . Define $s \in \text{End}_K(V)$ by $s(v_1) = v_4 + v_7$, $s(v_2) = v_6 + v_9$, $s(v_3) = 0$, $s(v_4) = v_2 + v_8$, $s(v_5) = v_3 + v_9$, $s(v_6) = 0$, $s(v_7) = -v_2 + v_5$, $s(v_8) = -v_3 - v_6$

and $s(v_9) = 0$. Set also $V_1 = \text{Lin}_K(v_1, v_2, v_3)$, $V_2 = \text{Lin}_K(v_4, v_5, v_6)$ and $V_3 = \text{Lin}_K(v_7, v_8, v_9)$. Then $V = V_1 \oplus V_2 \oplus V_3$. It is easy to check that $s^k(V_i) \subseteq \bigoplus_{j \neq i} V_j$ for $k = 1, 2, \dots$, $i = 1, 2, 3$ and $s^3 \neq 0$.

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